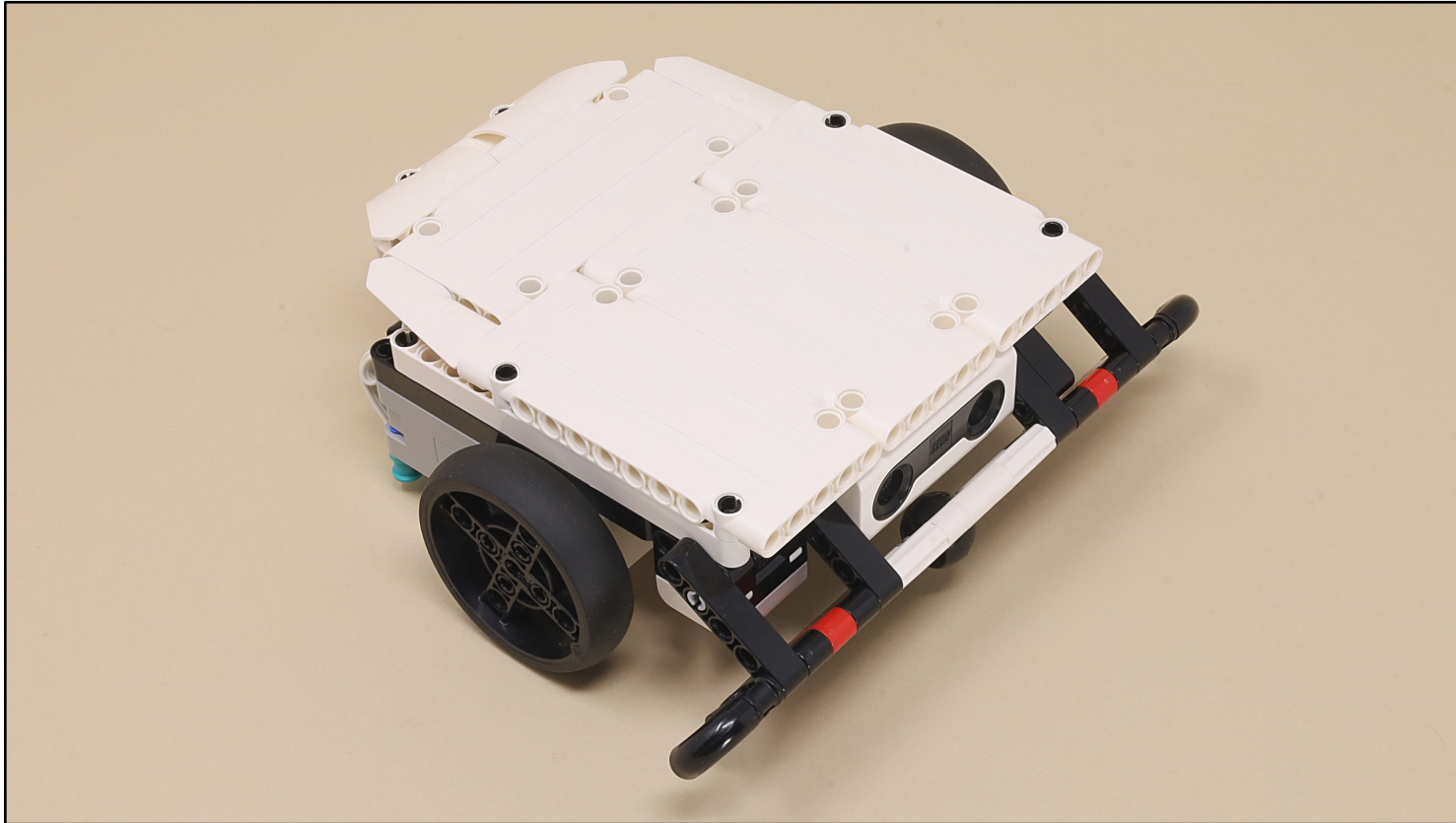
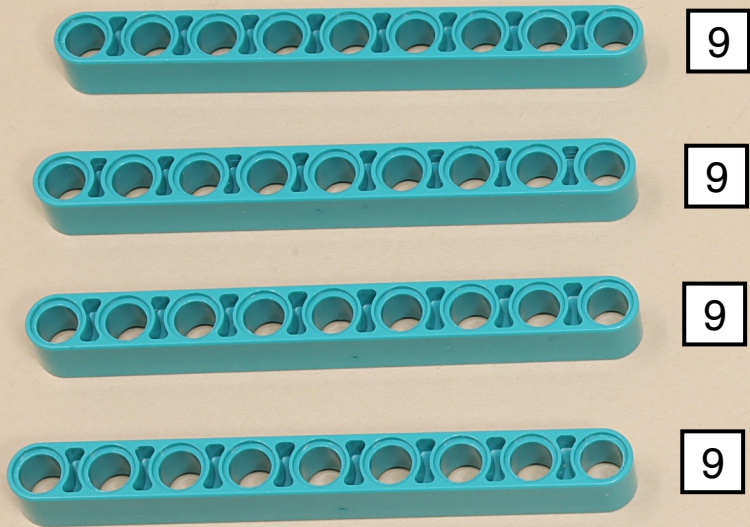


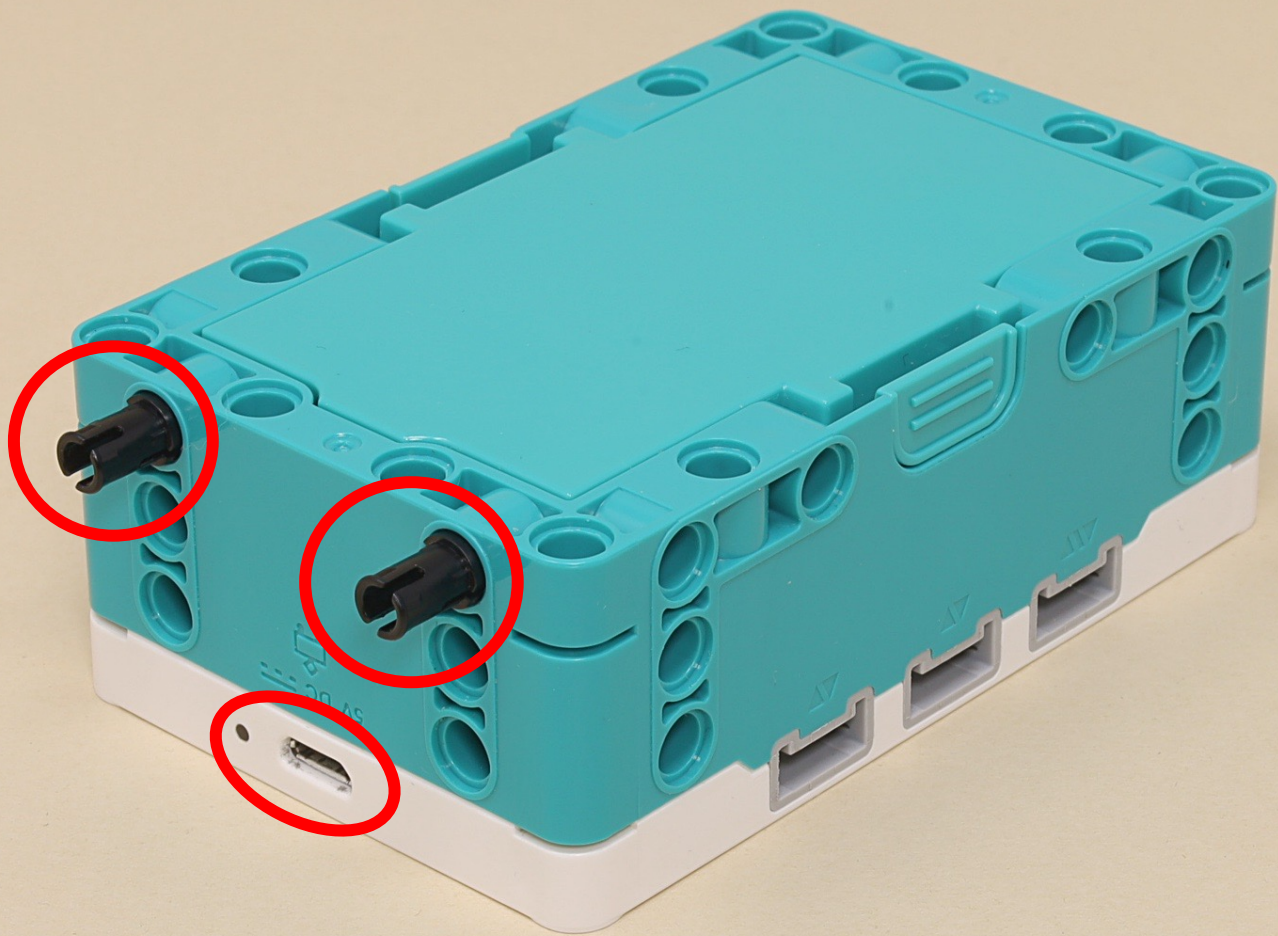
Robot Vacuum

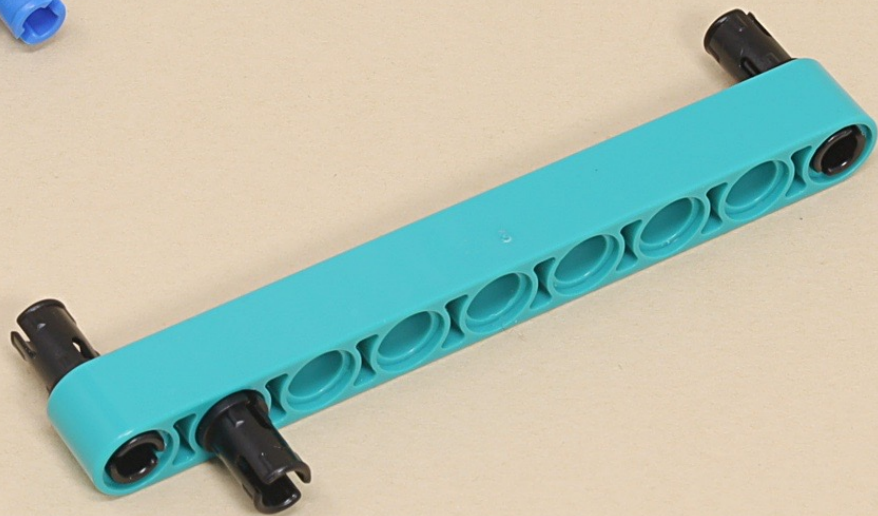
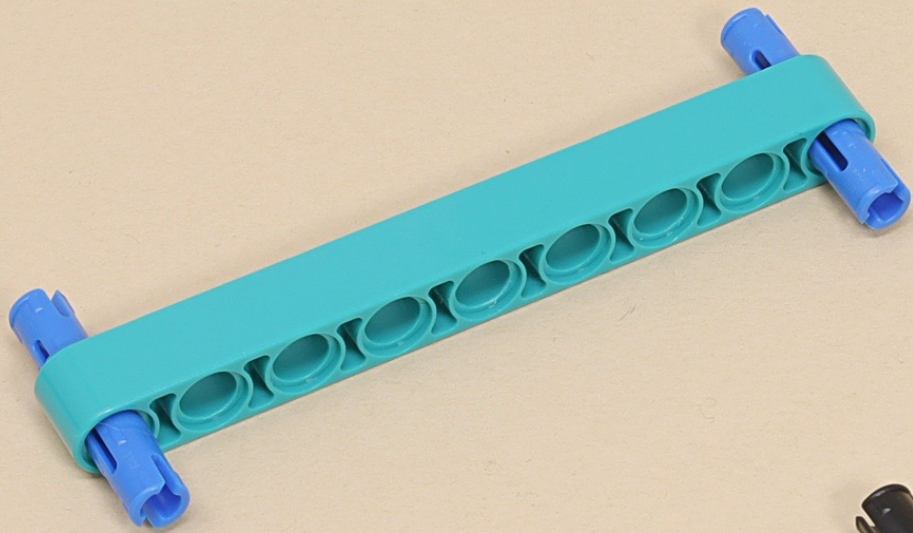


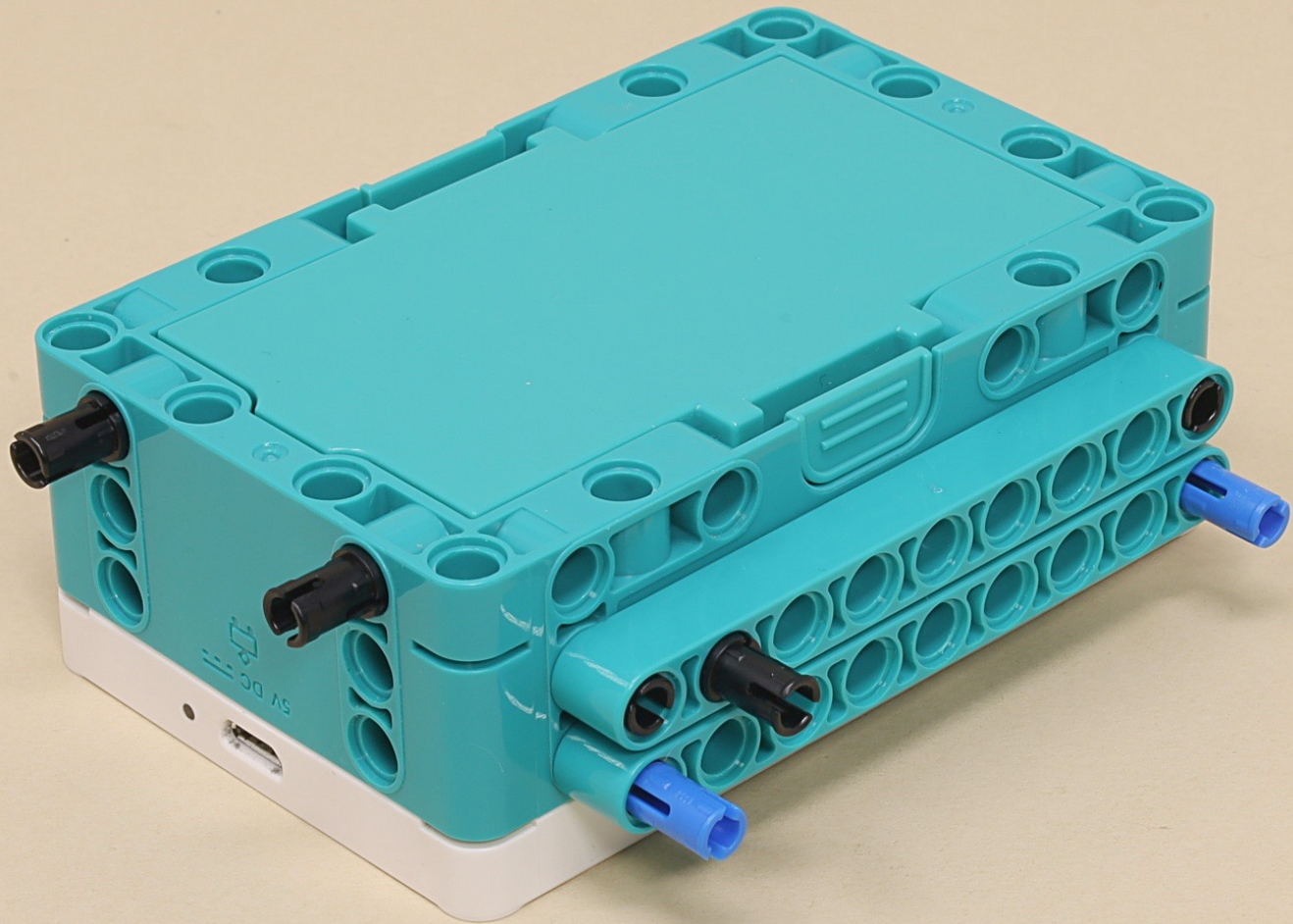
Scroll for
building
instructions

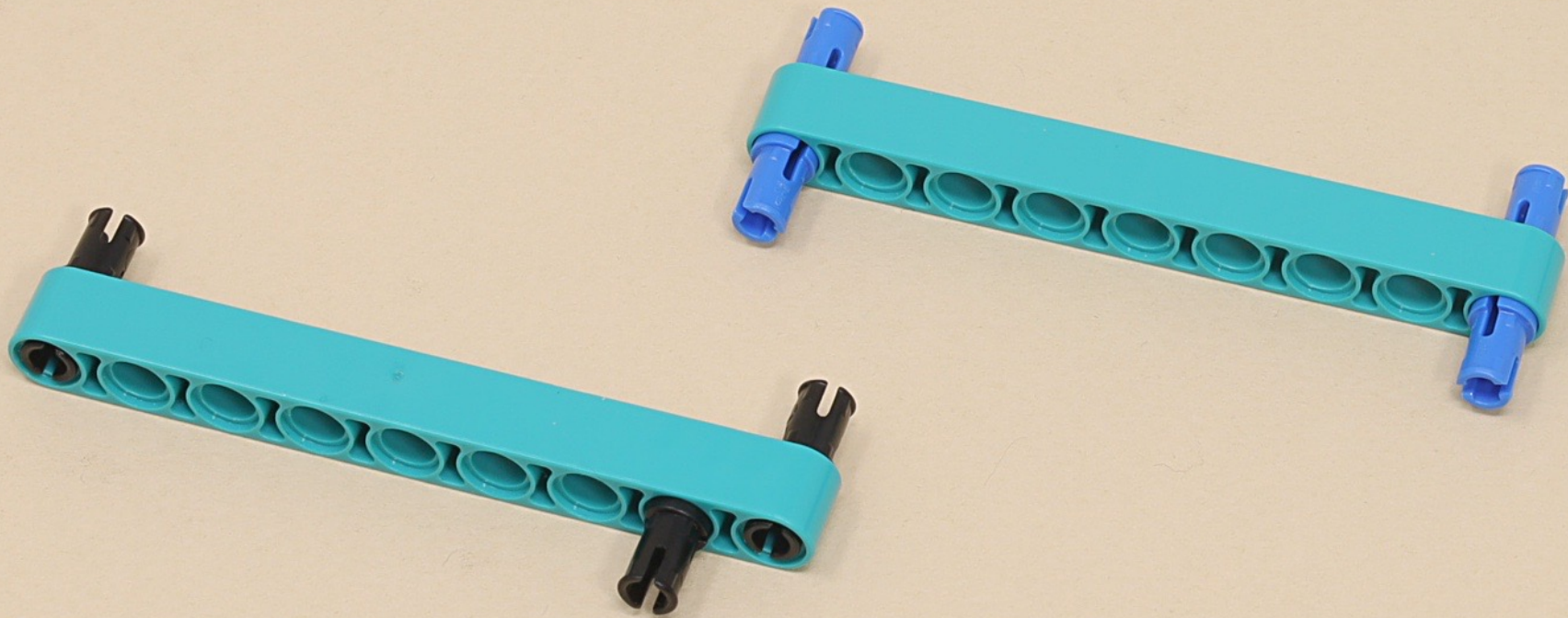


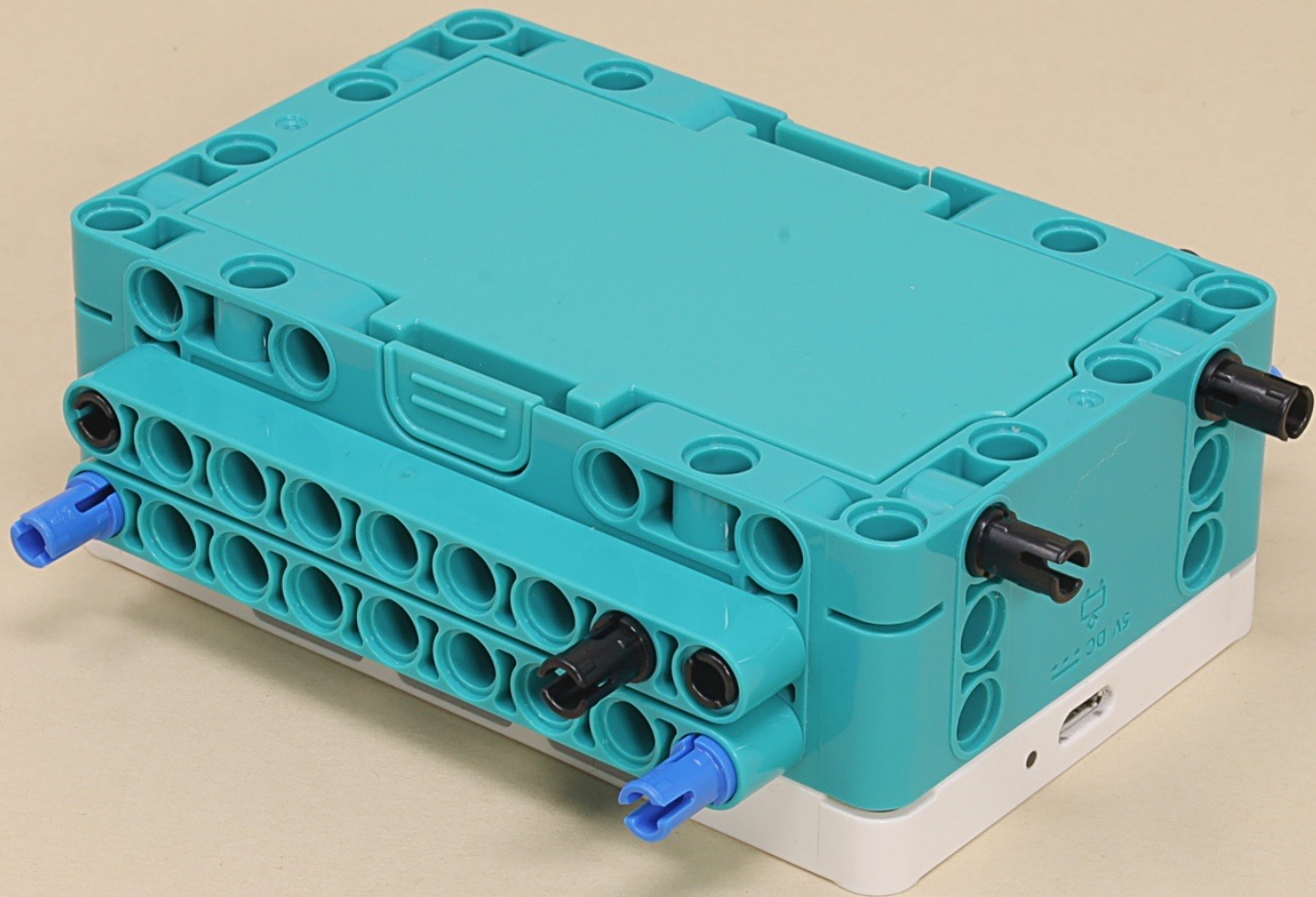












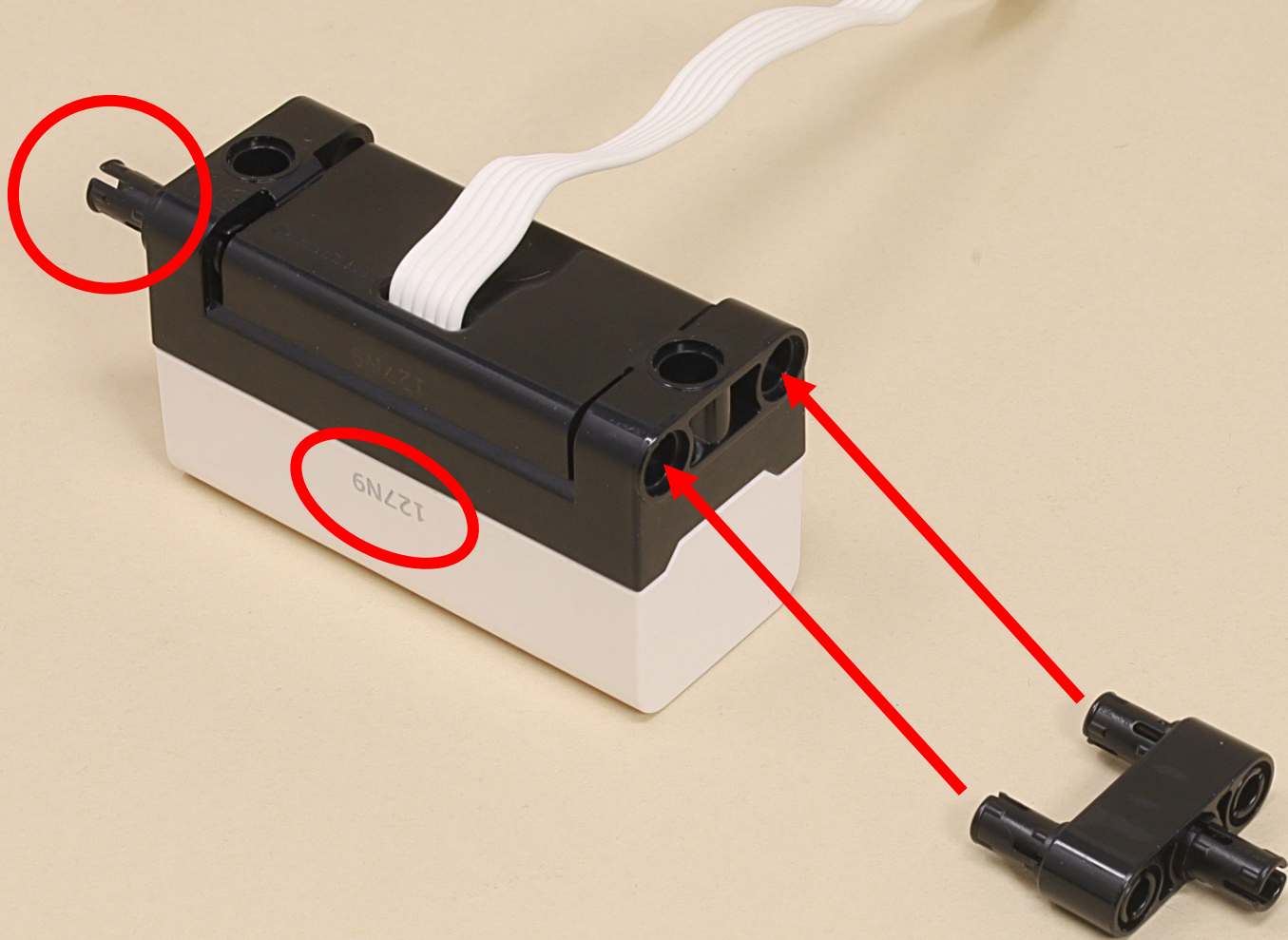


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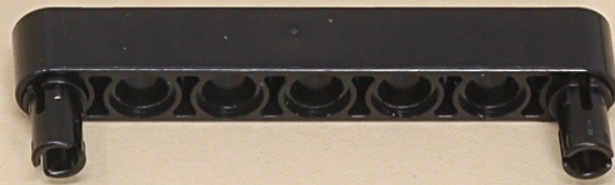
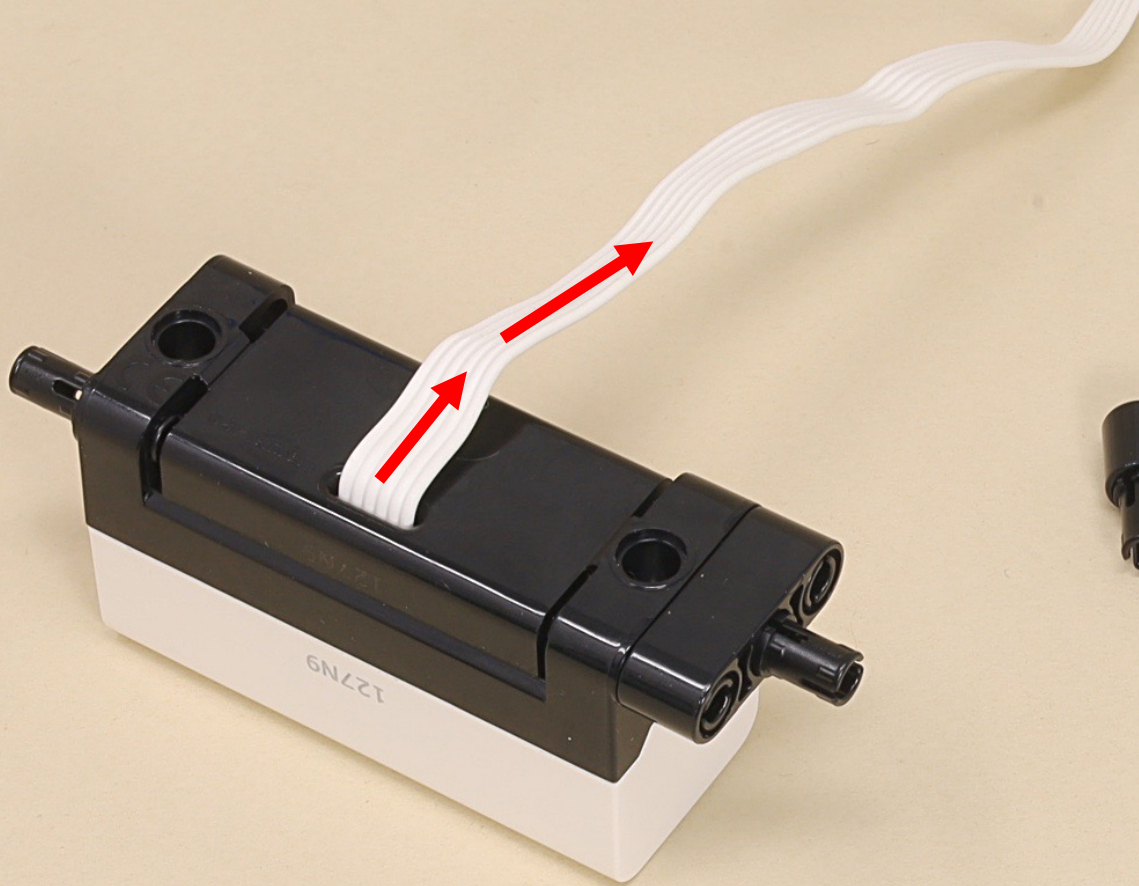
(6 x)

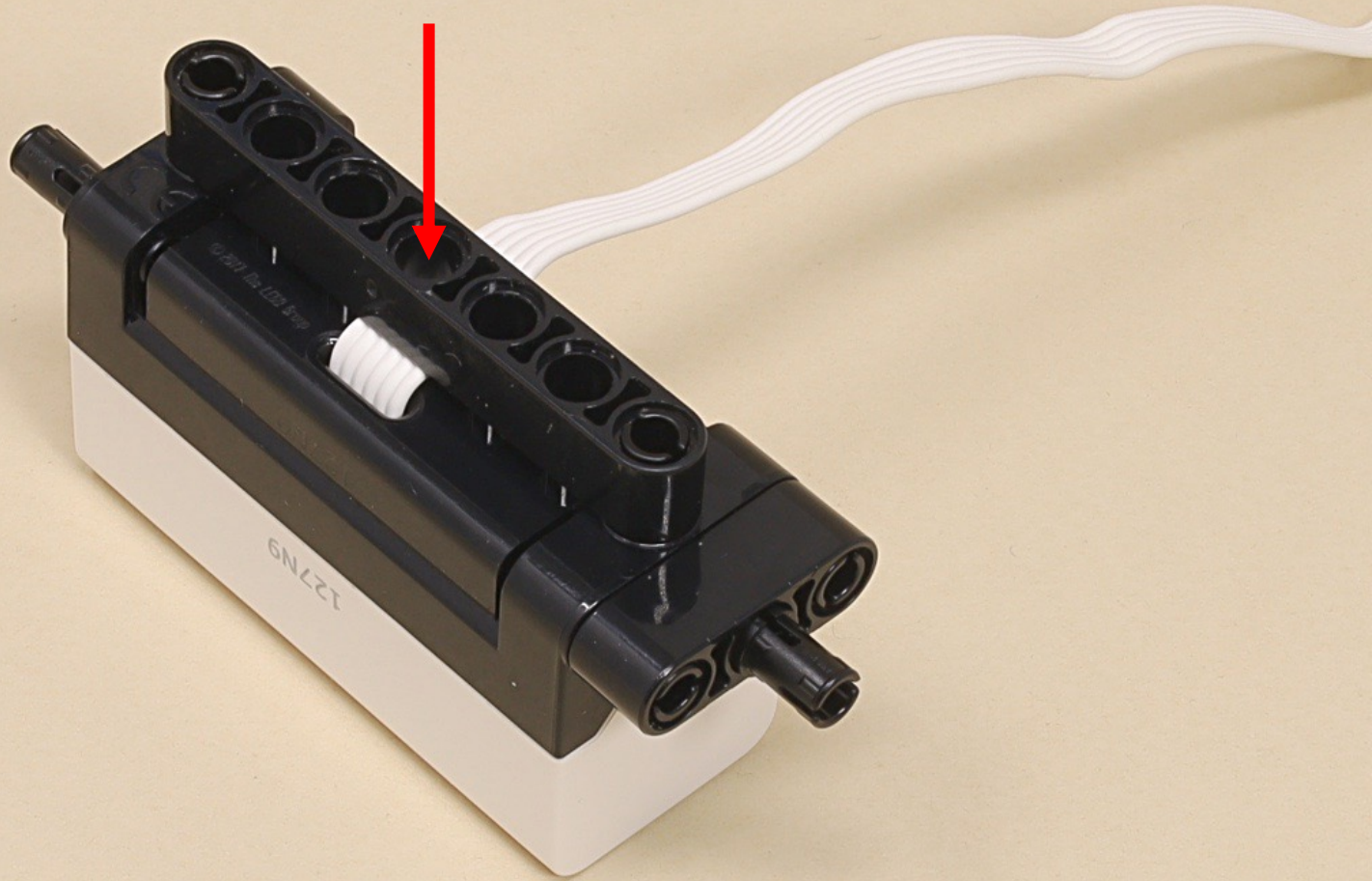




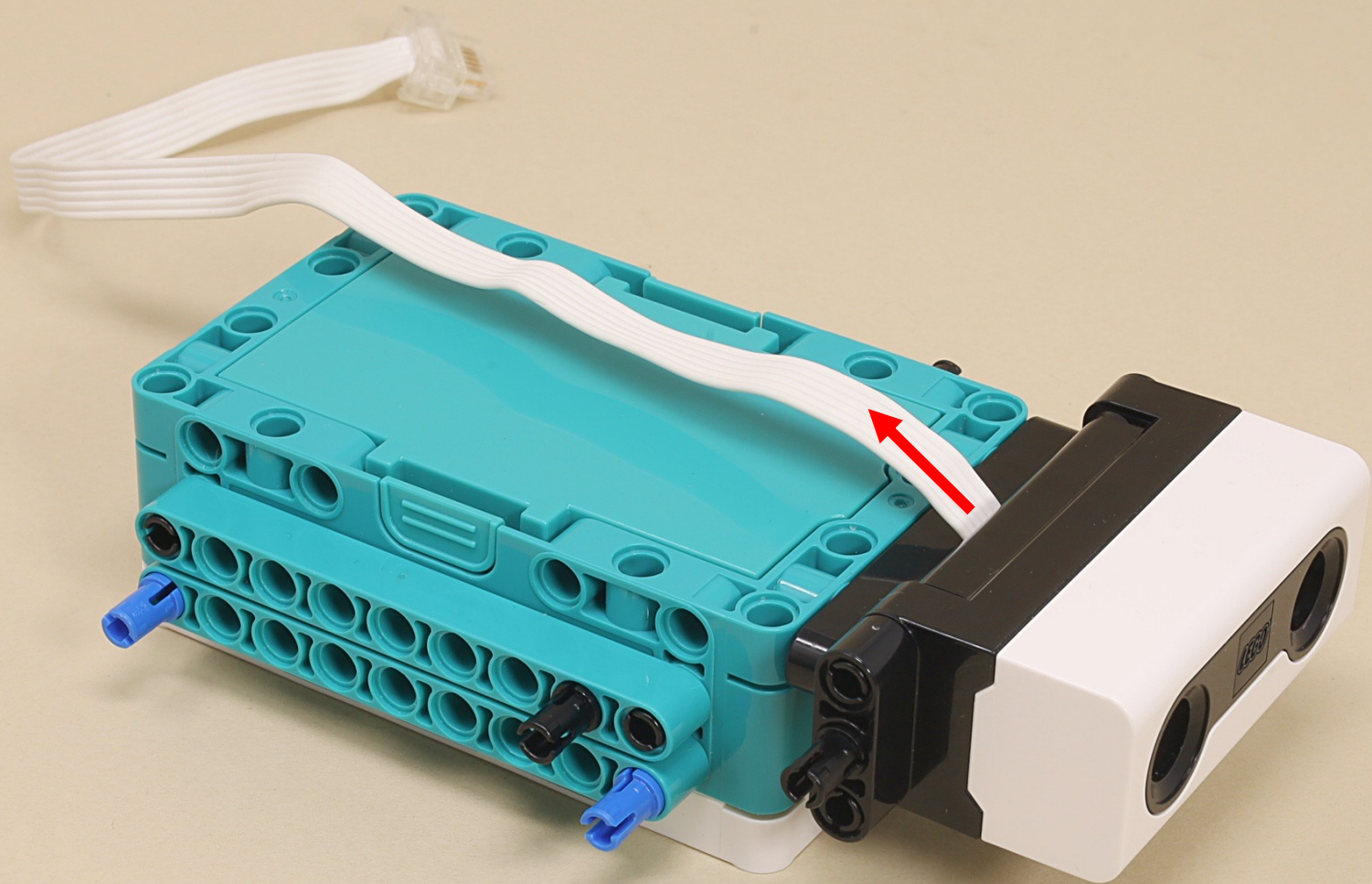


127N9

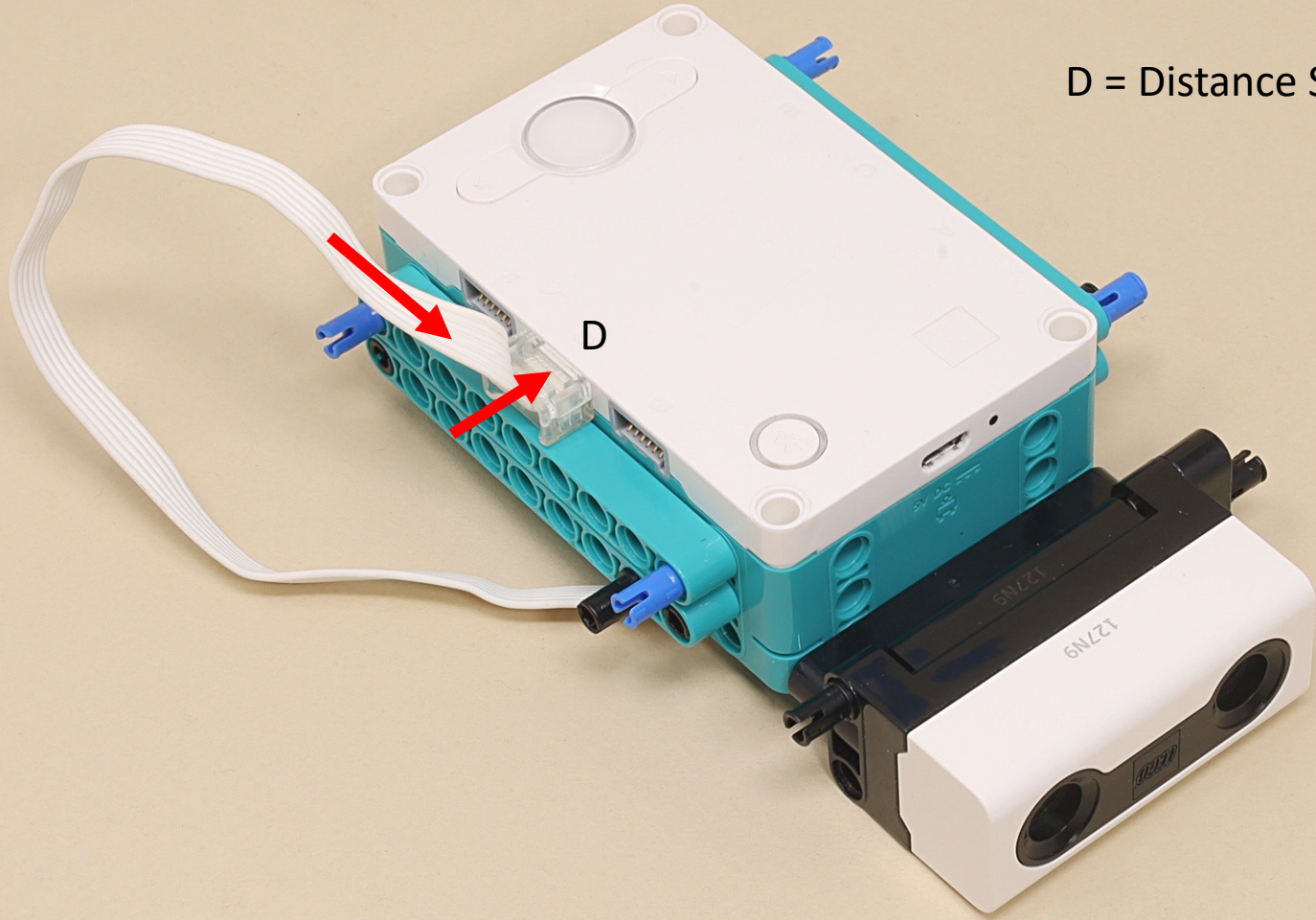




6N21



D = Distance Sensor



D

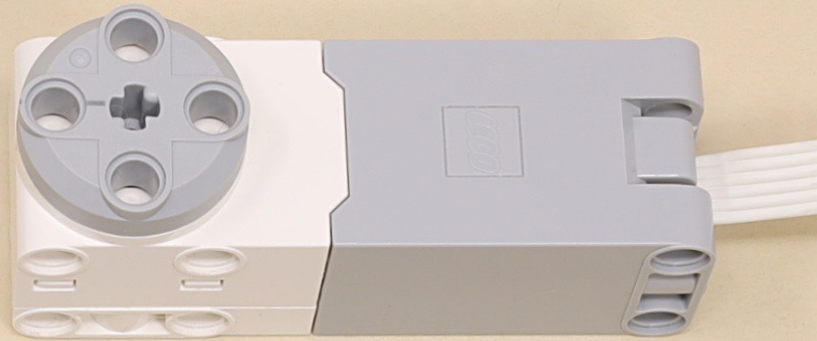
12719



9

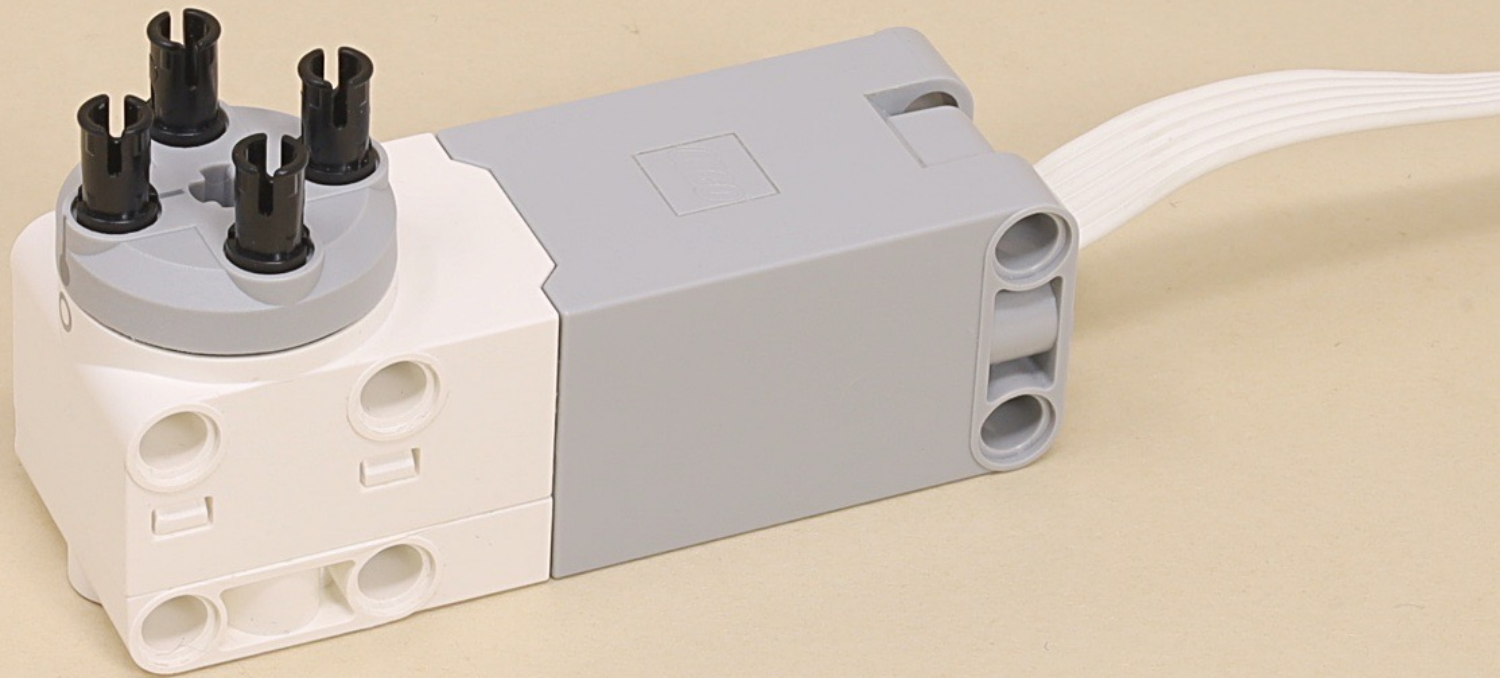


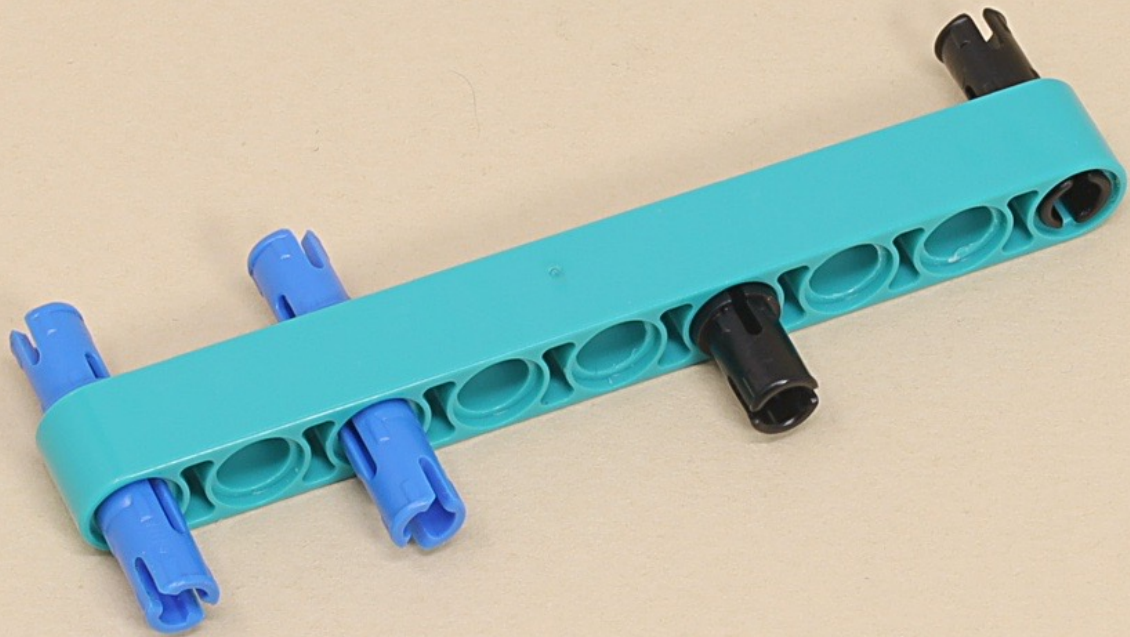
9

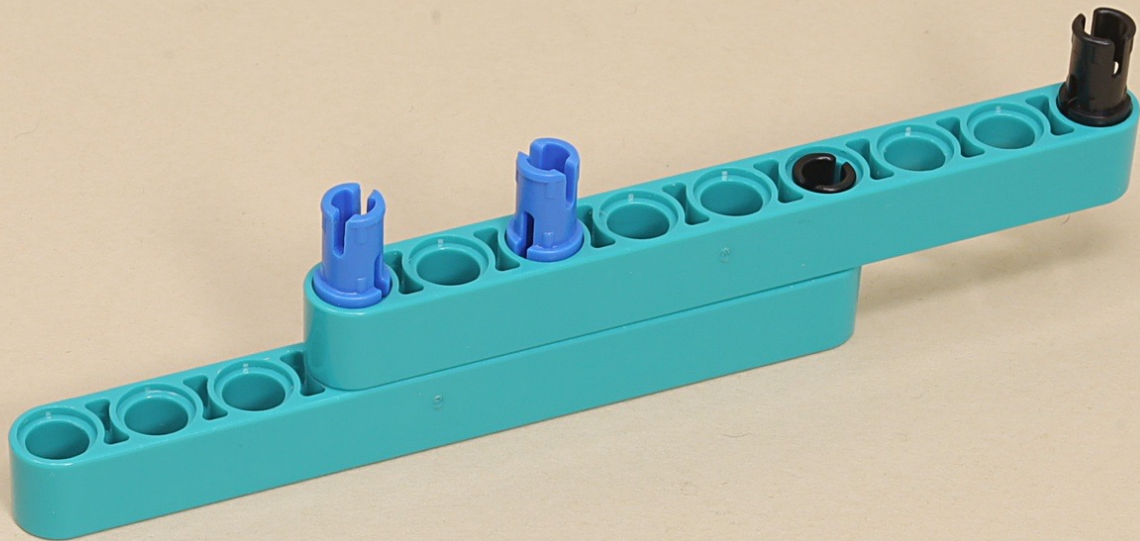


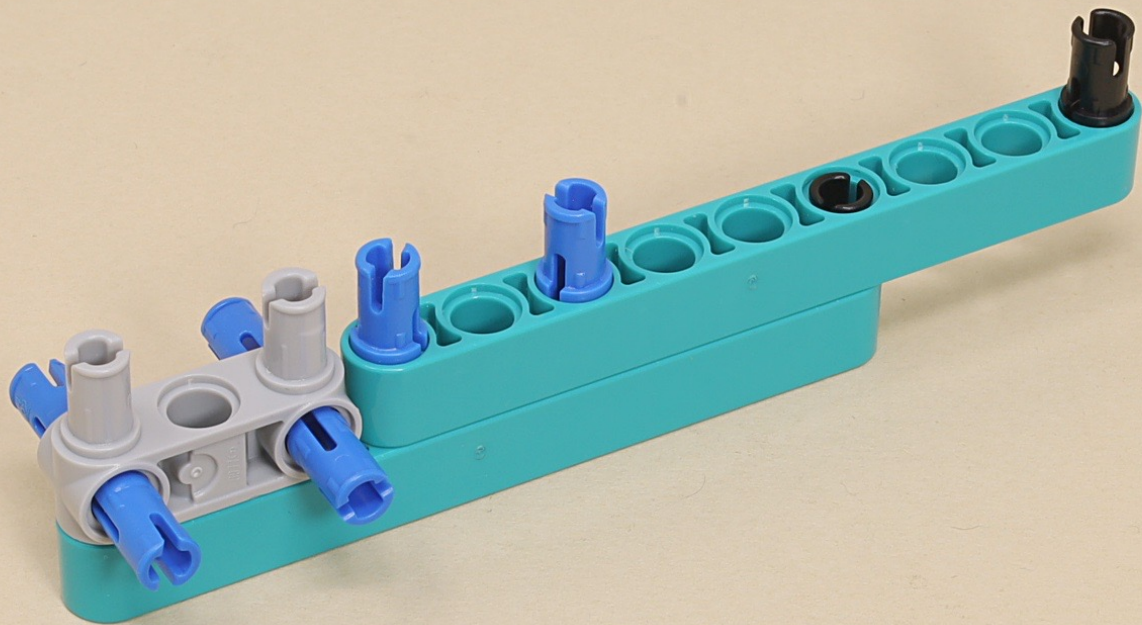
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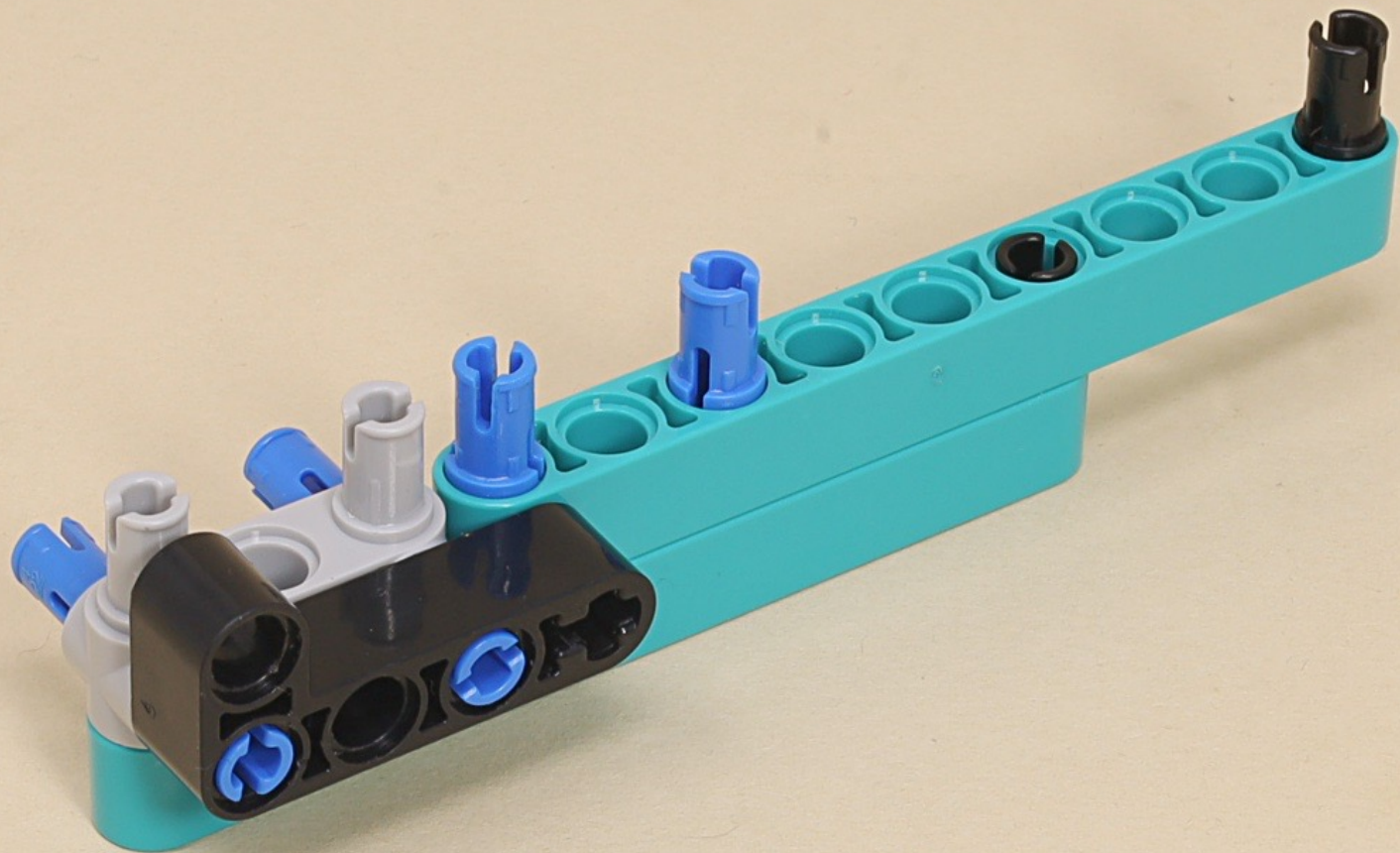


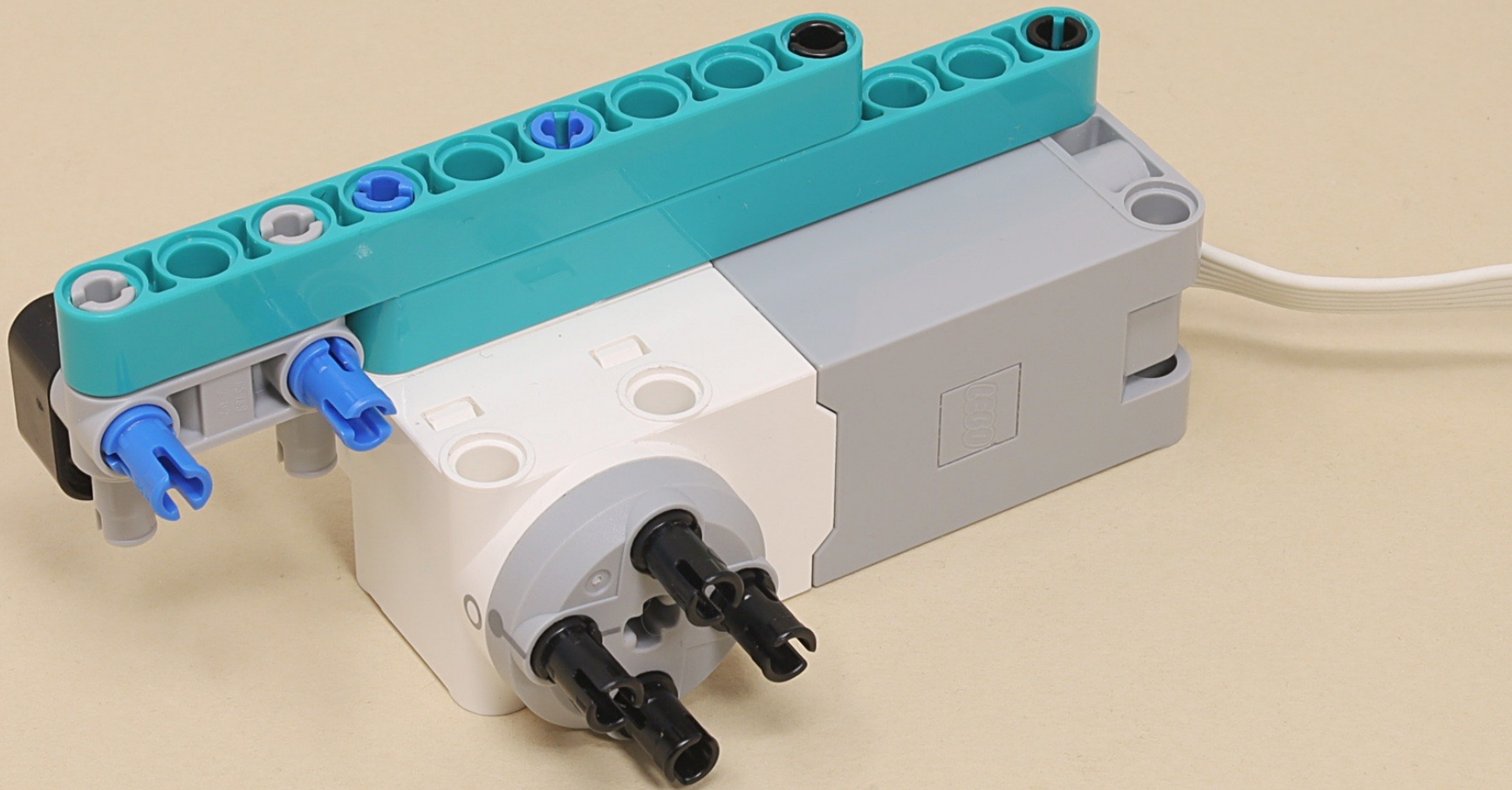




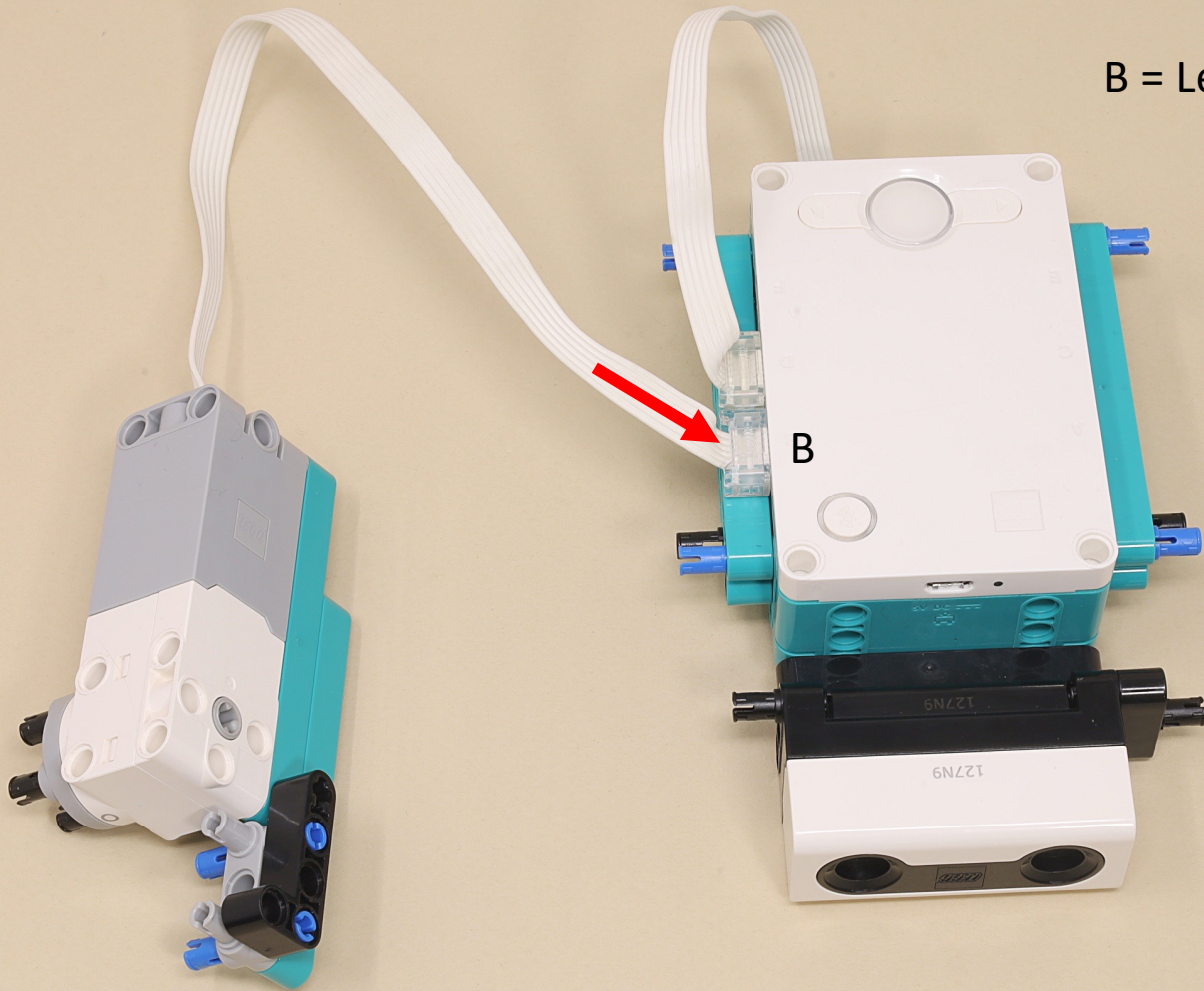


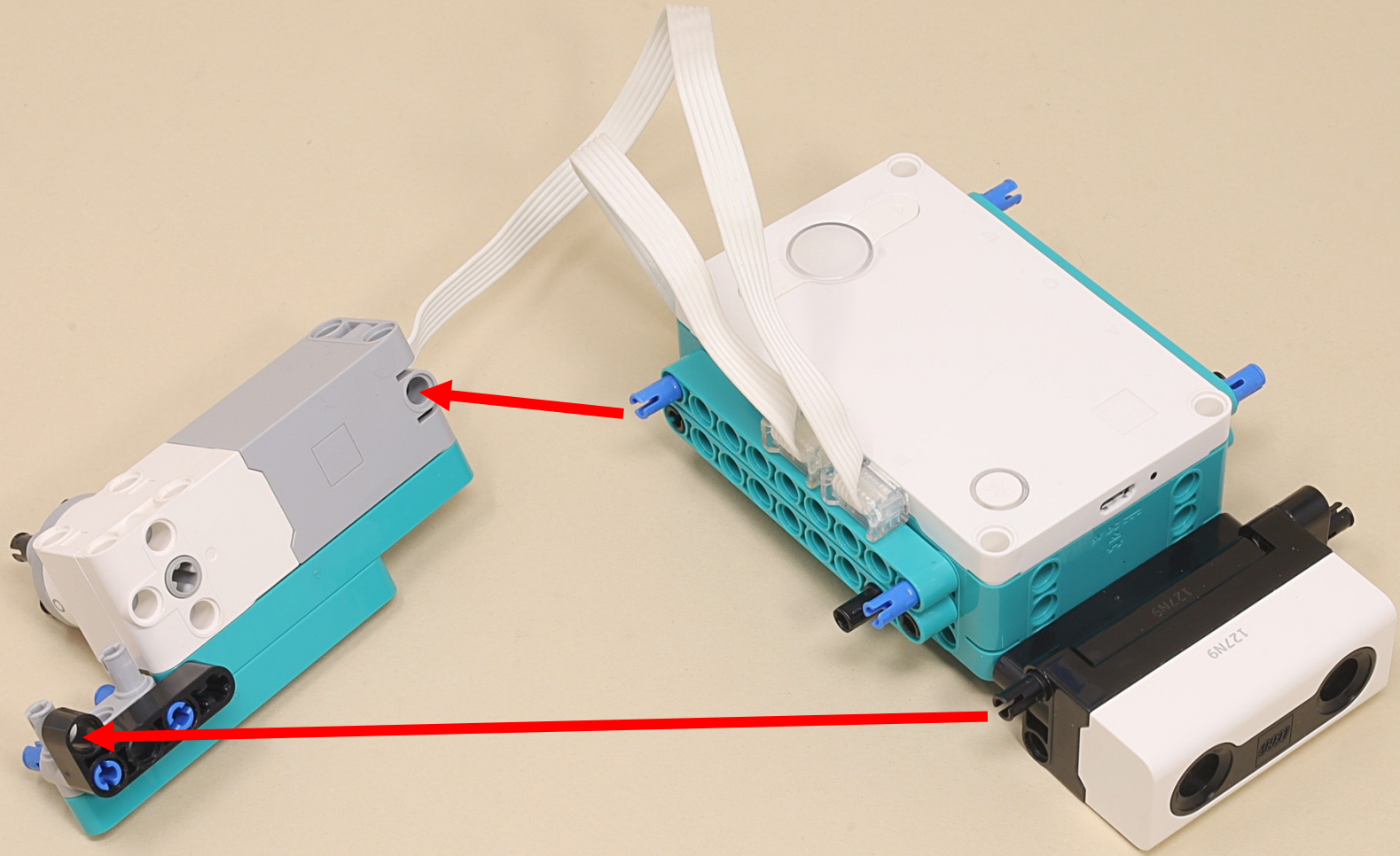


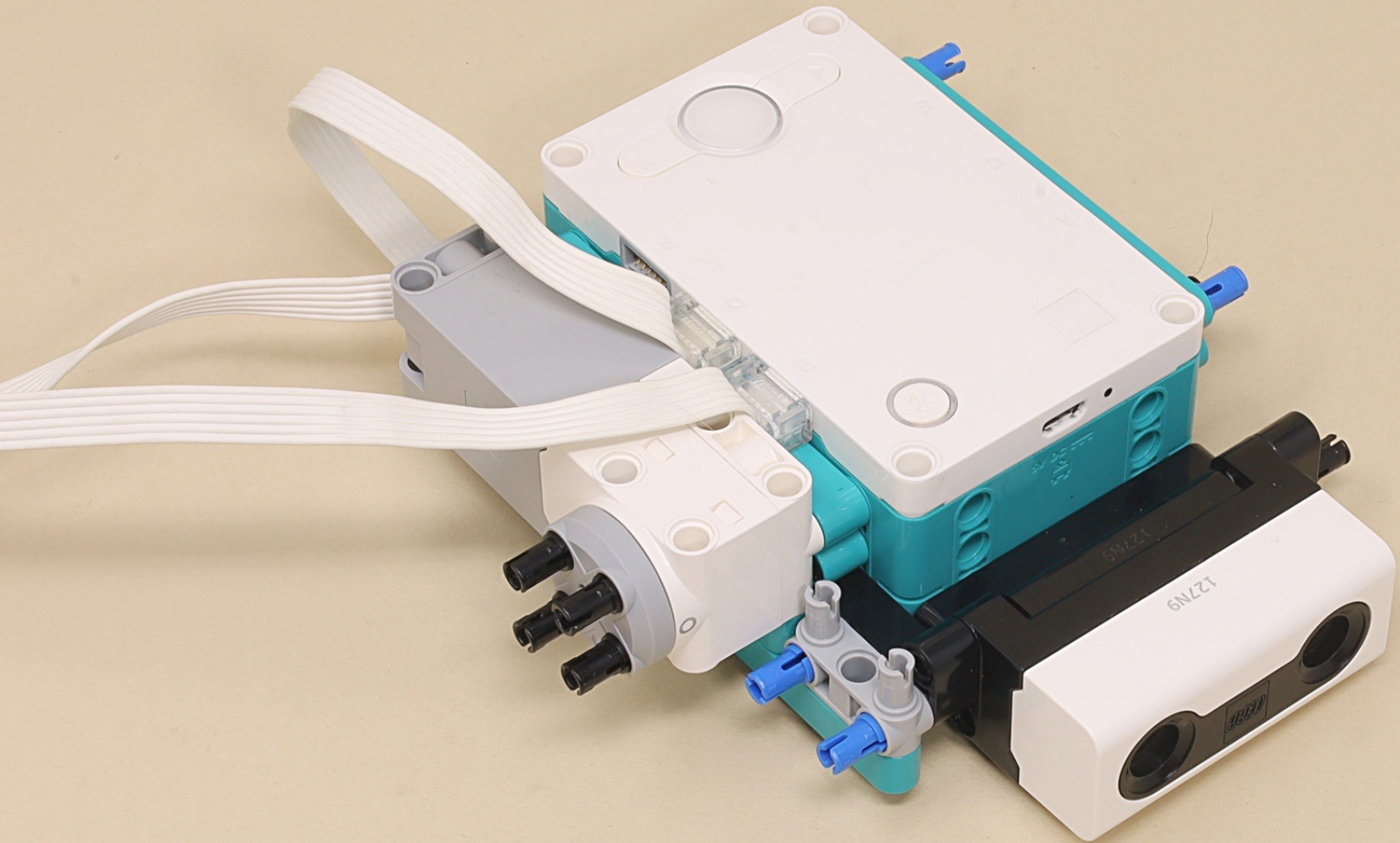




B = Left Wheel Motor









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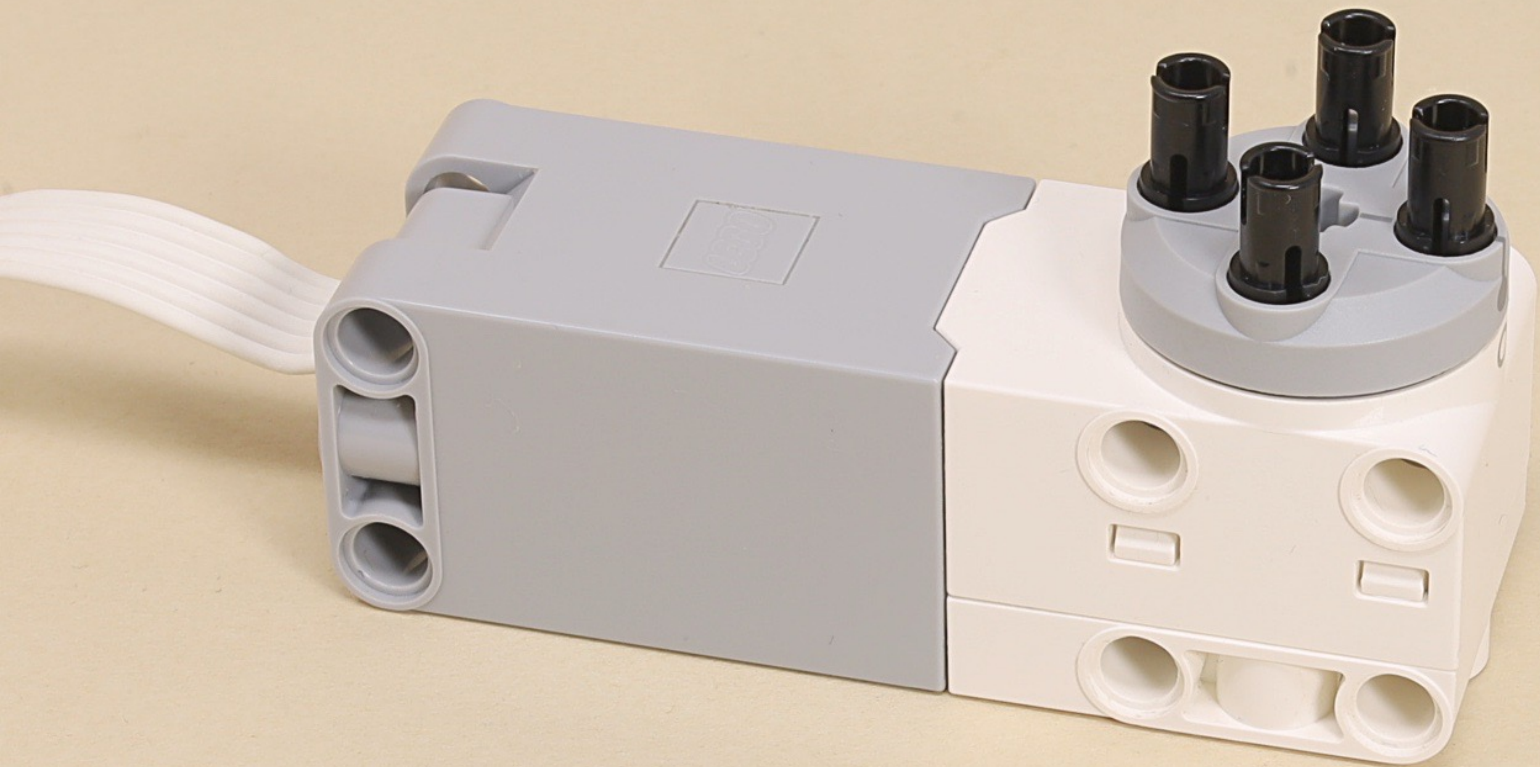


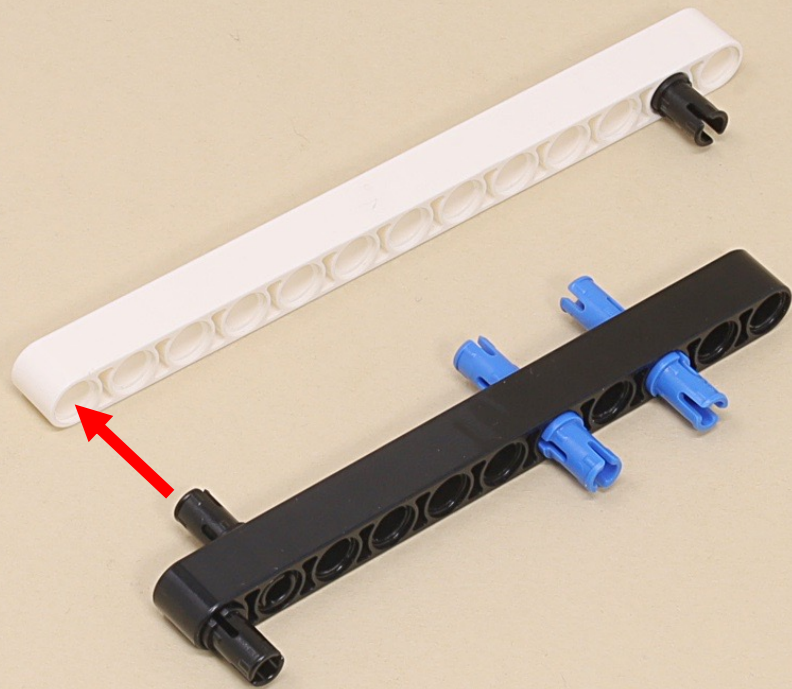
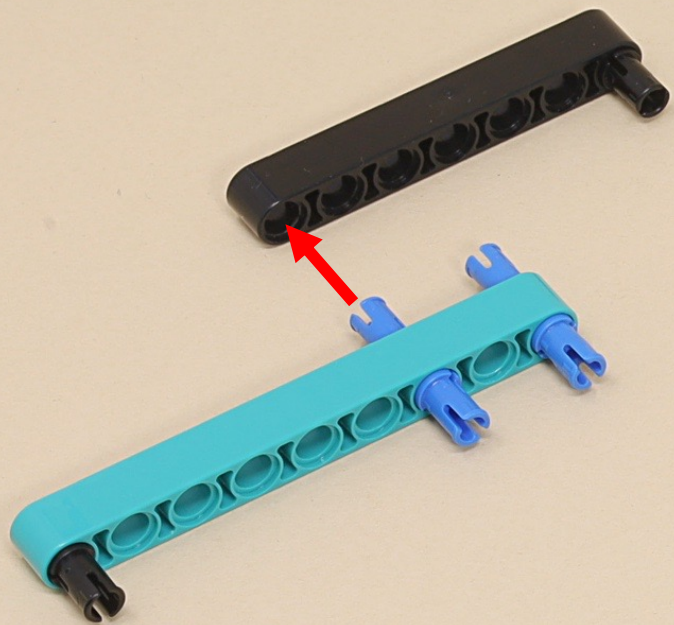
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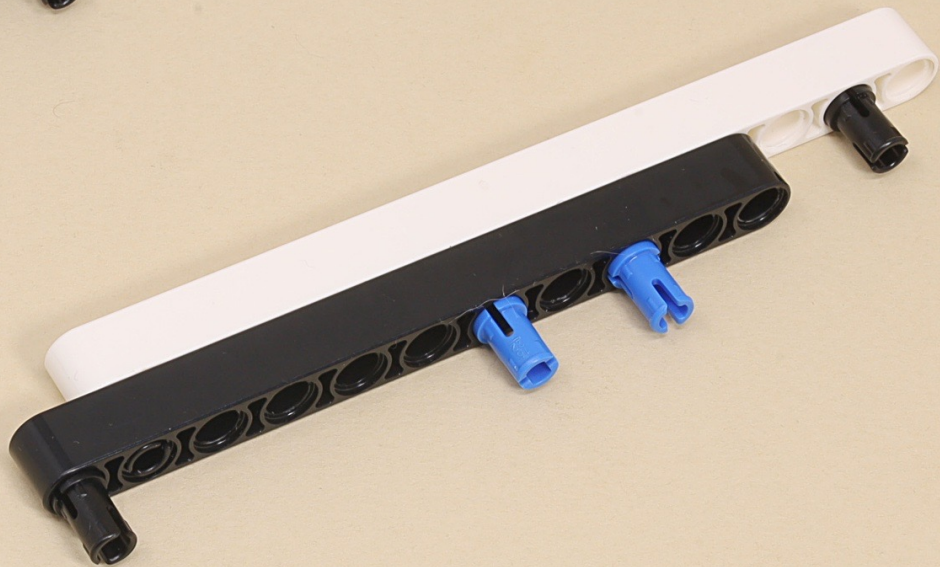
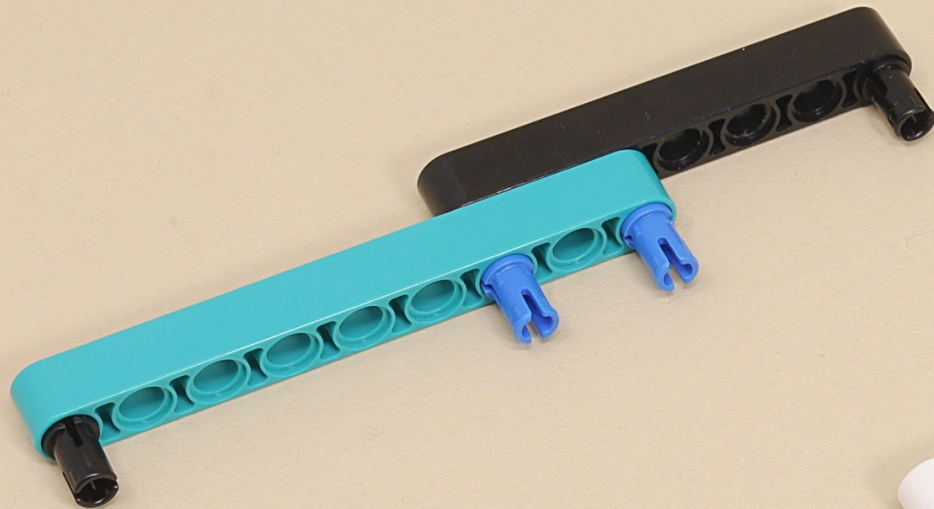


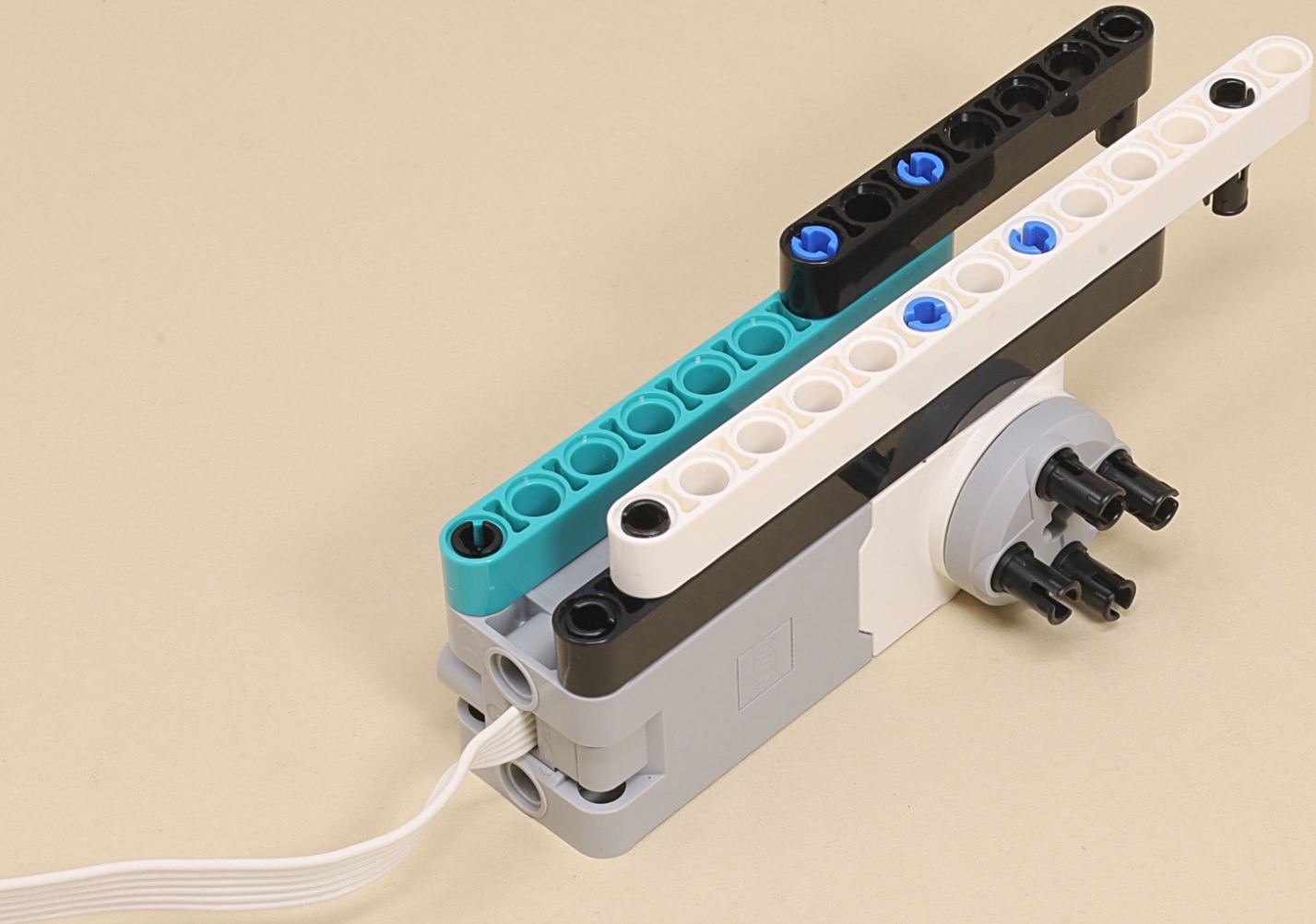
(9 x)

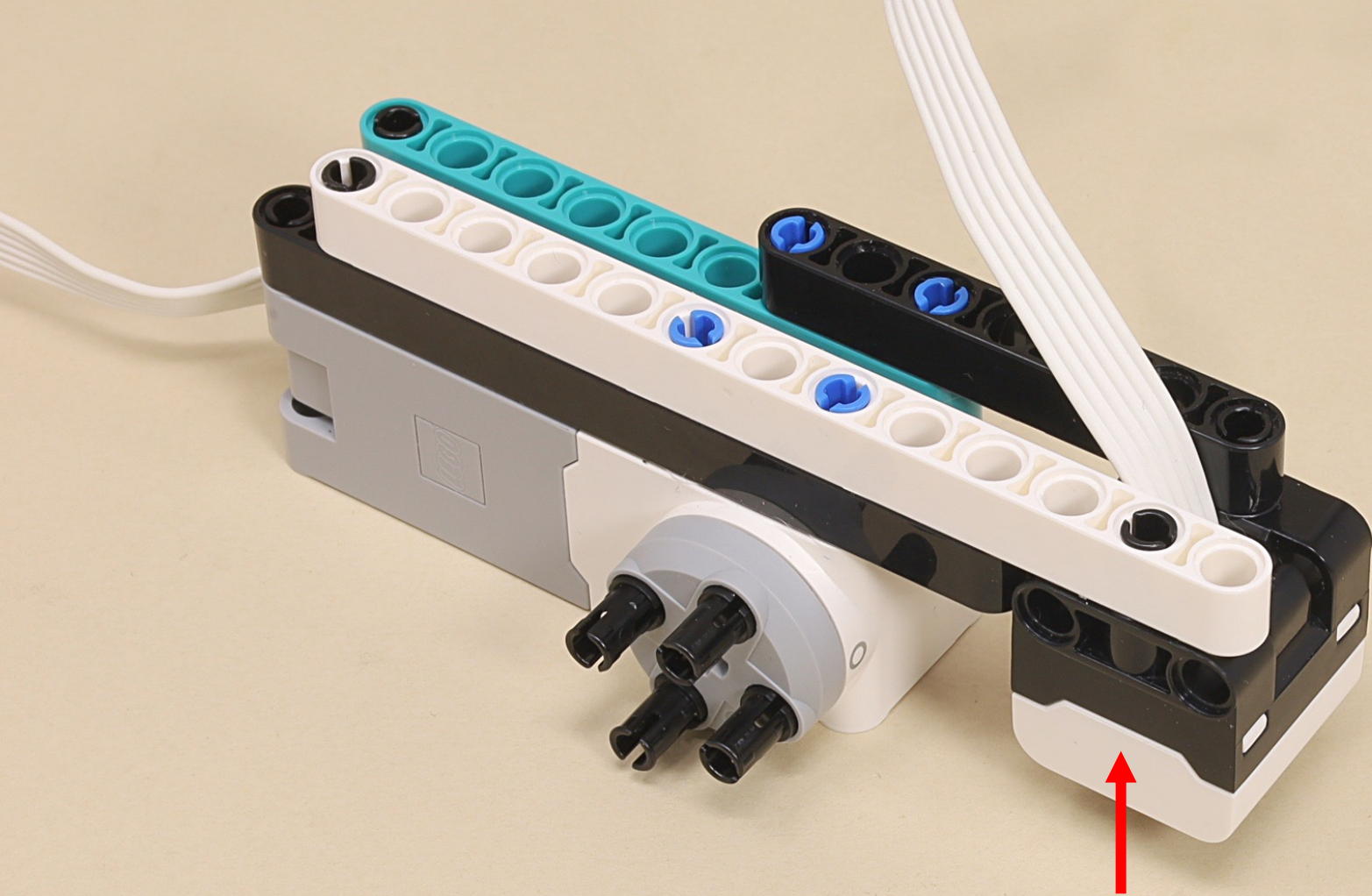


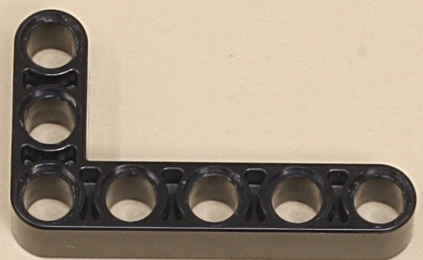
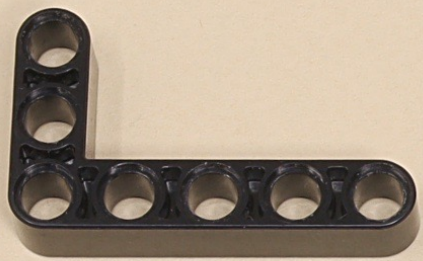












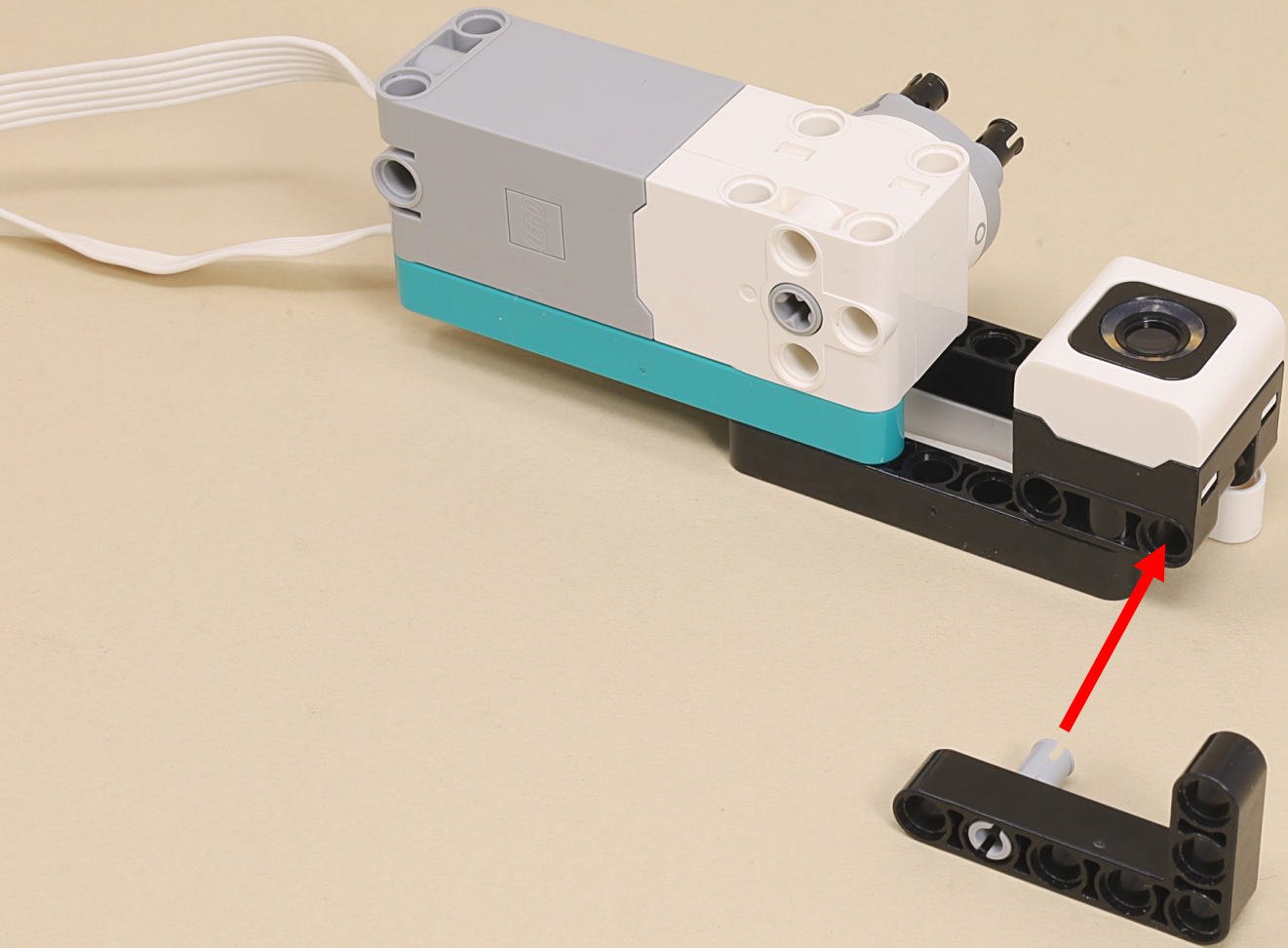
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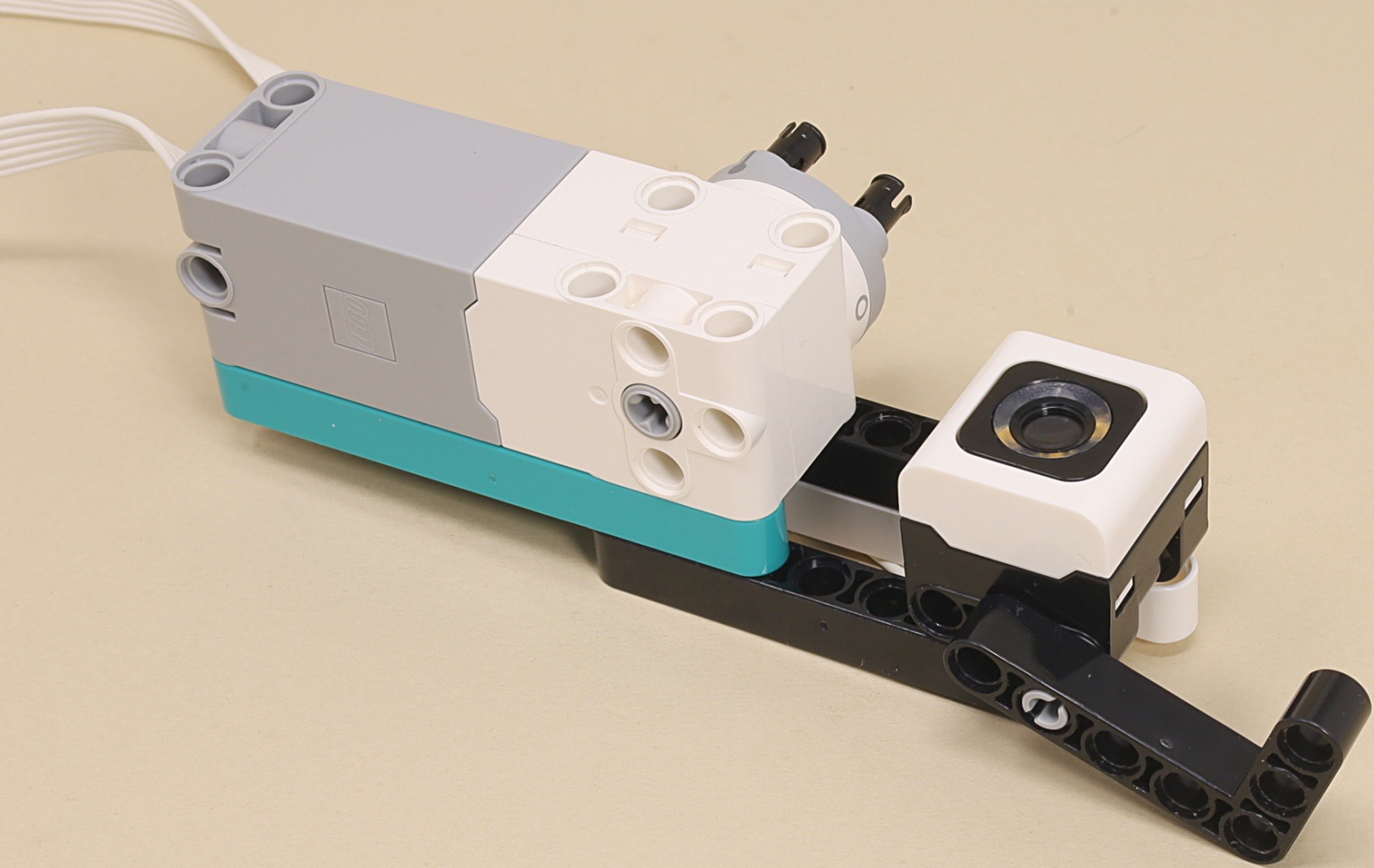


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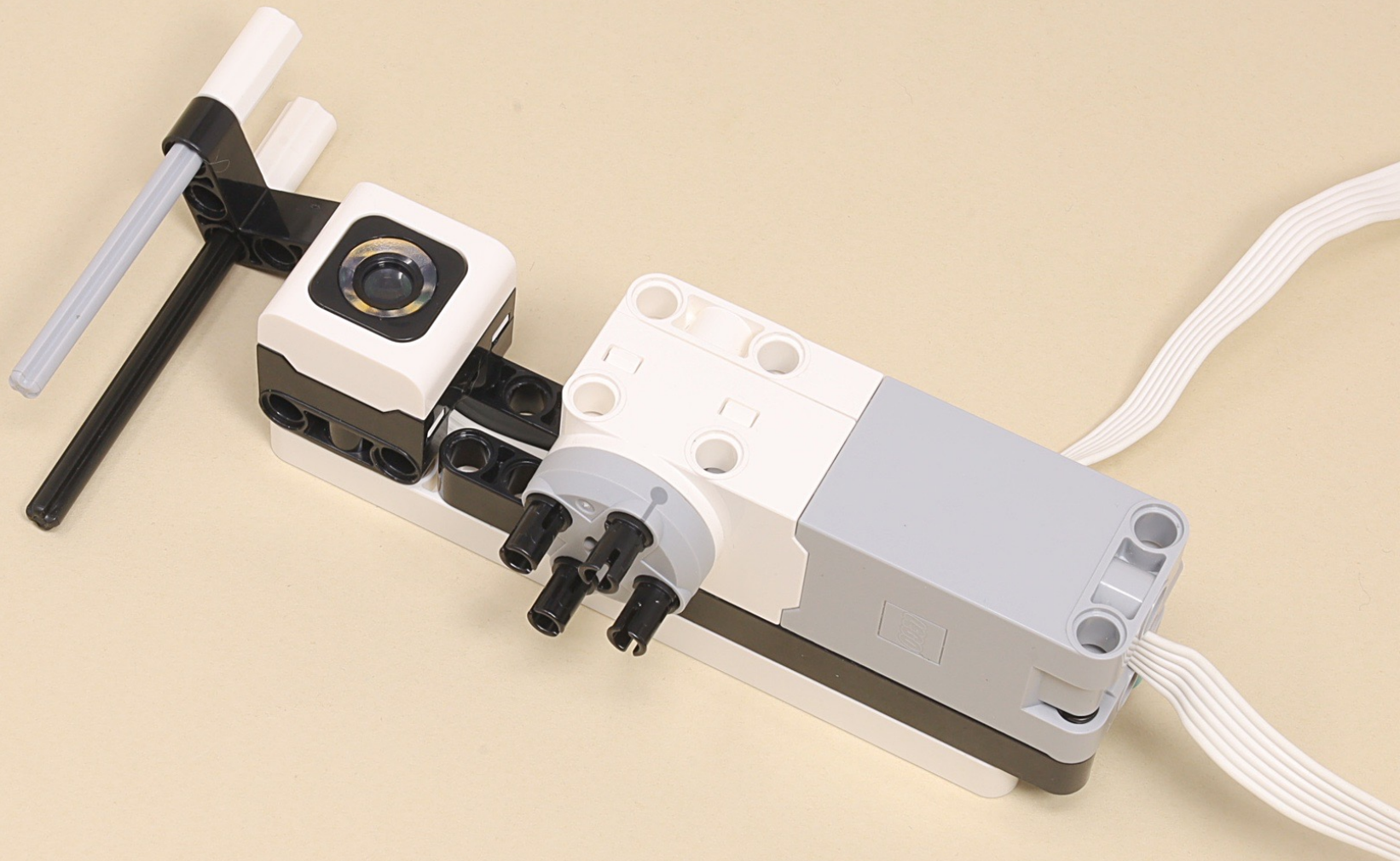






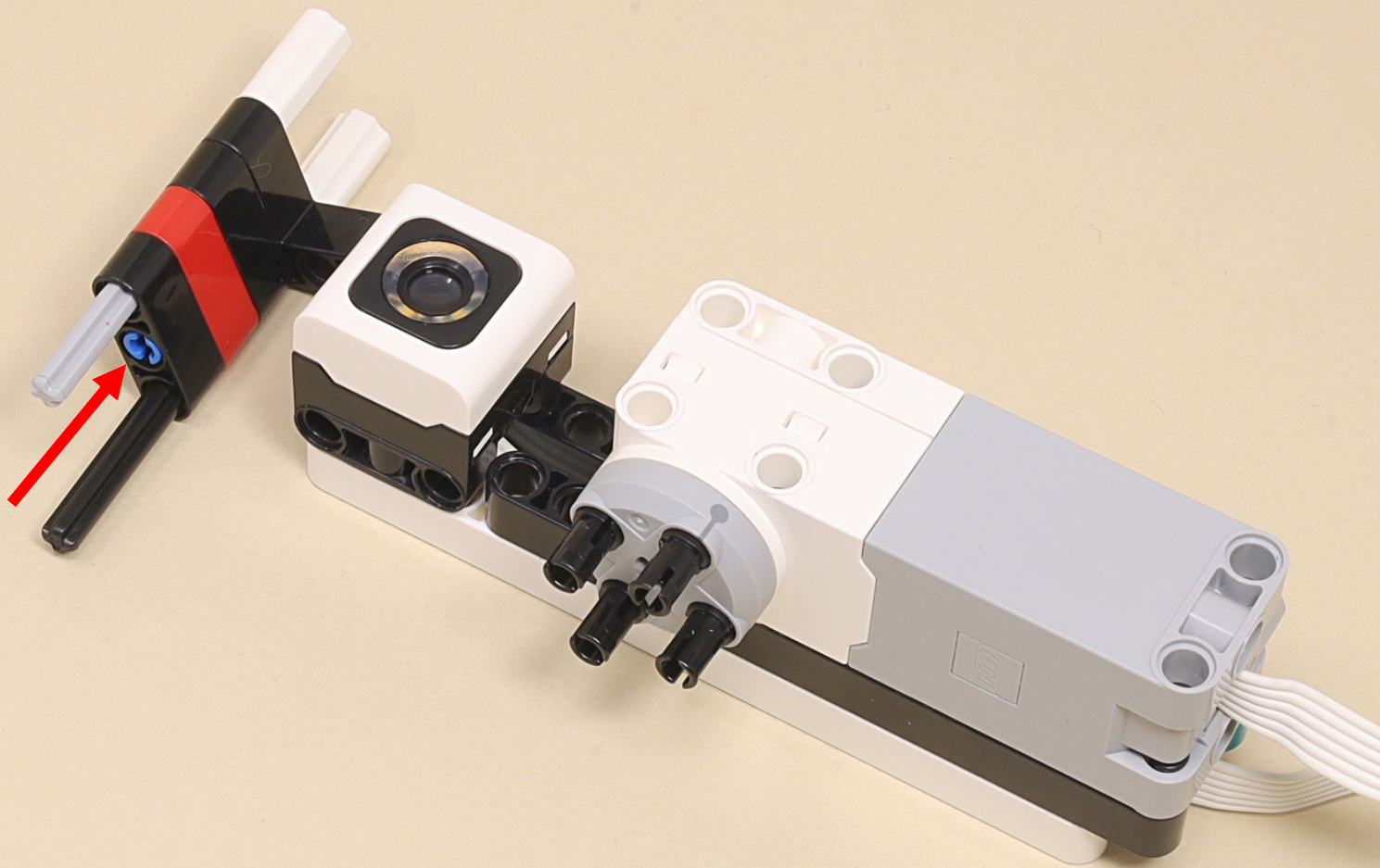


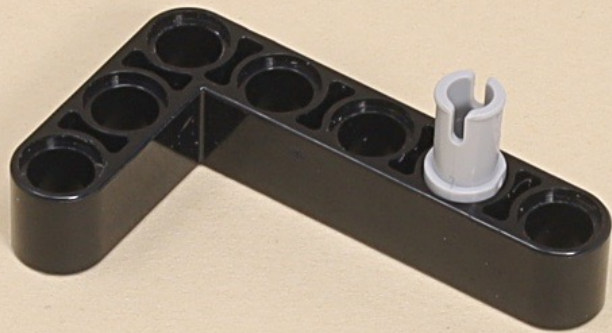


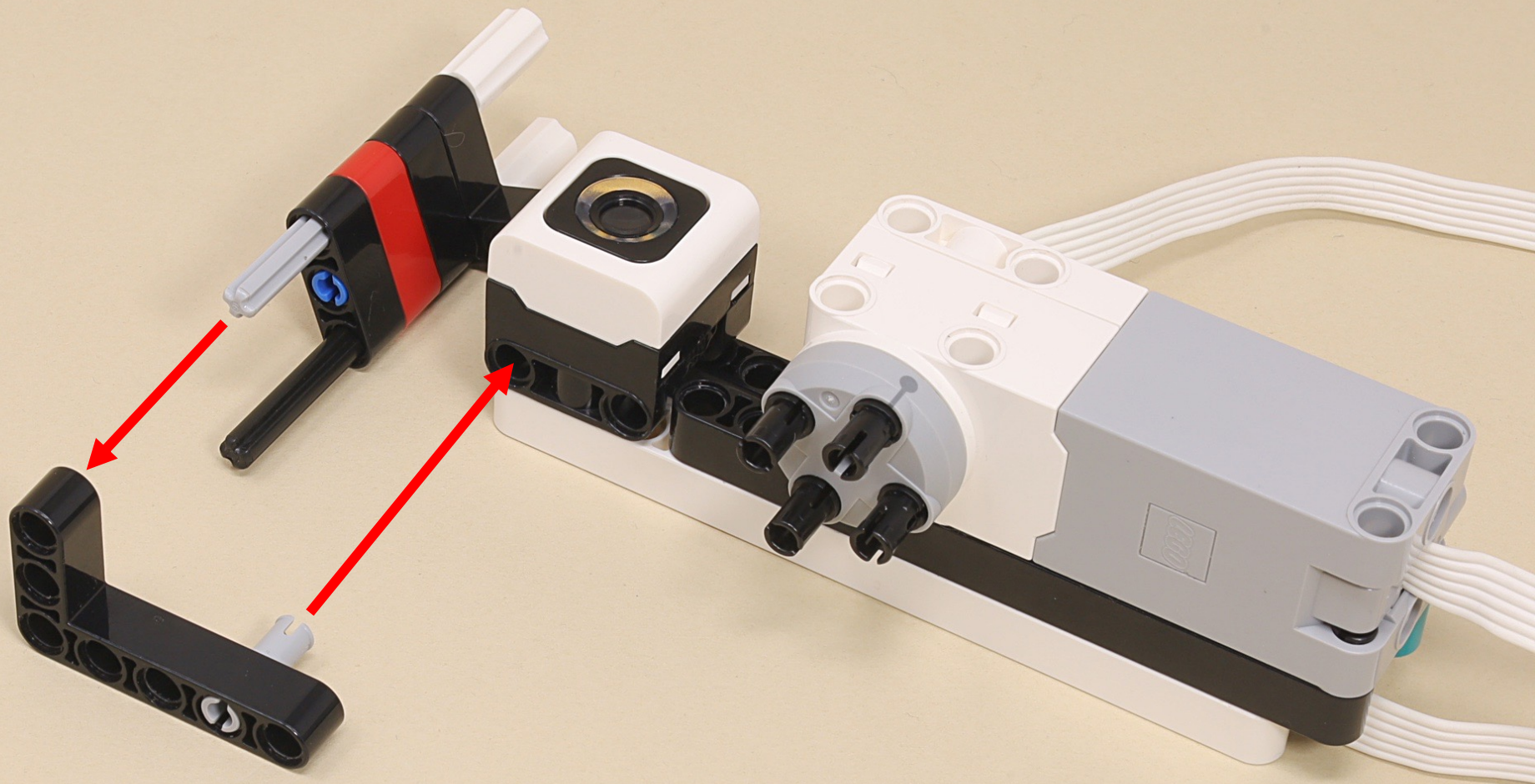


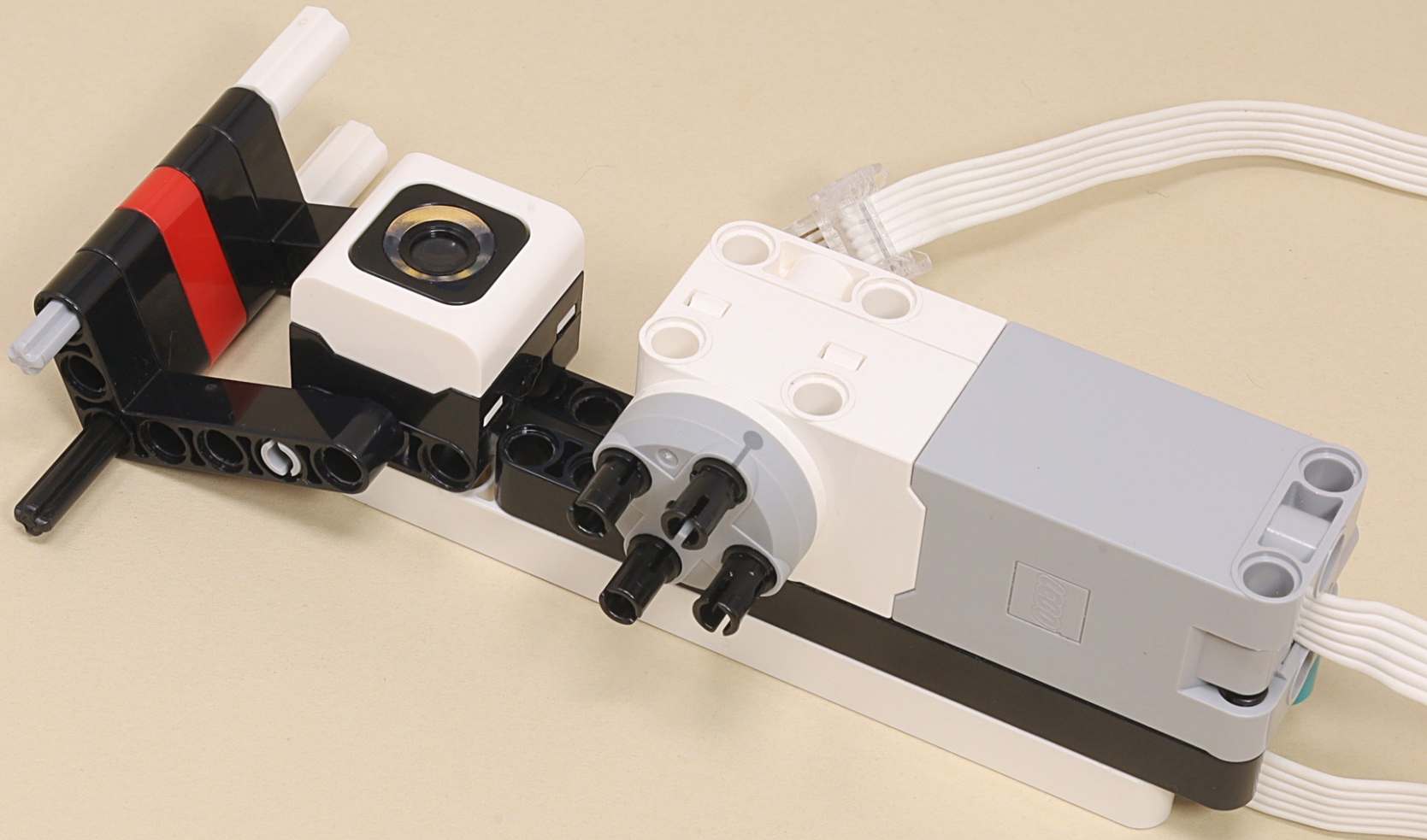


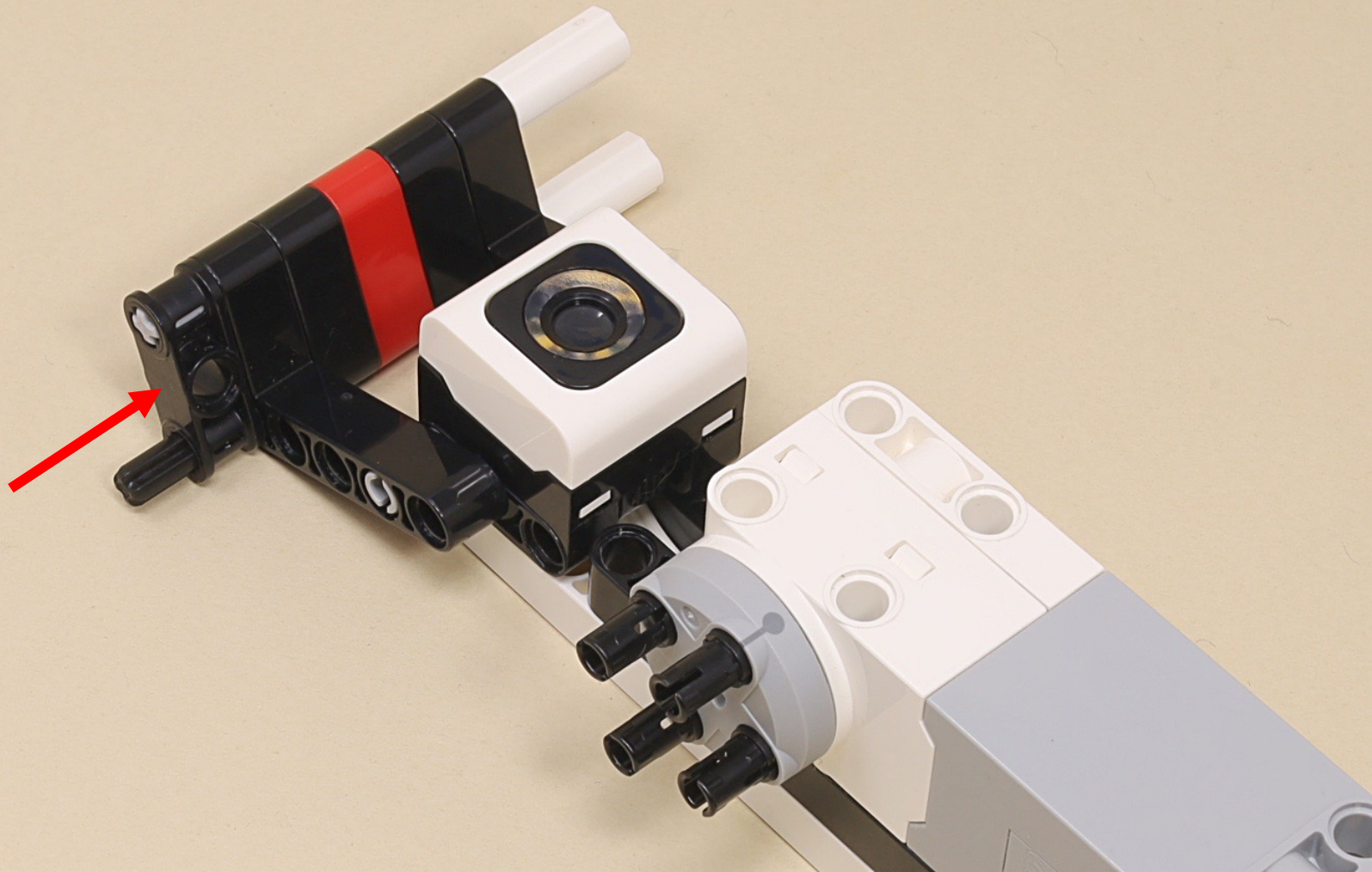


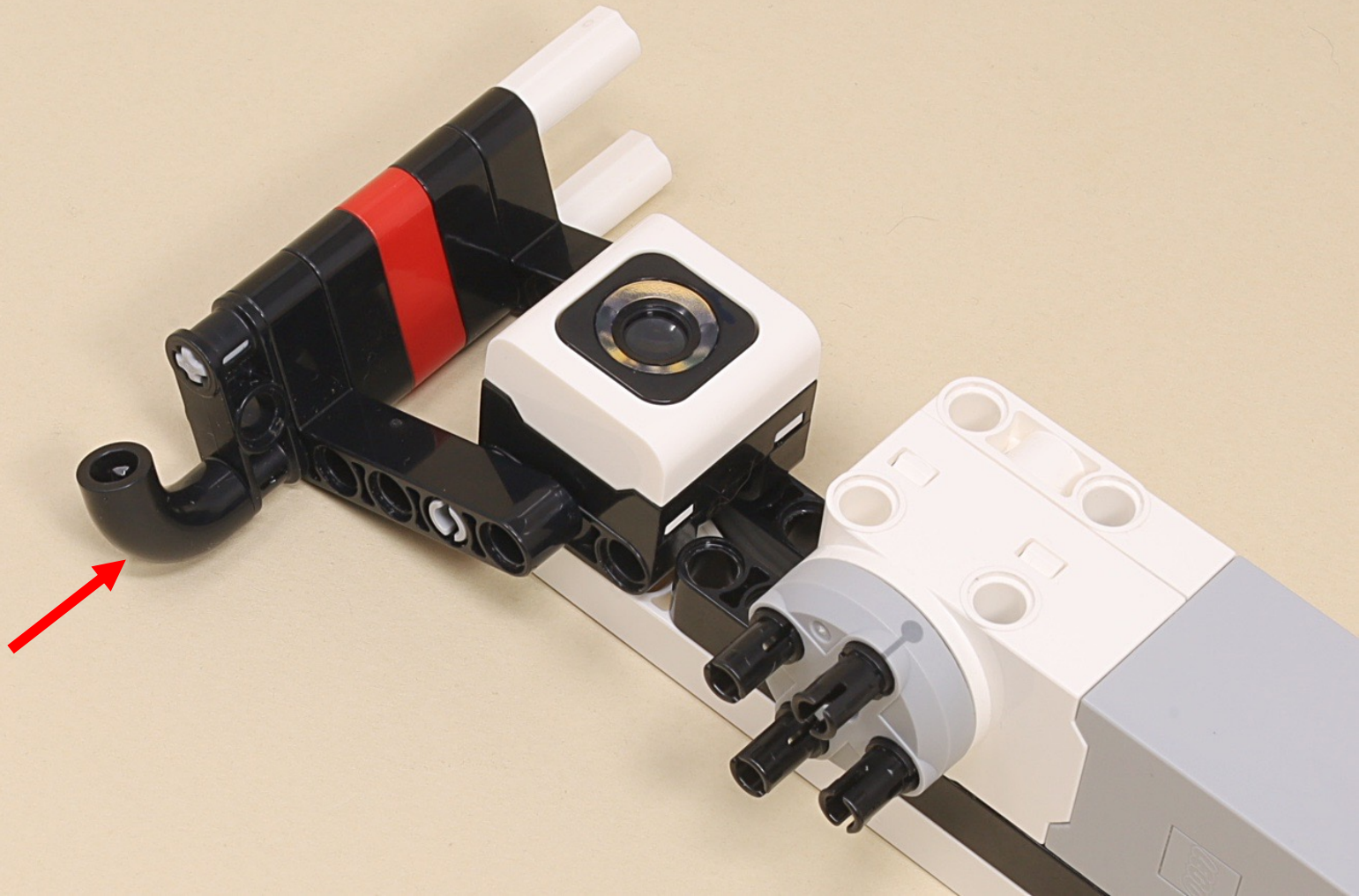




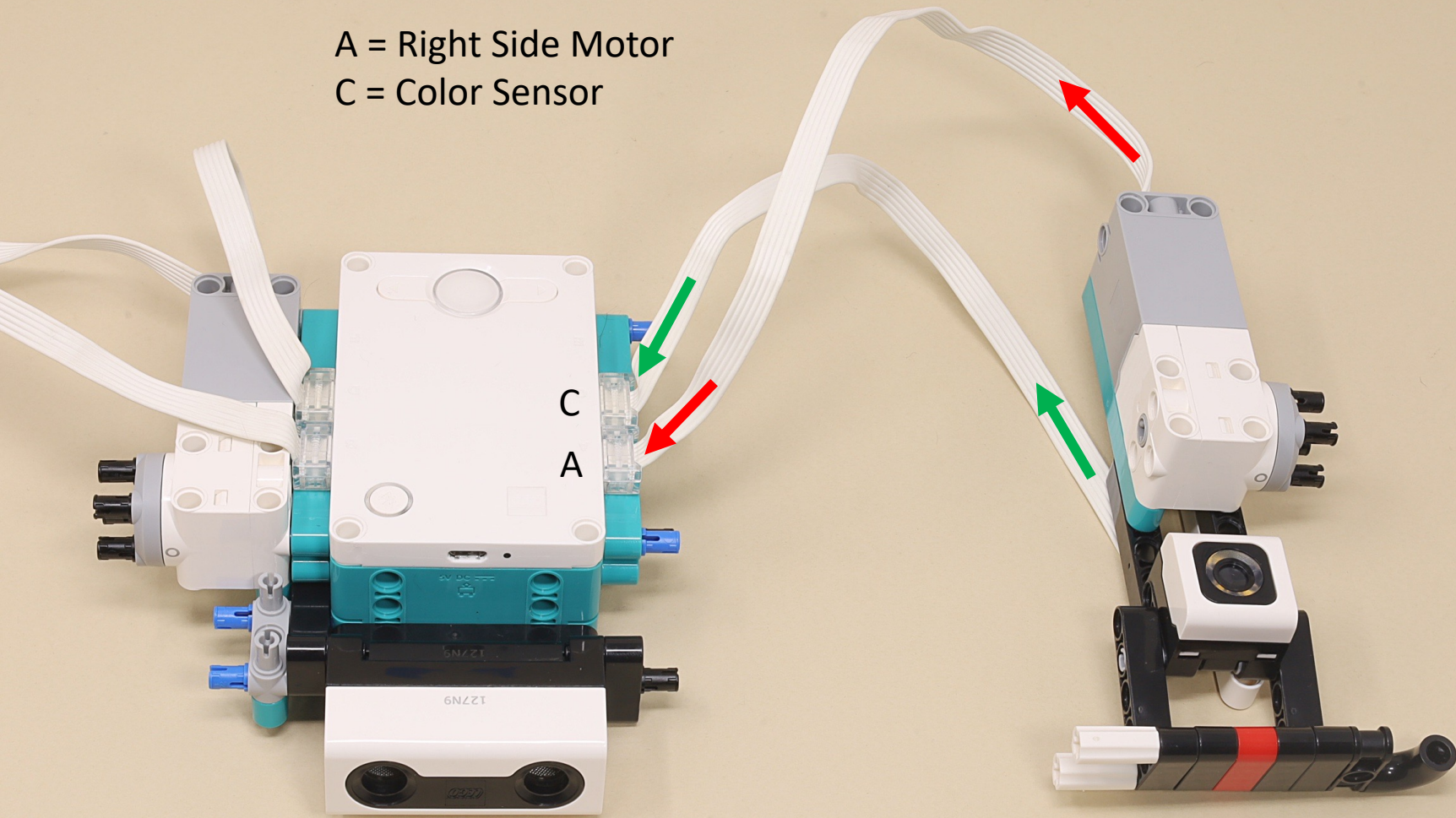


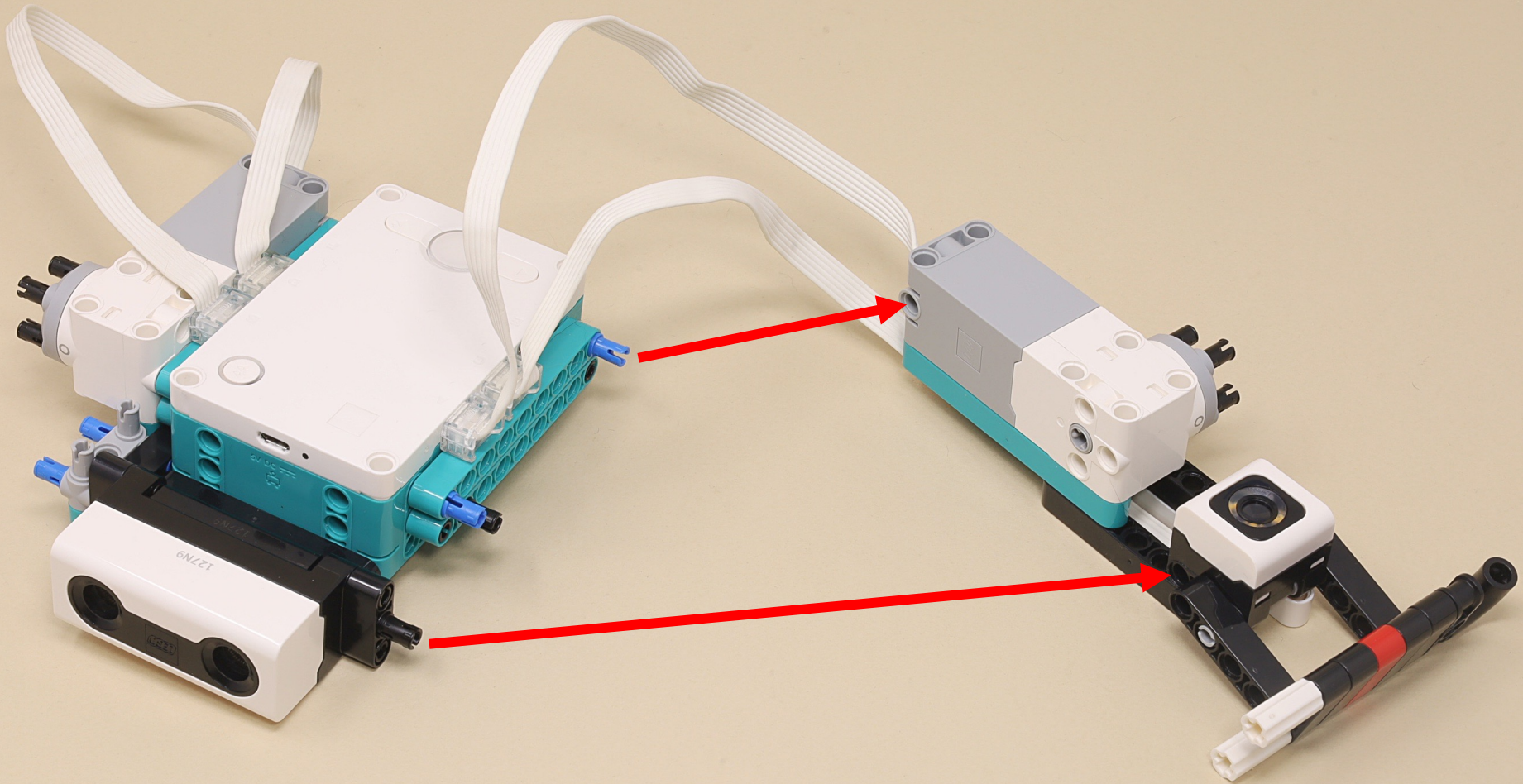


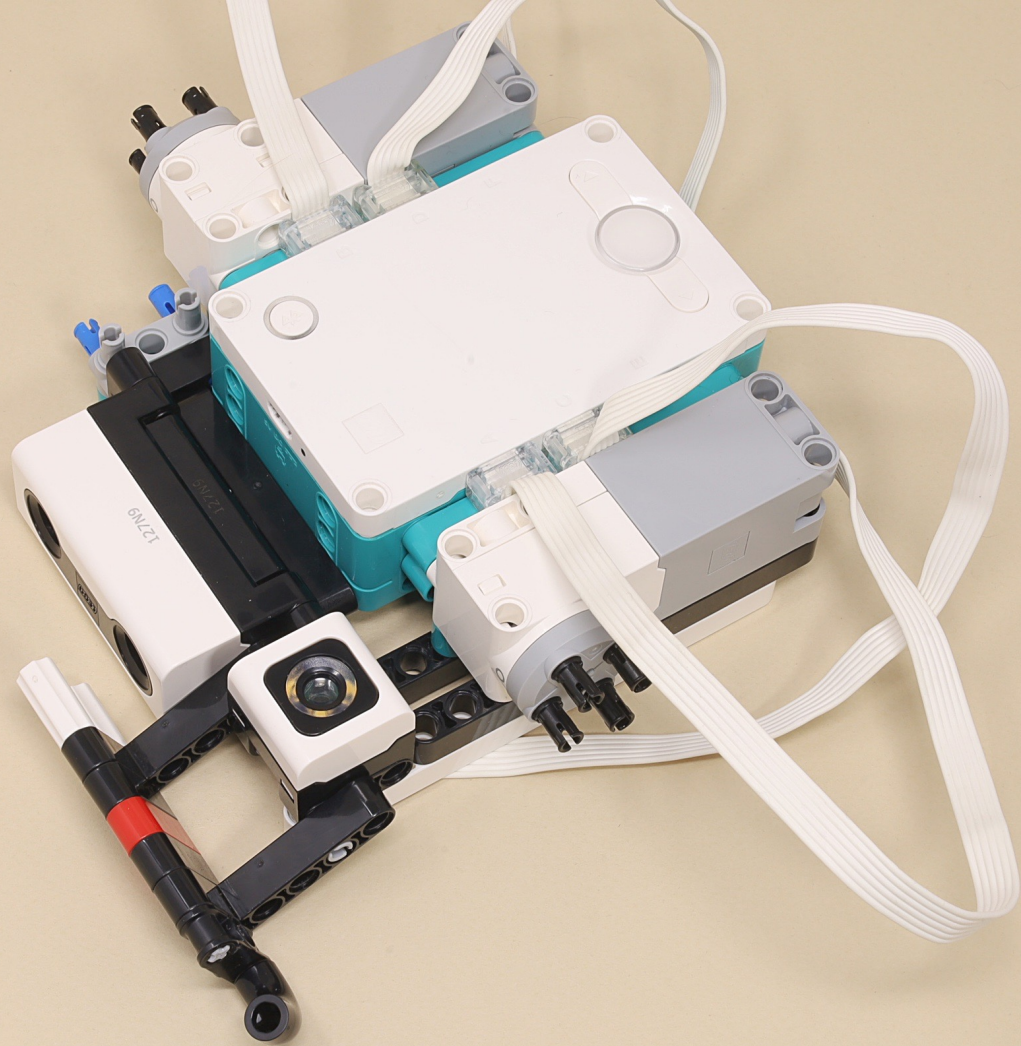


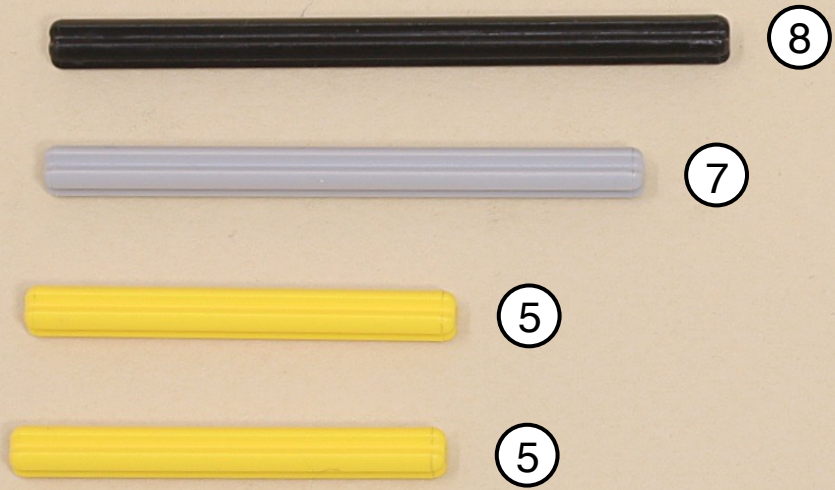


A = Right Side Motor
C = Color Sensor





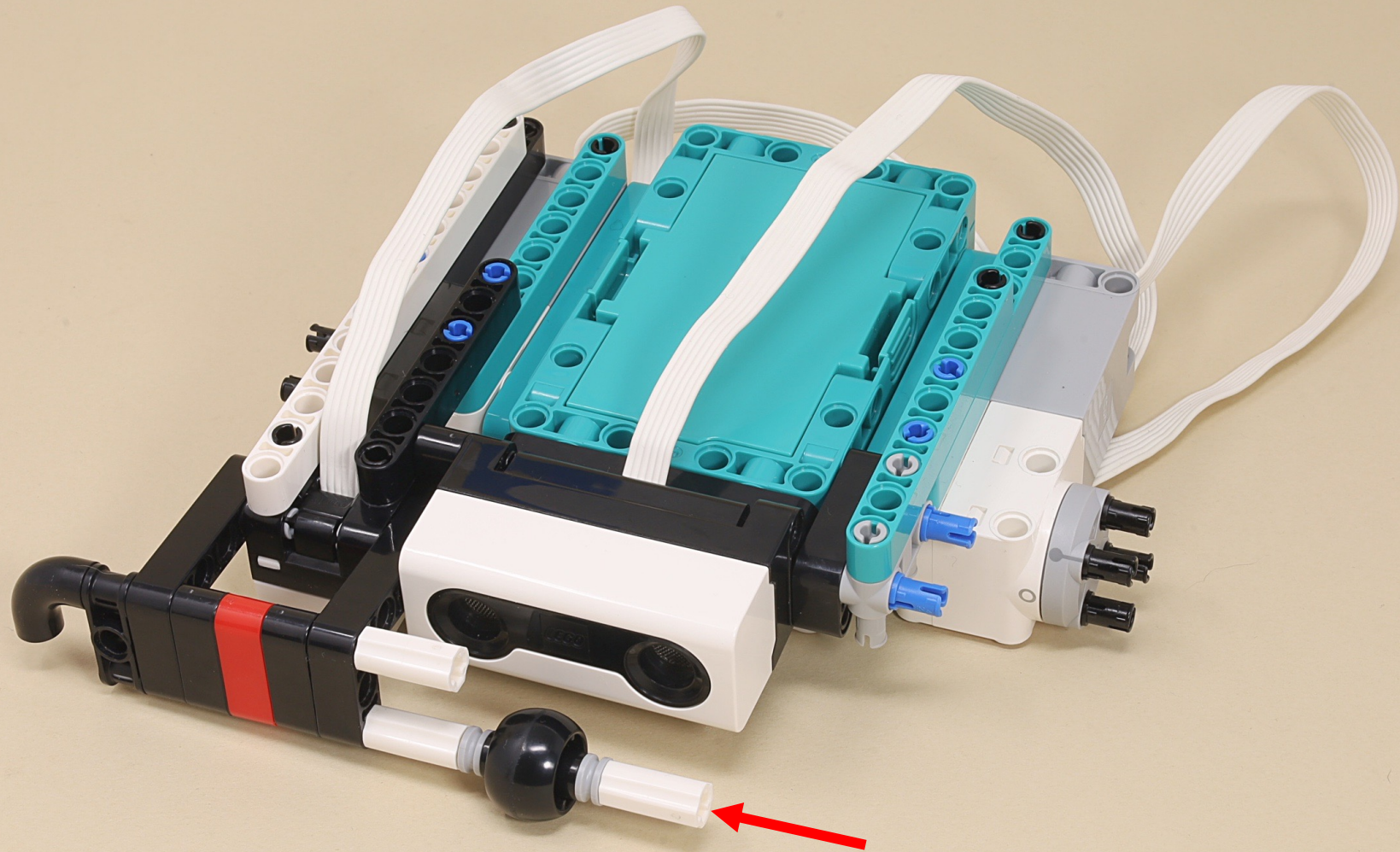






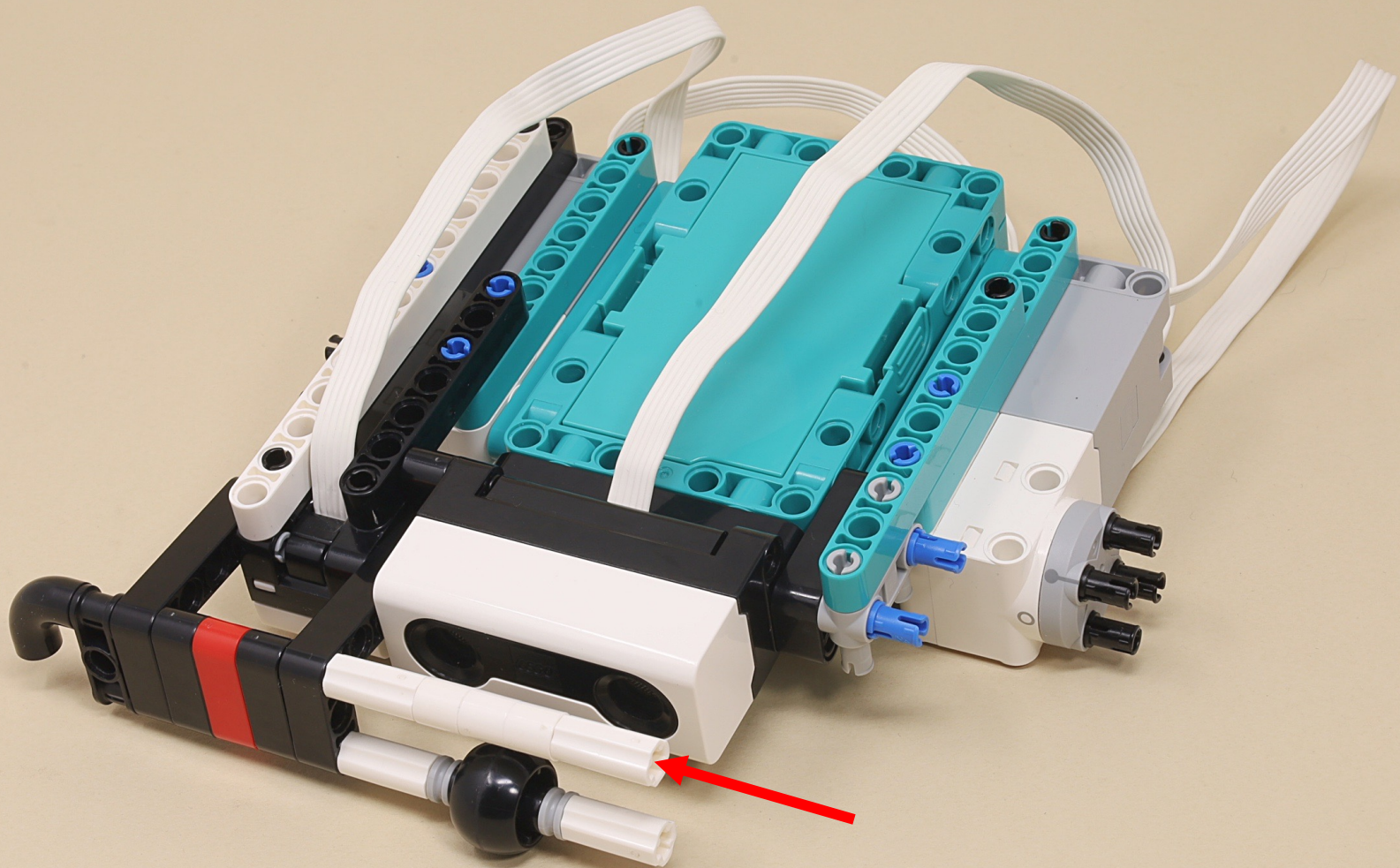


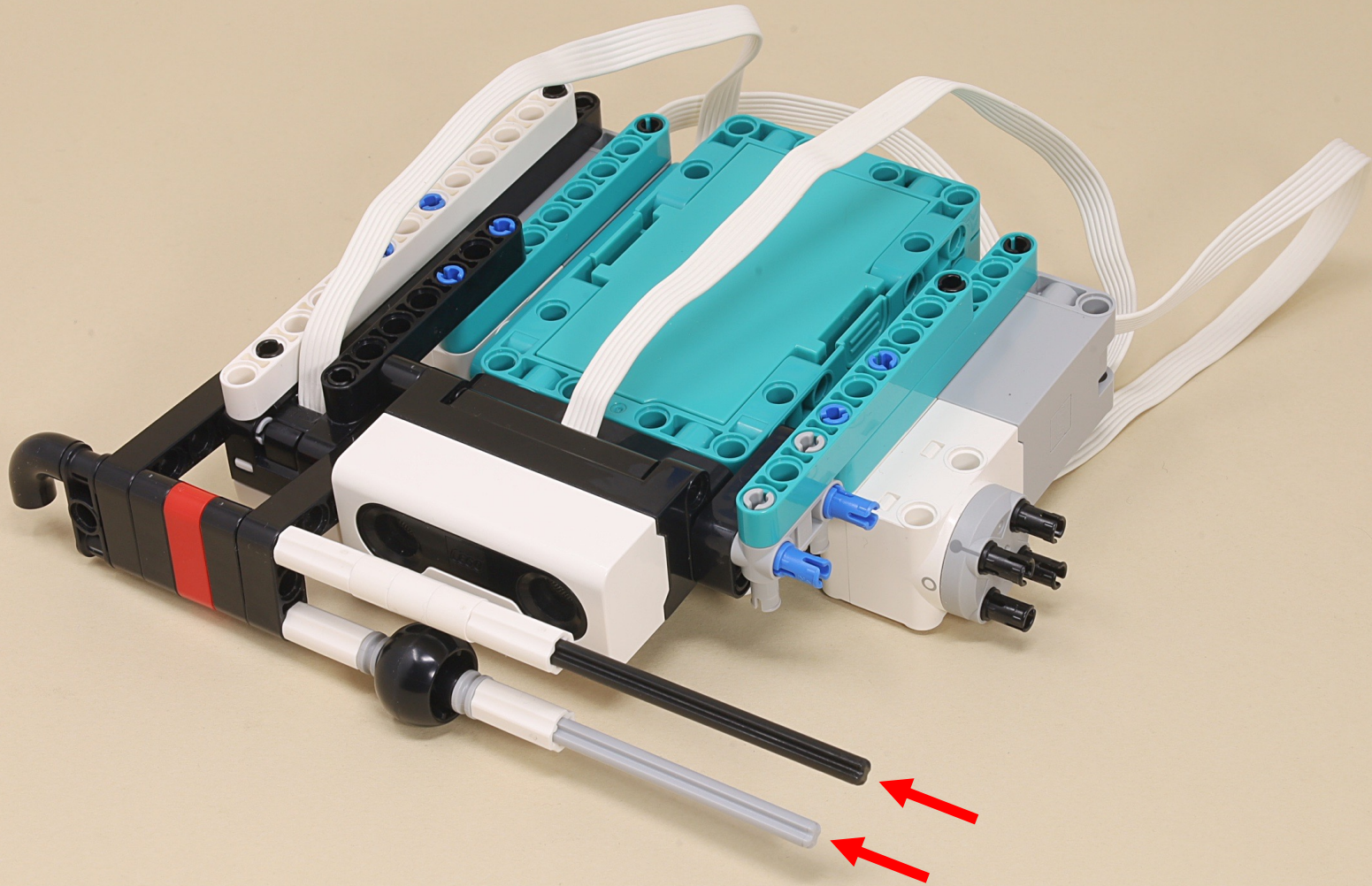














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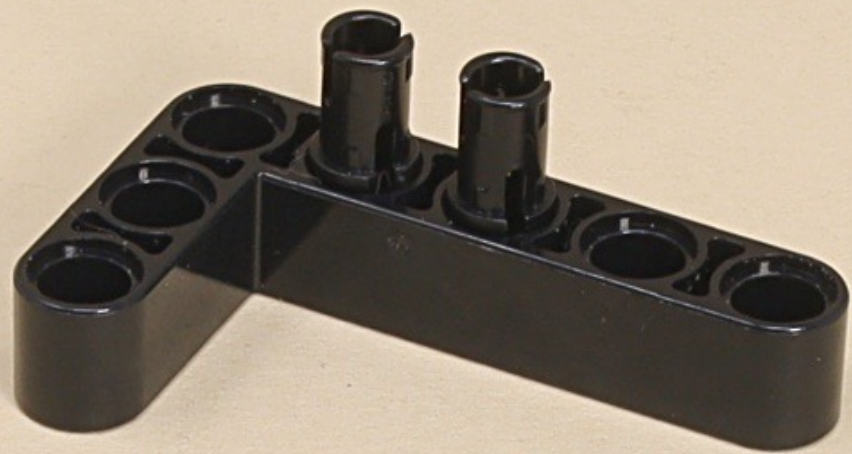


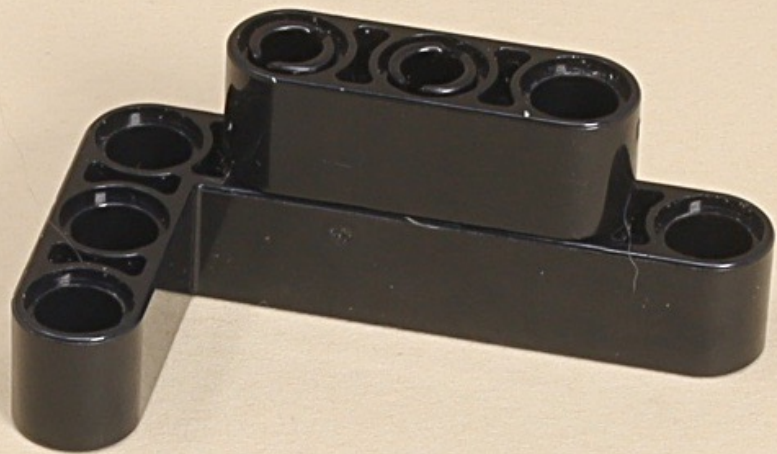
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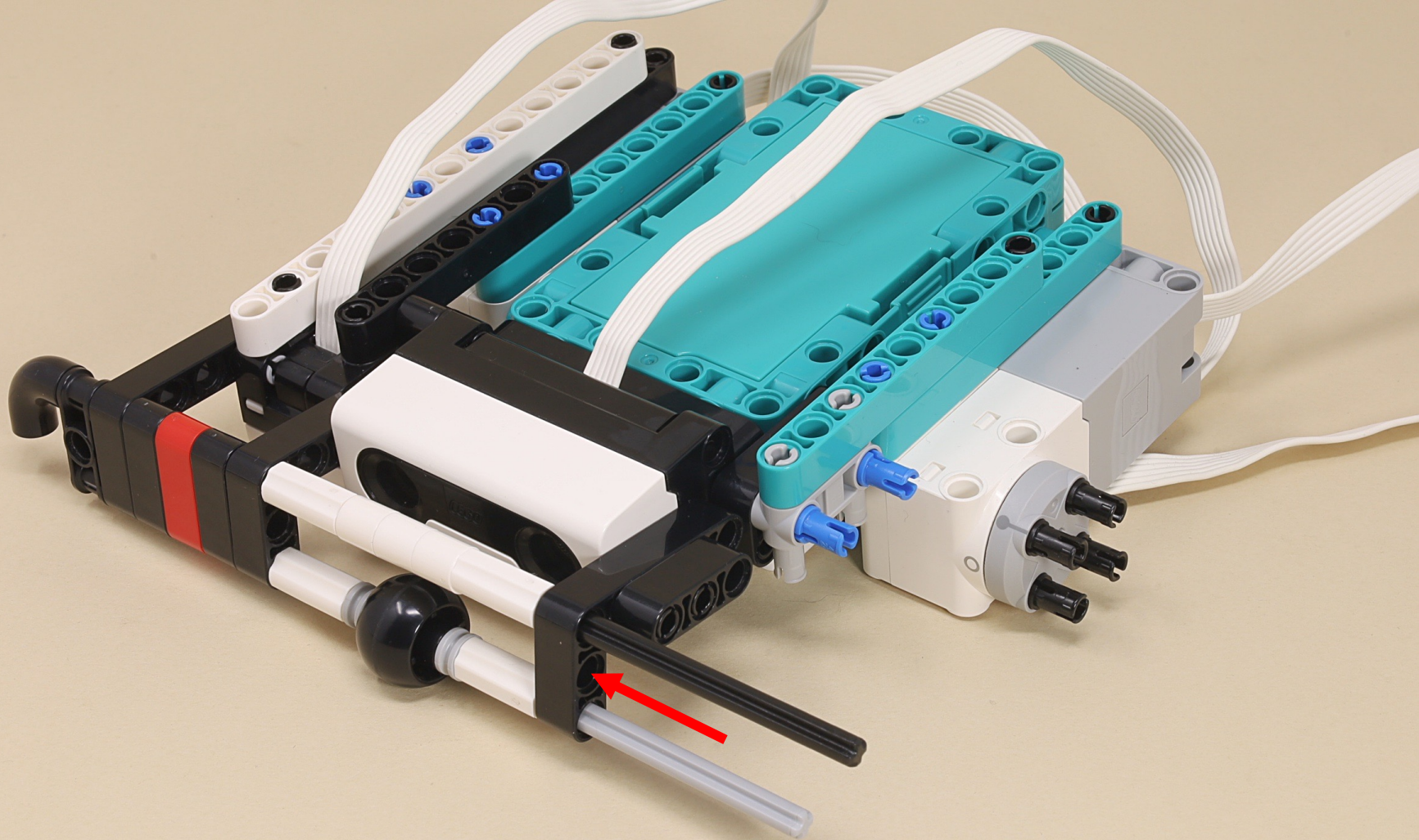


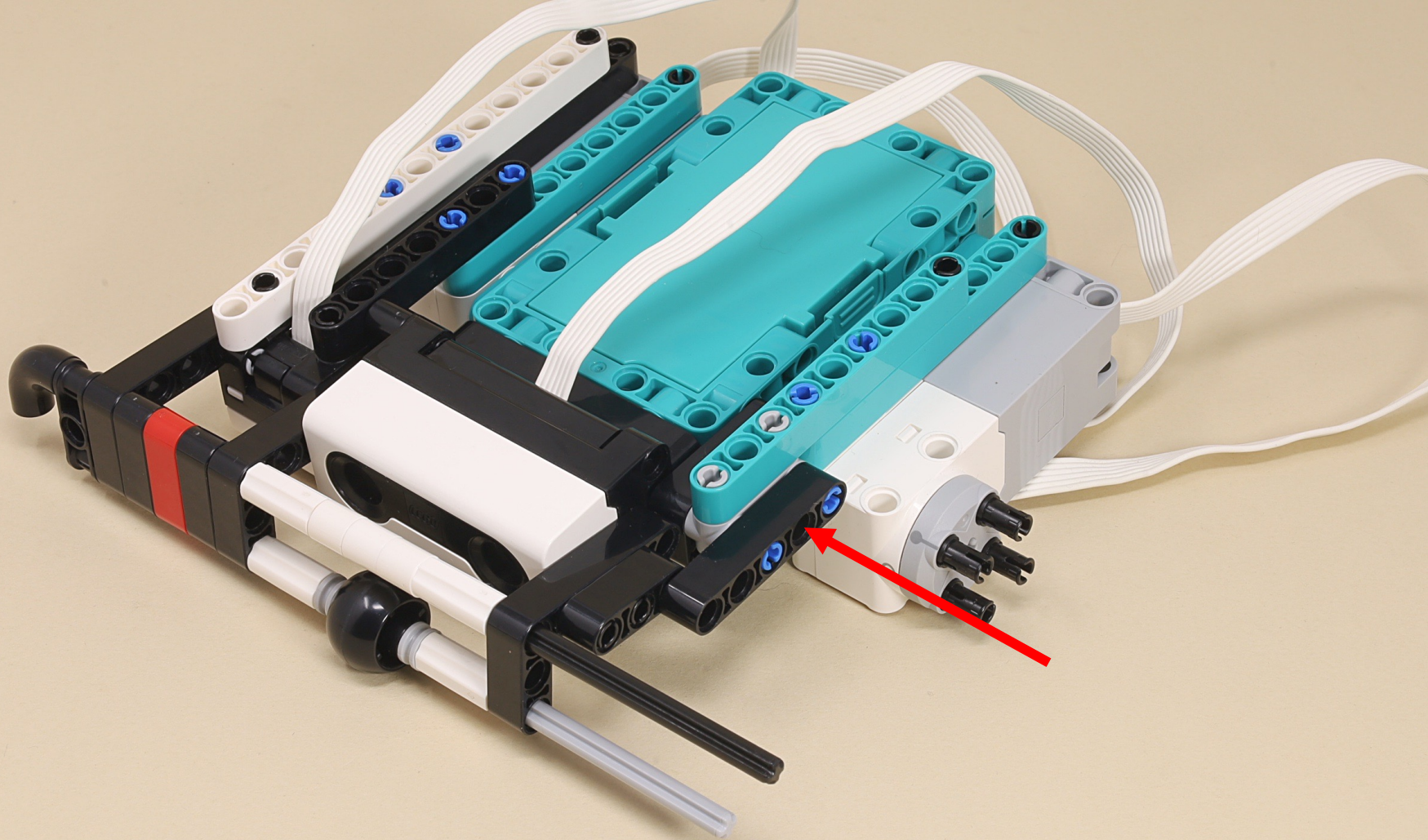
(6 x)

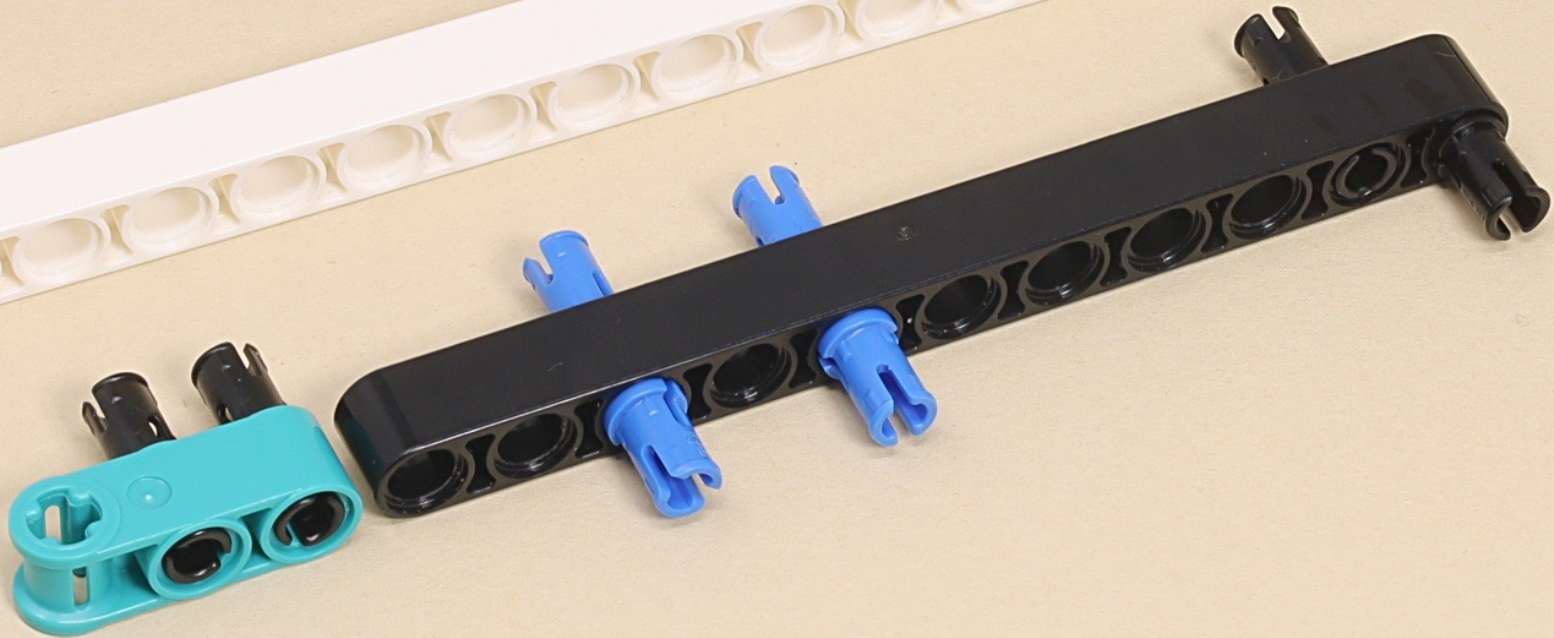
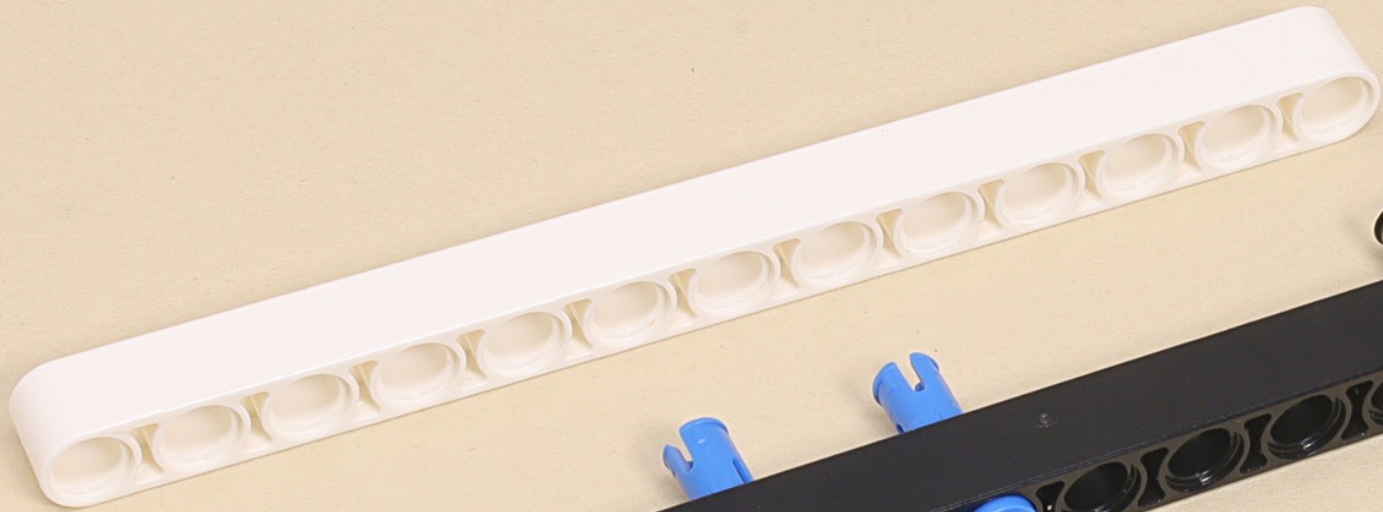


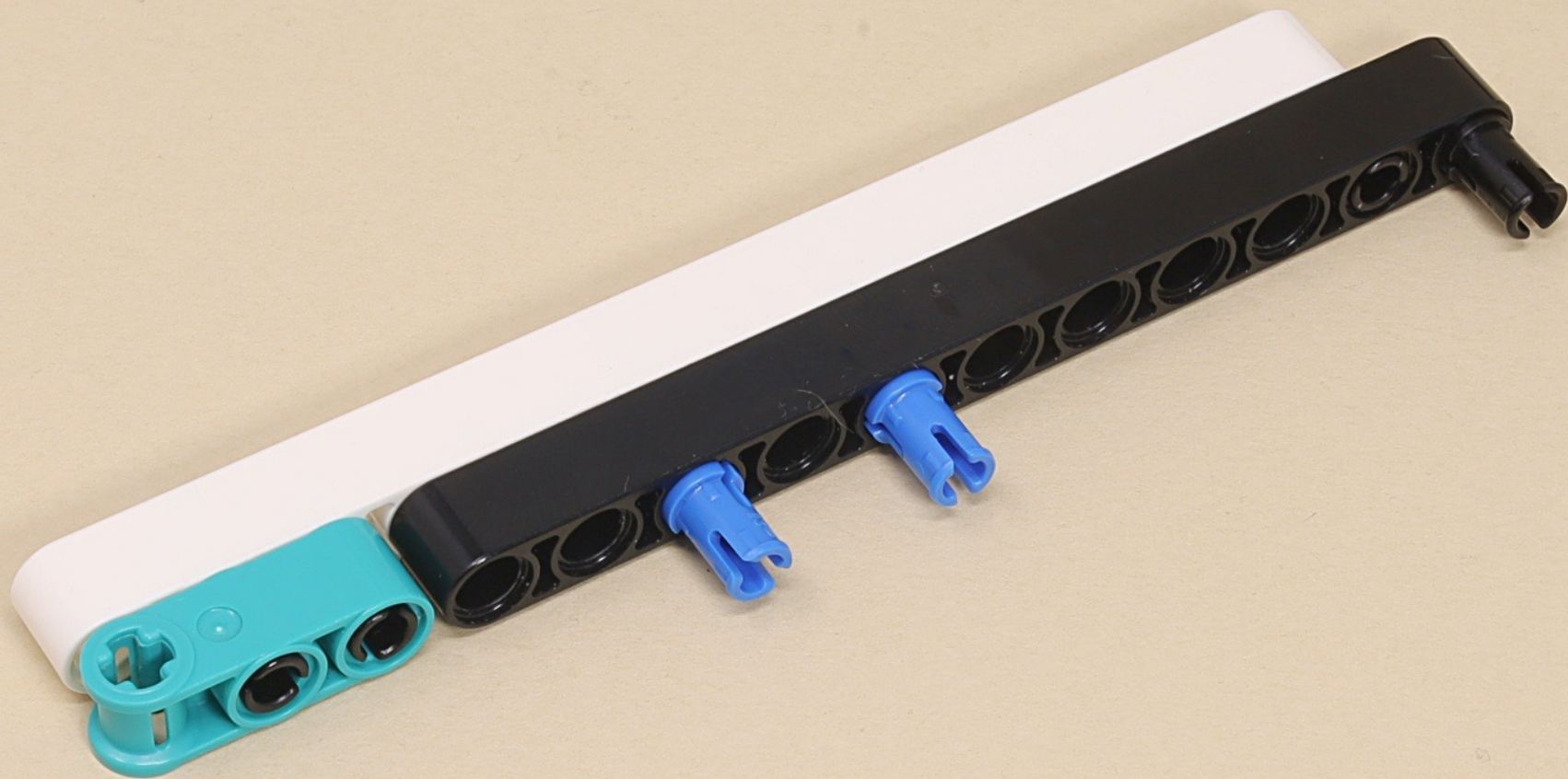


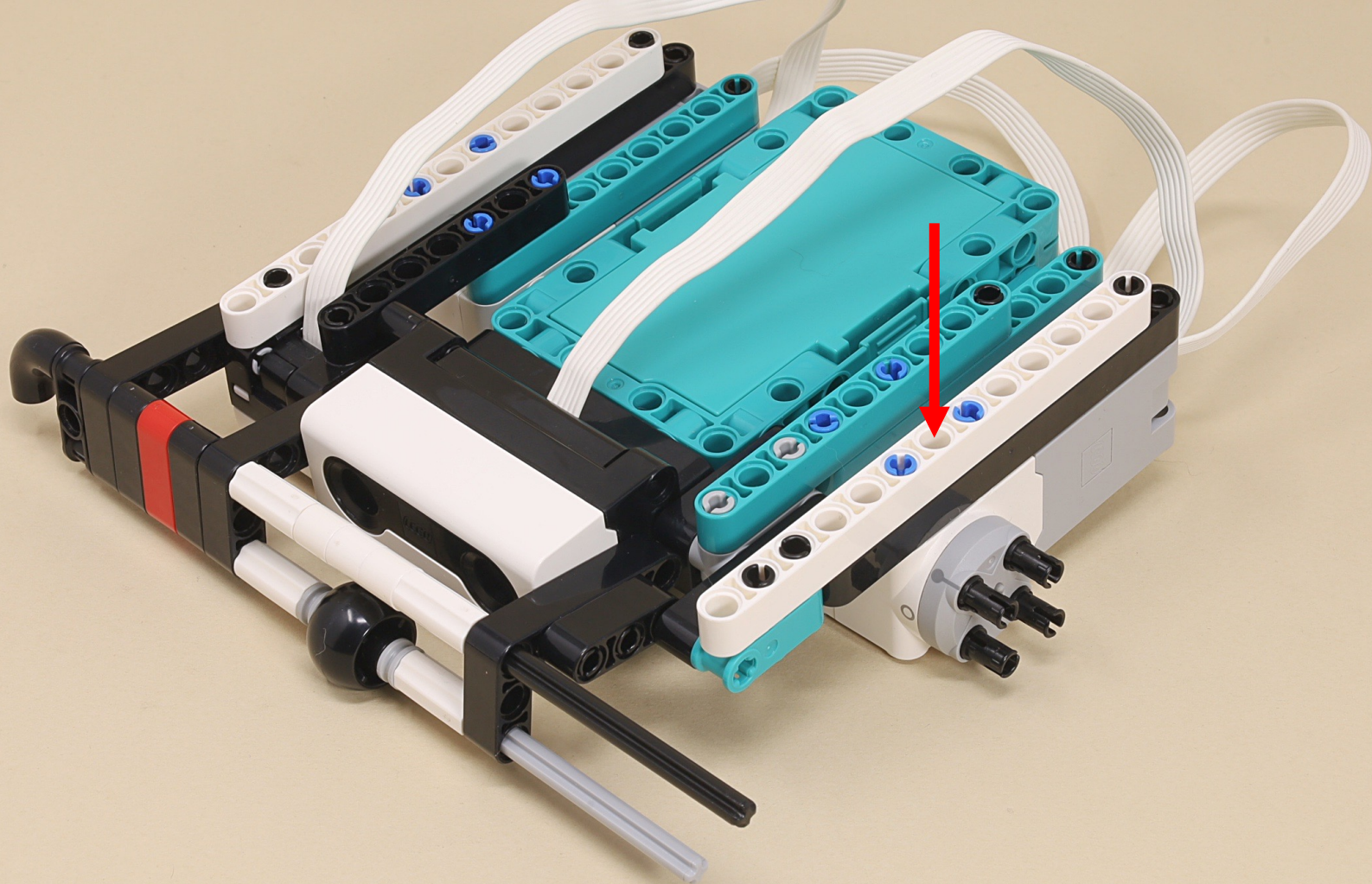






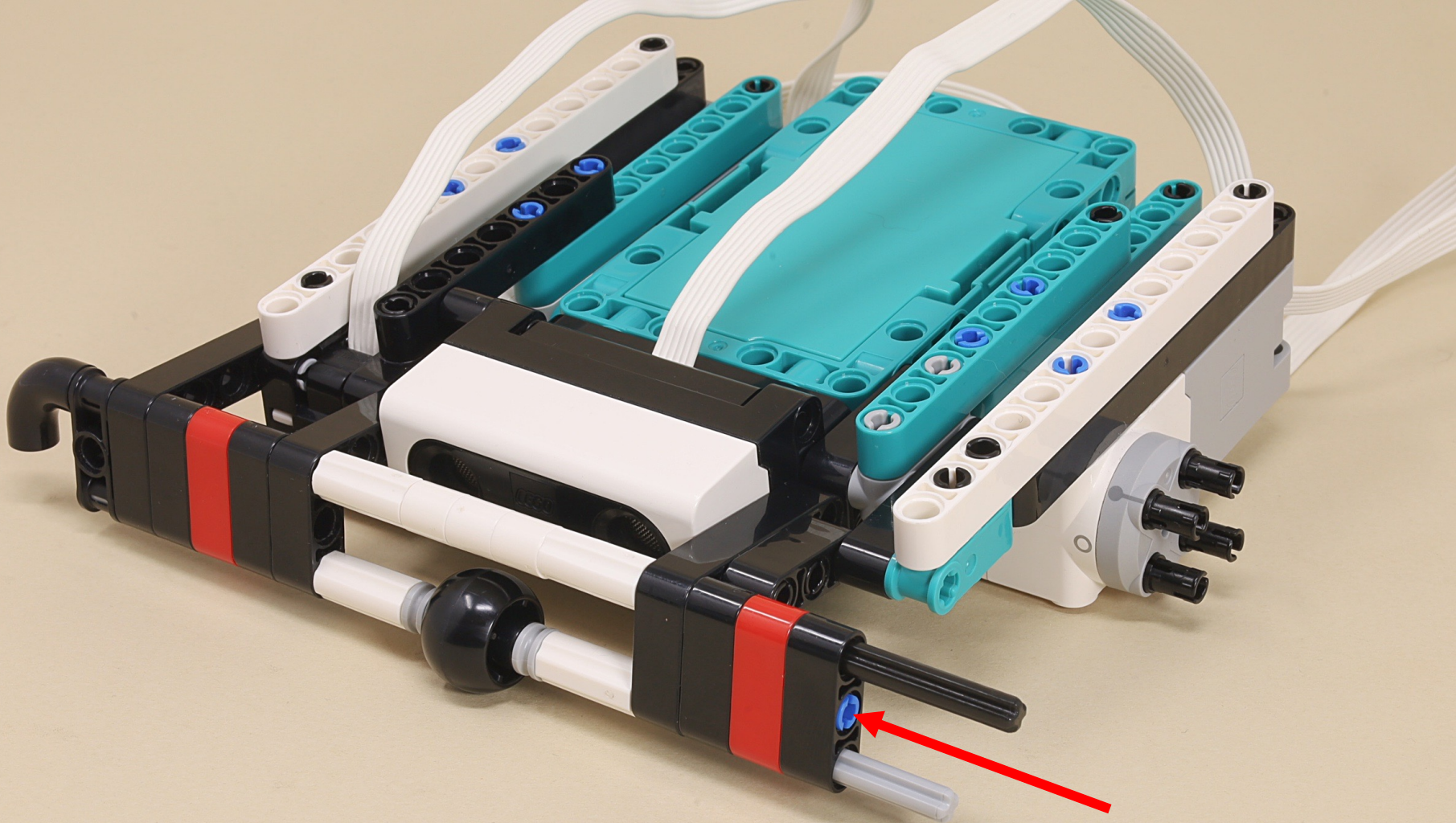


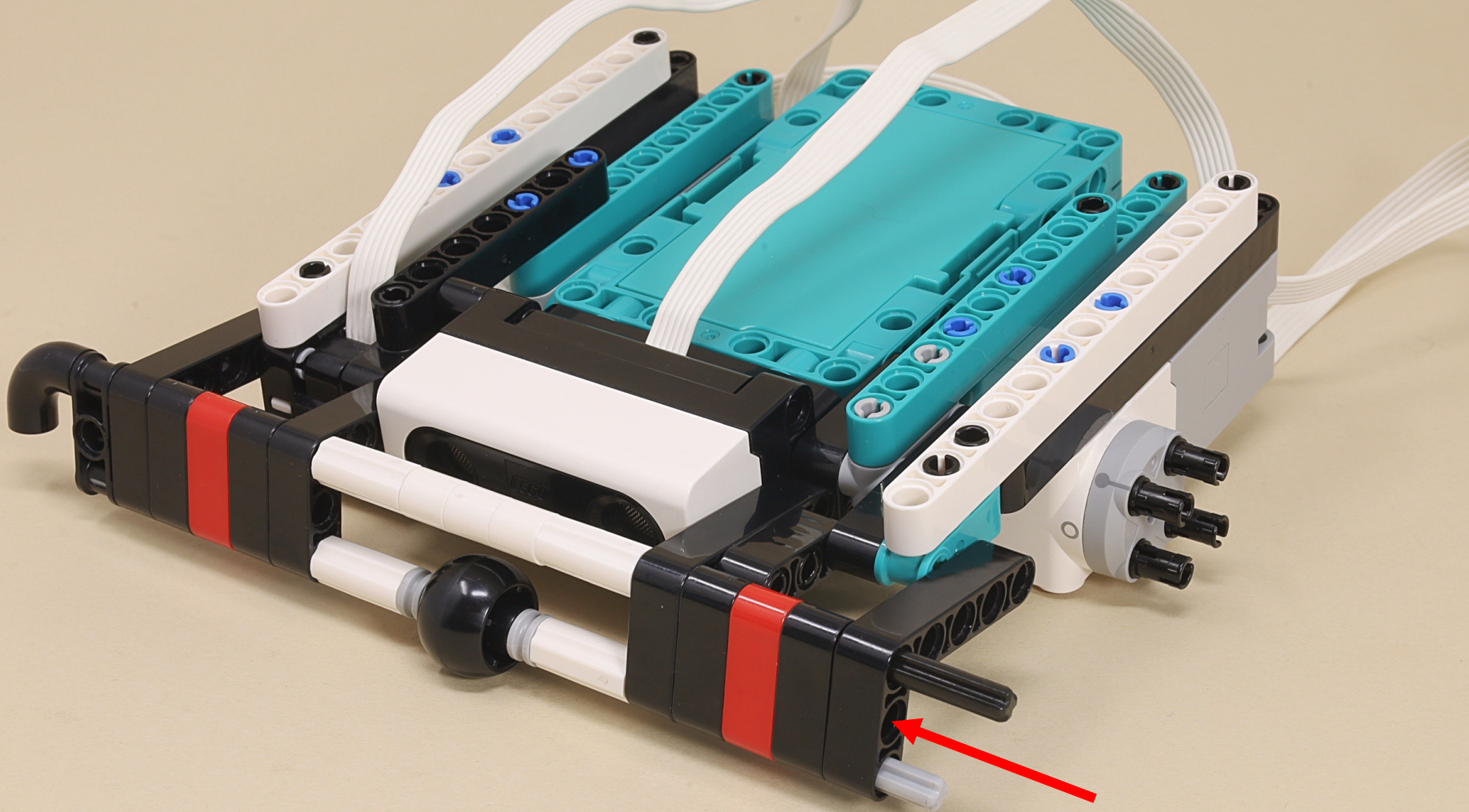


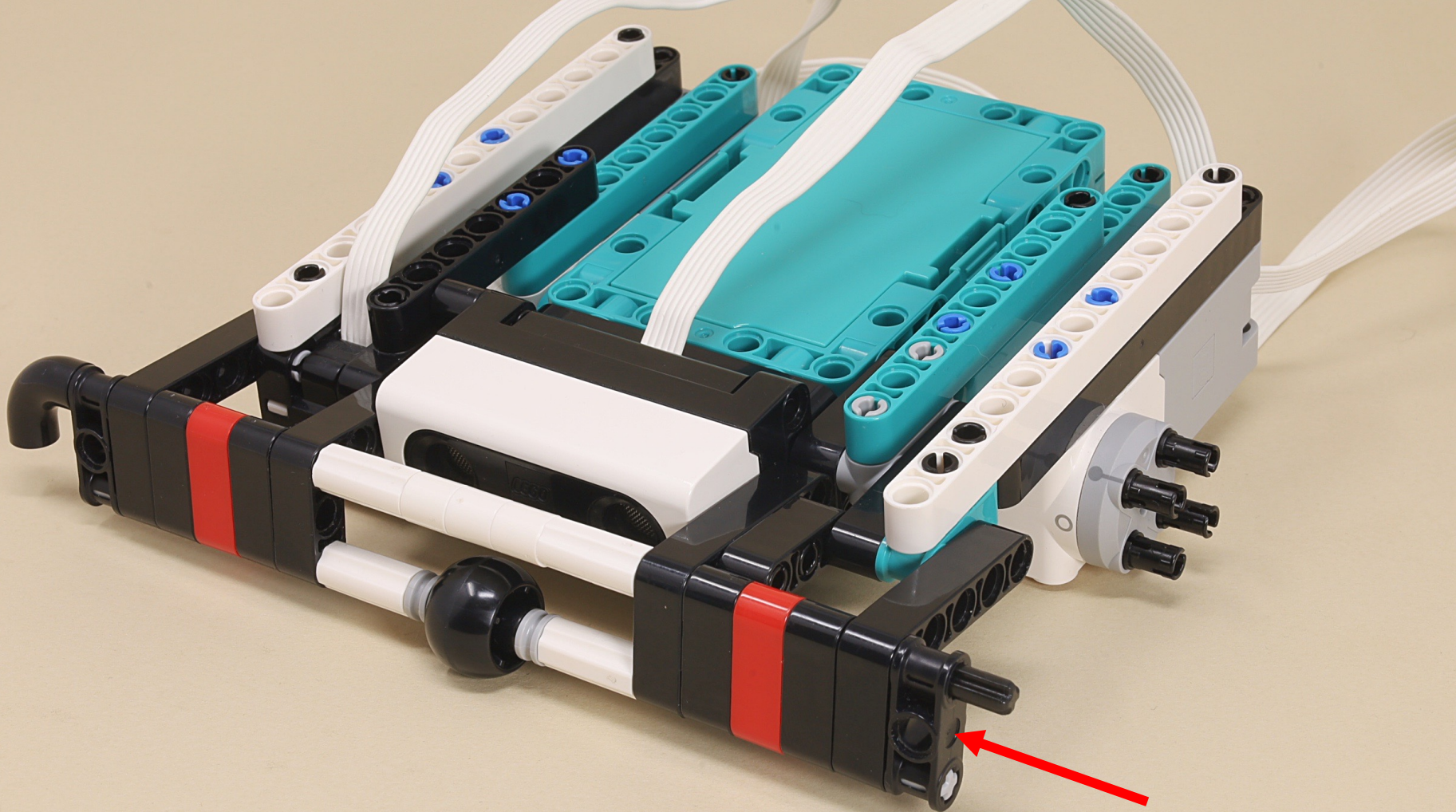


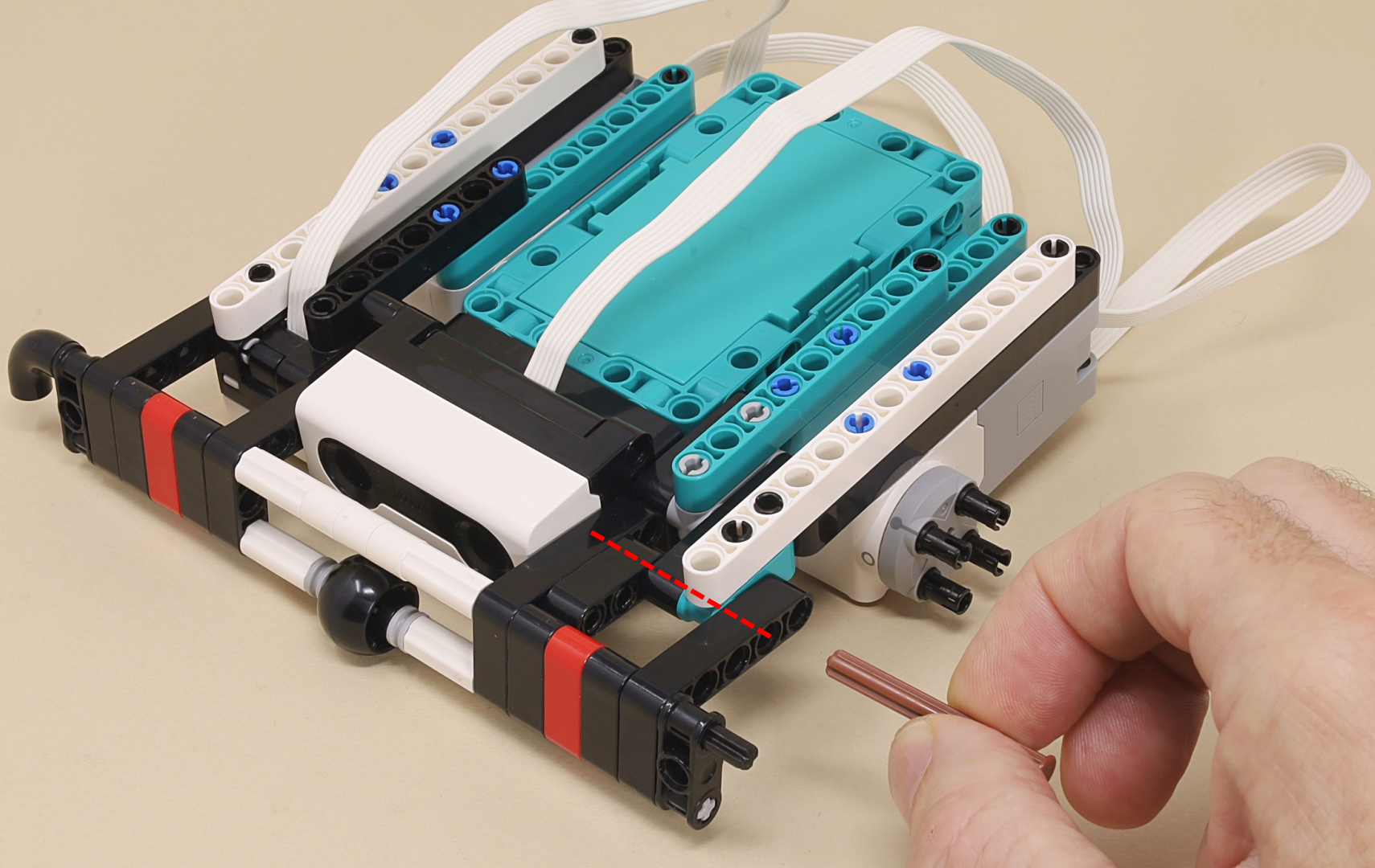


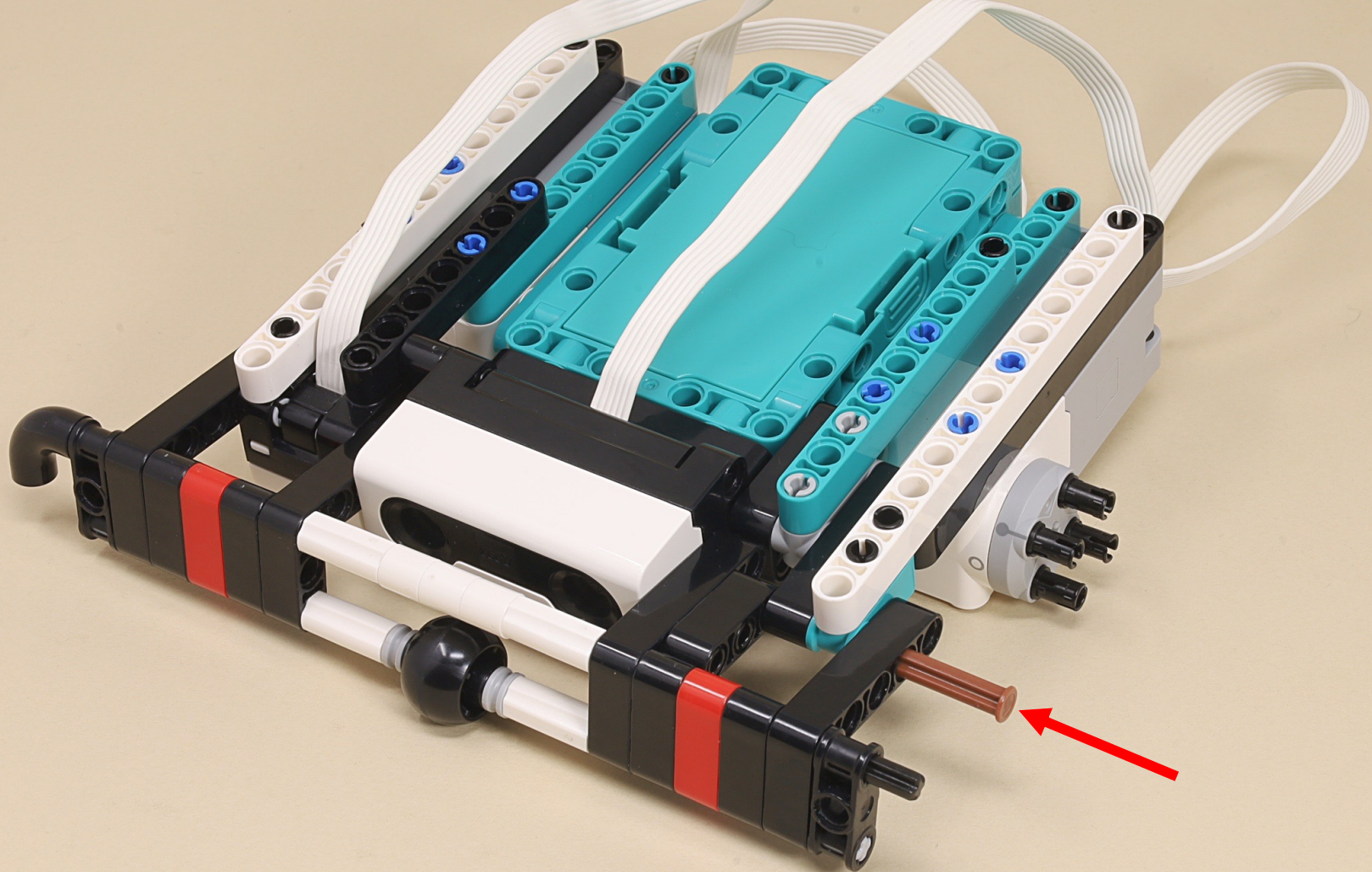


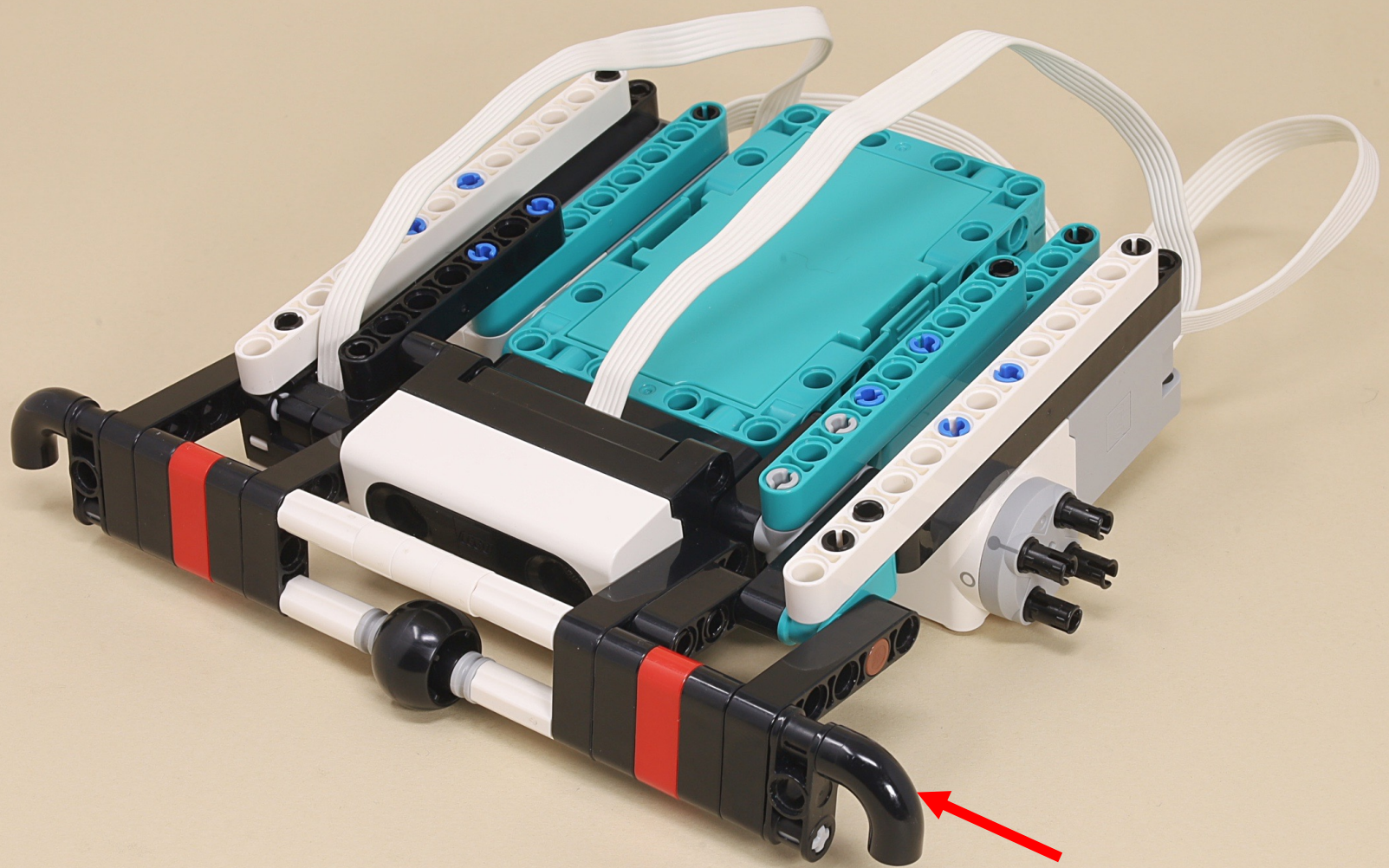




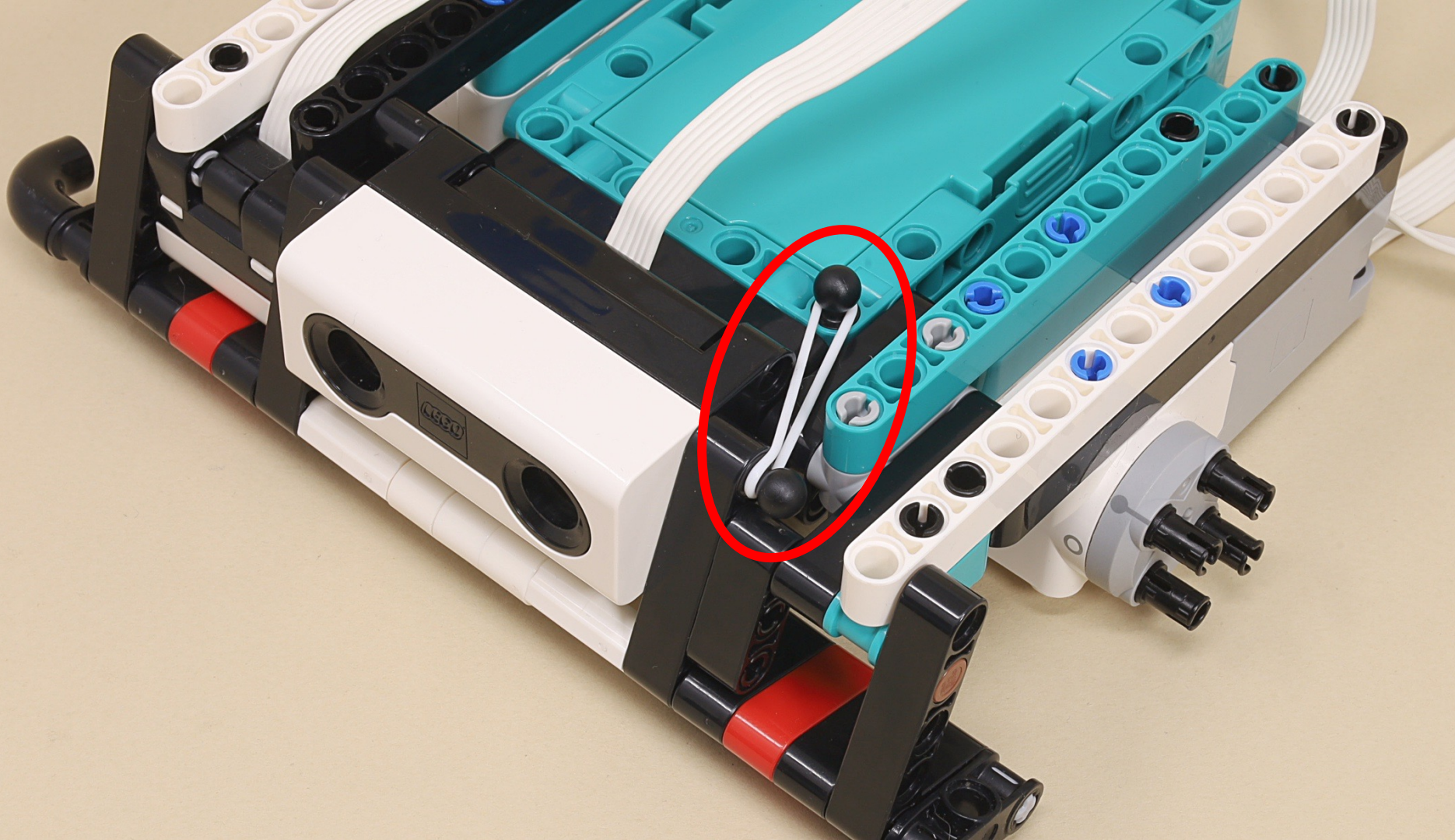


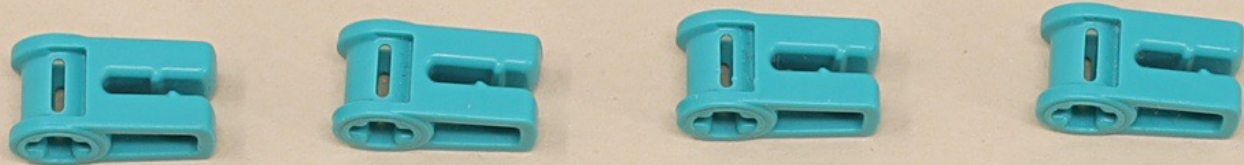








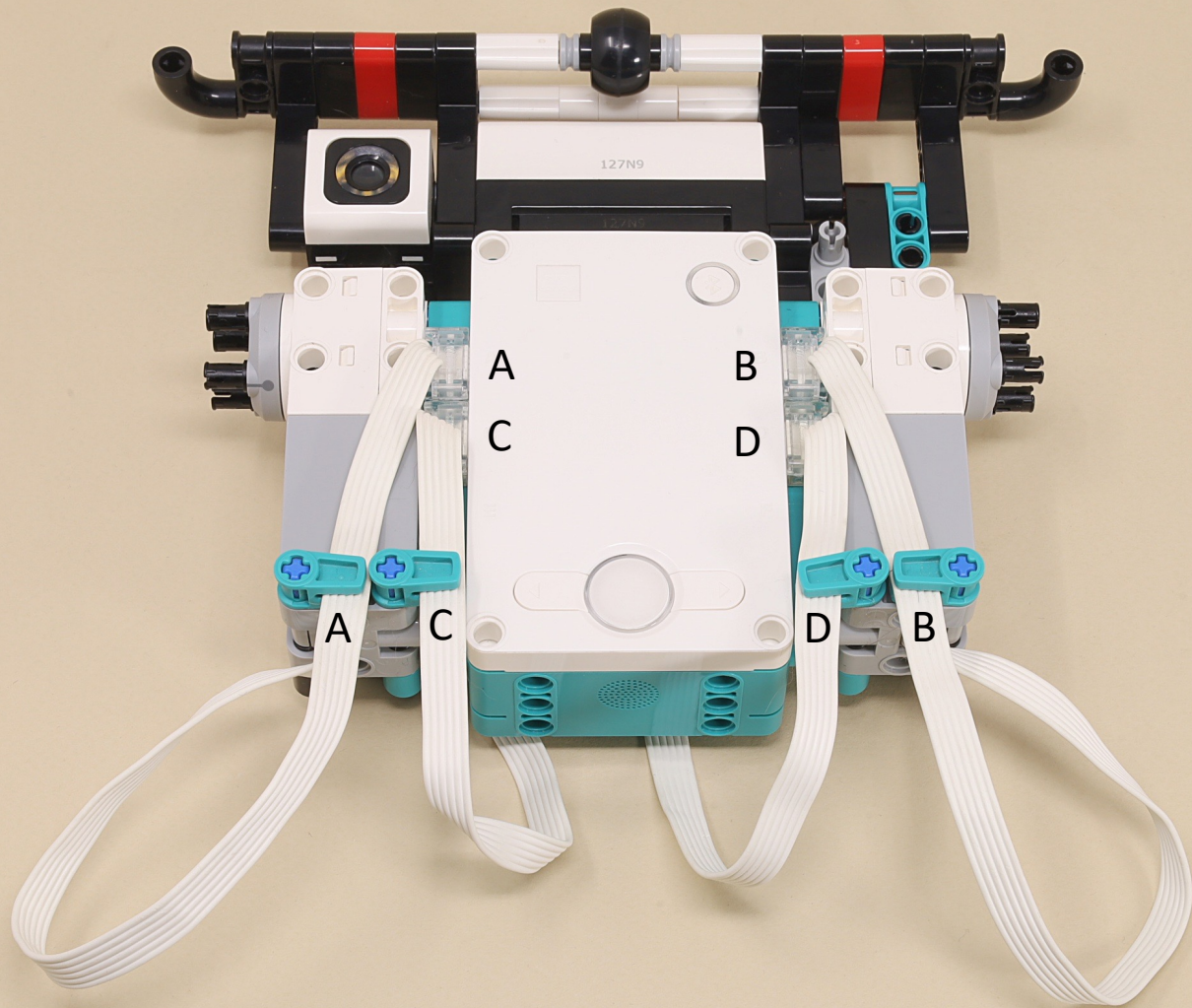


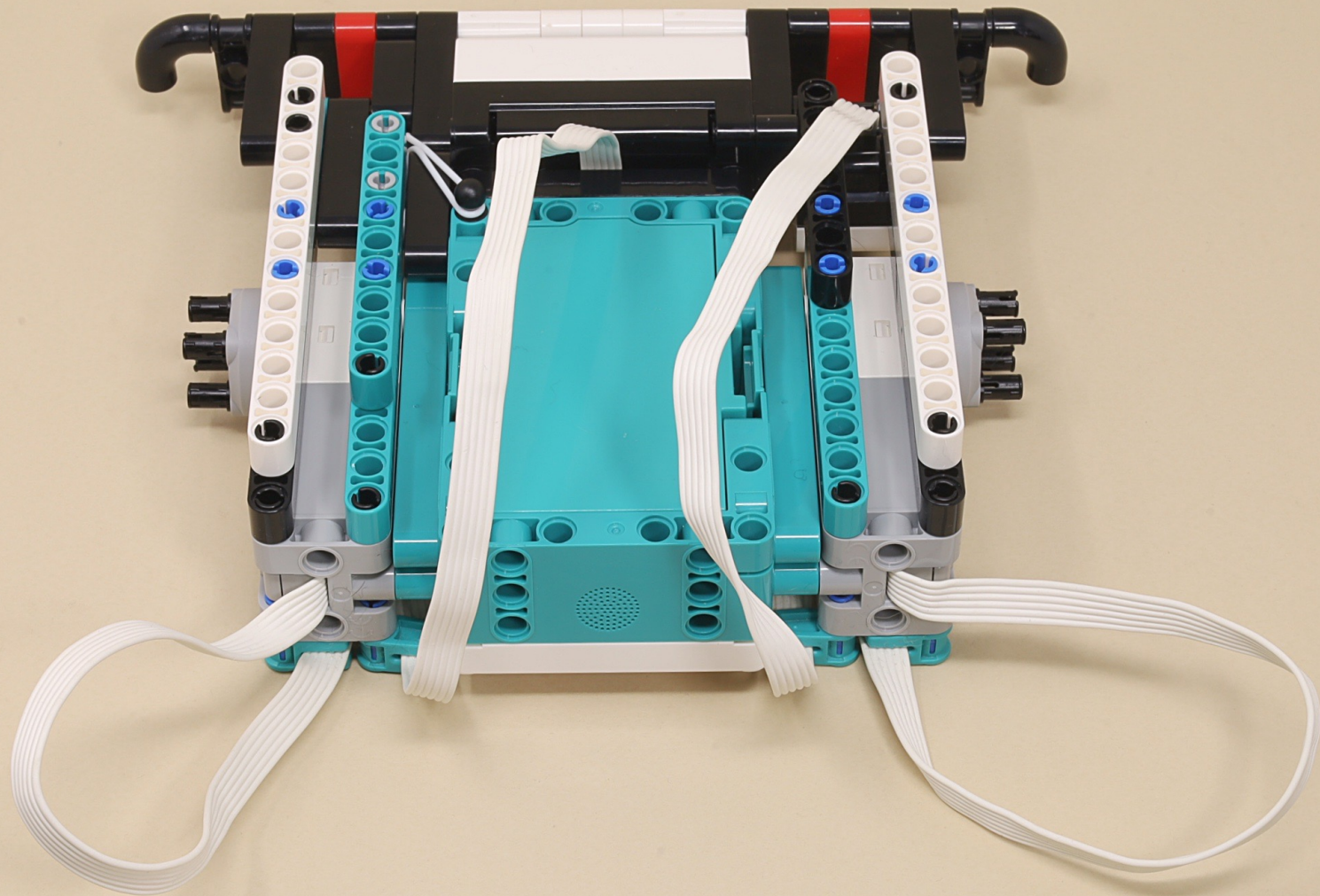


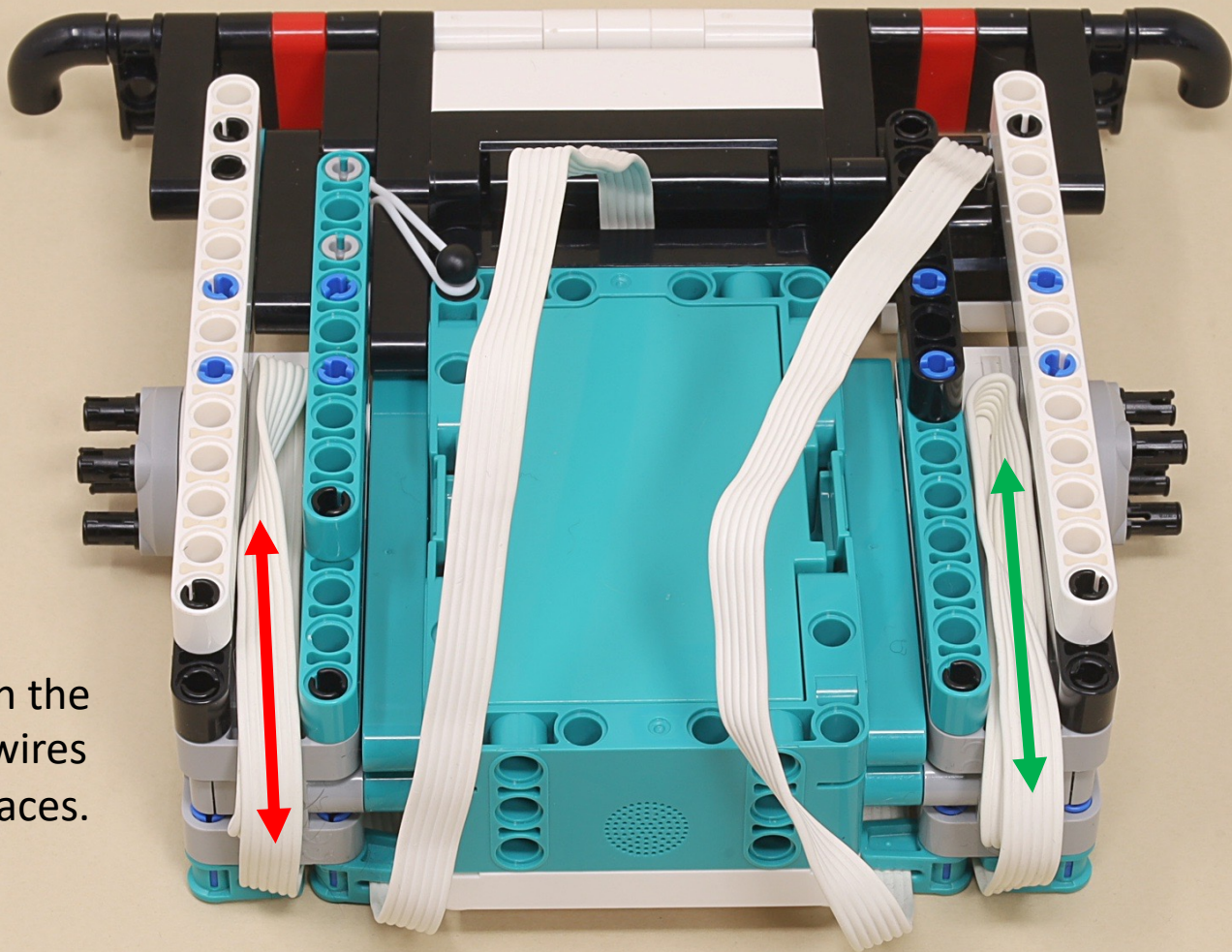
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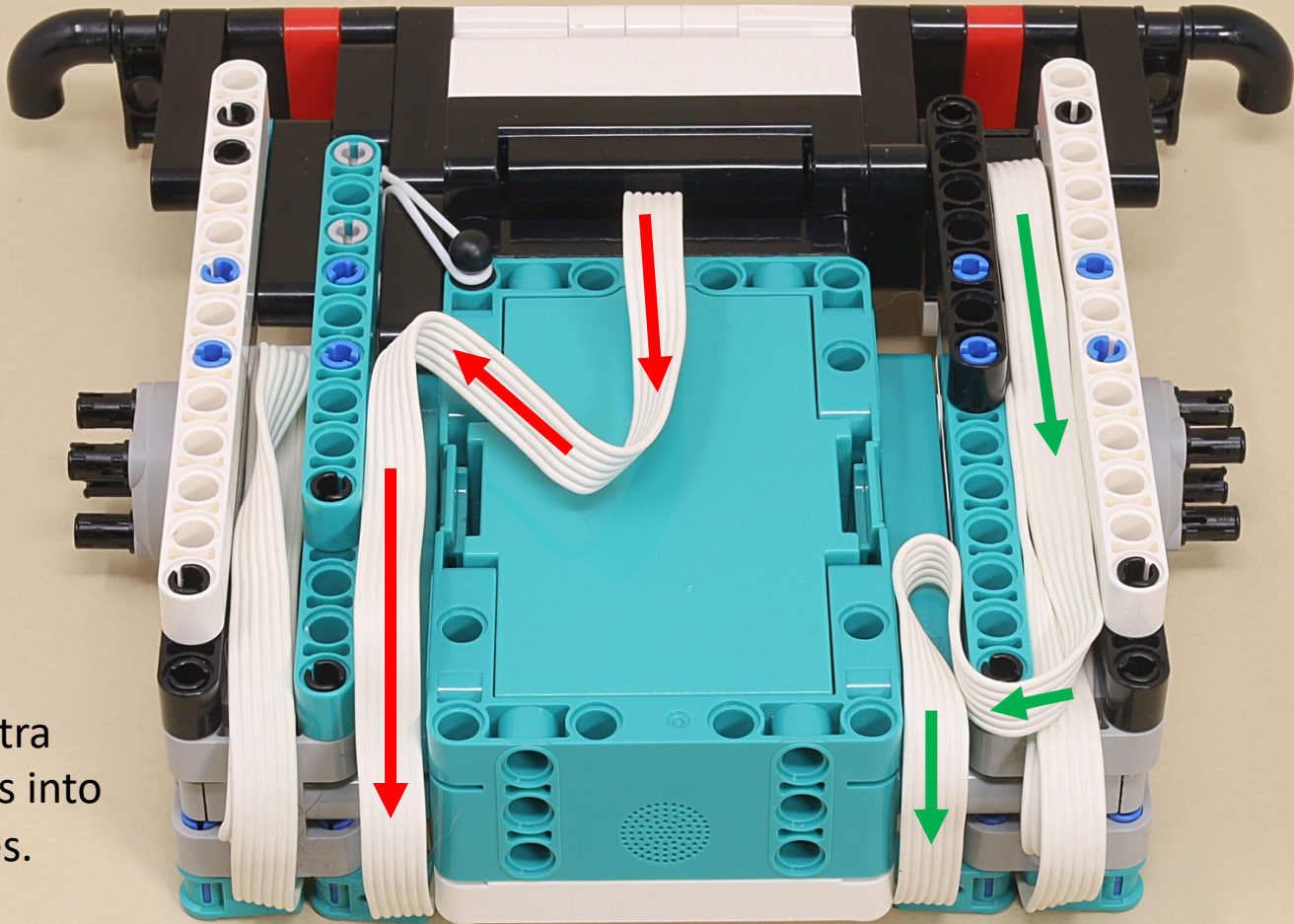






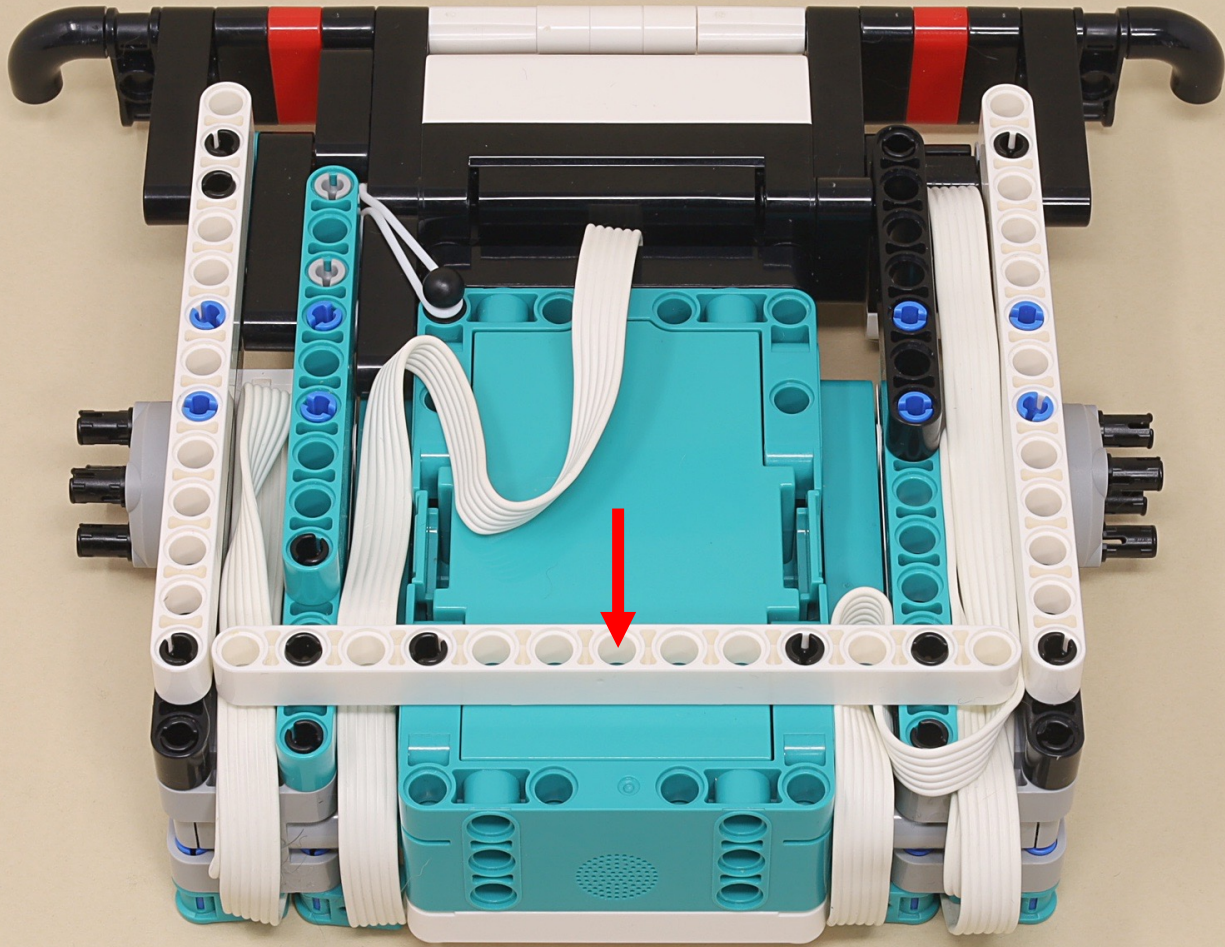


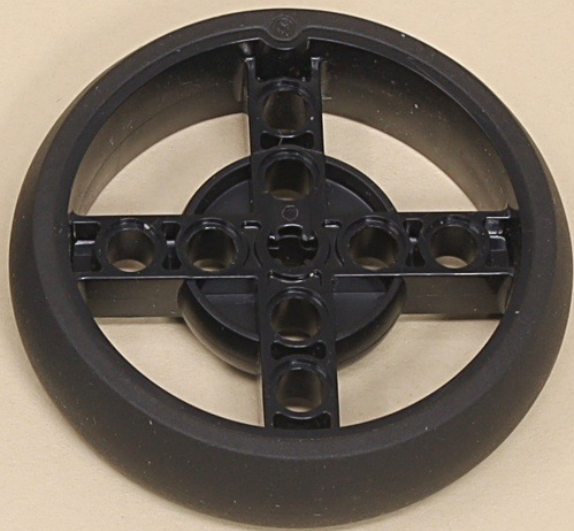
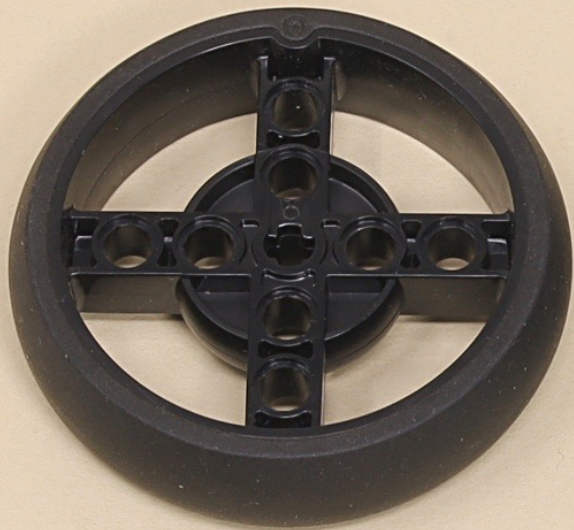
Fold and push the extra motor wires into these spaces.

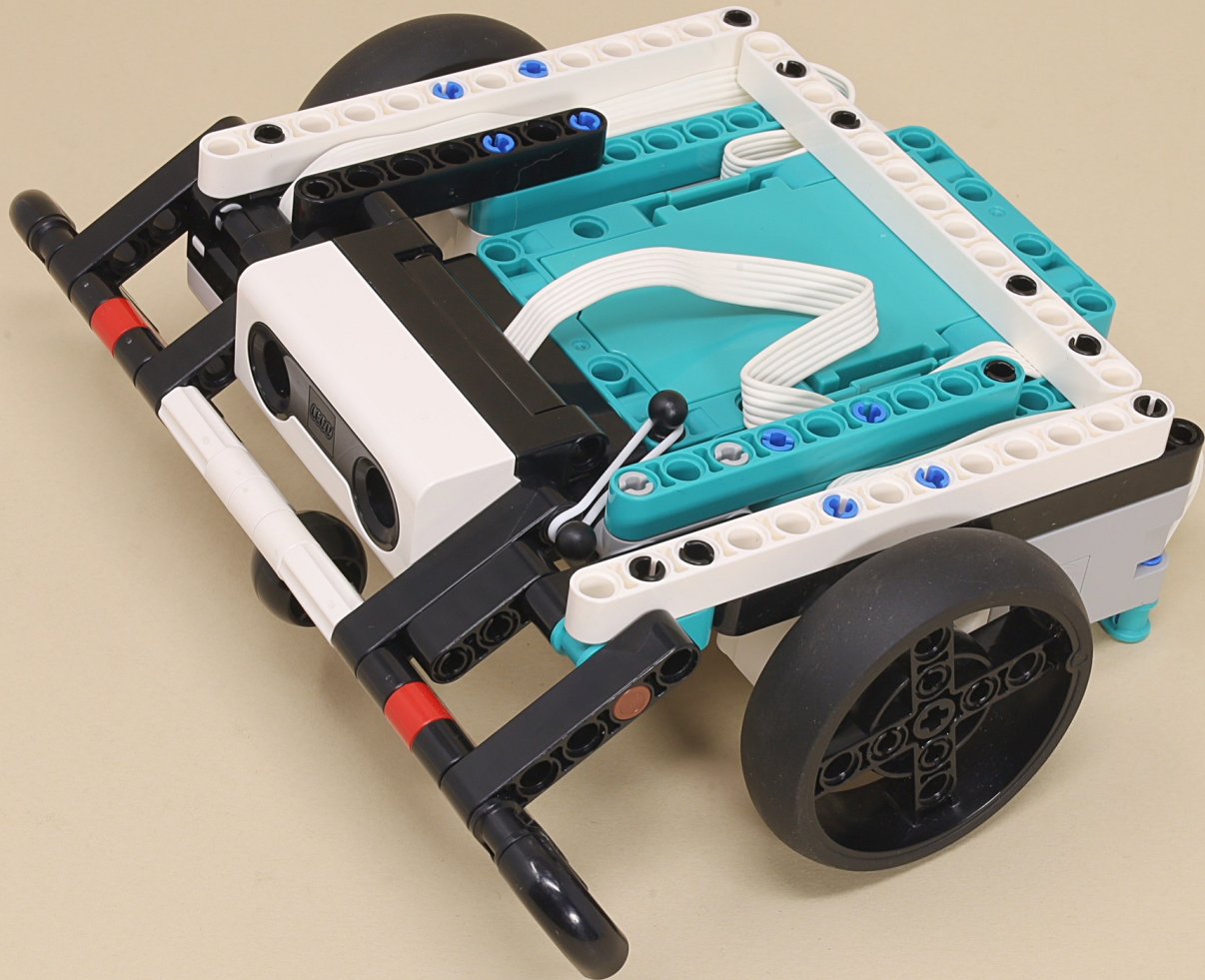


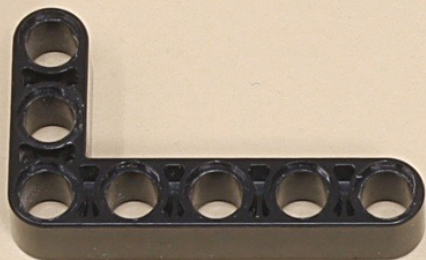
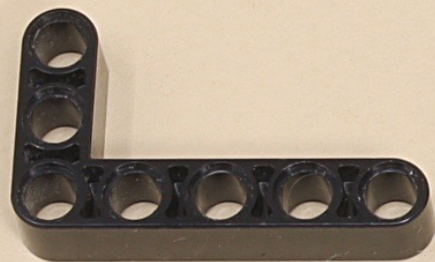
Push the extra sensor wires into these spaces.





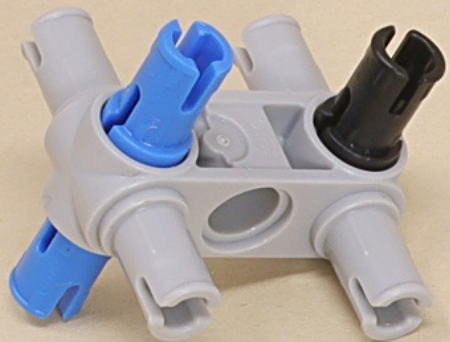


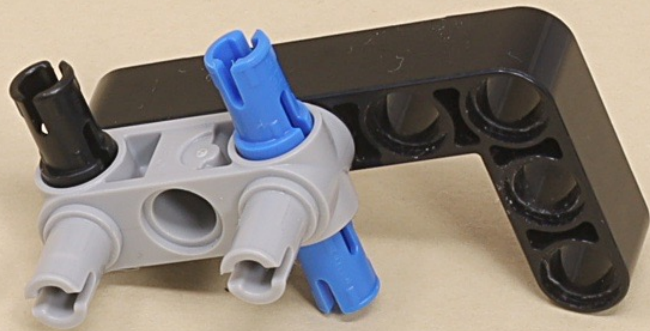




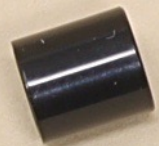
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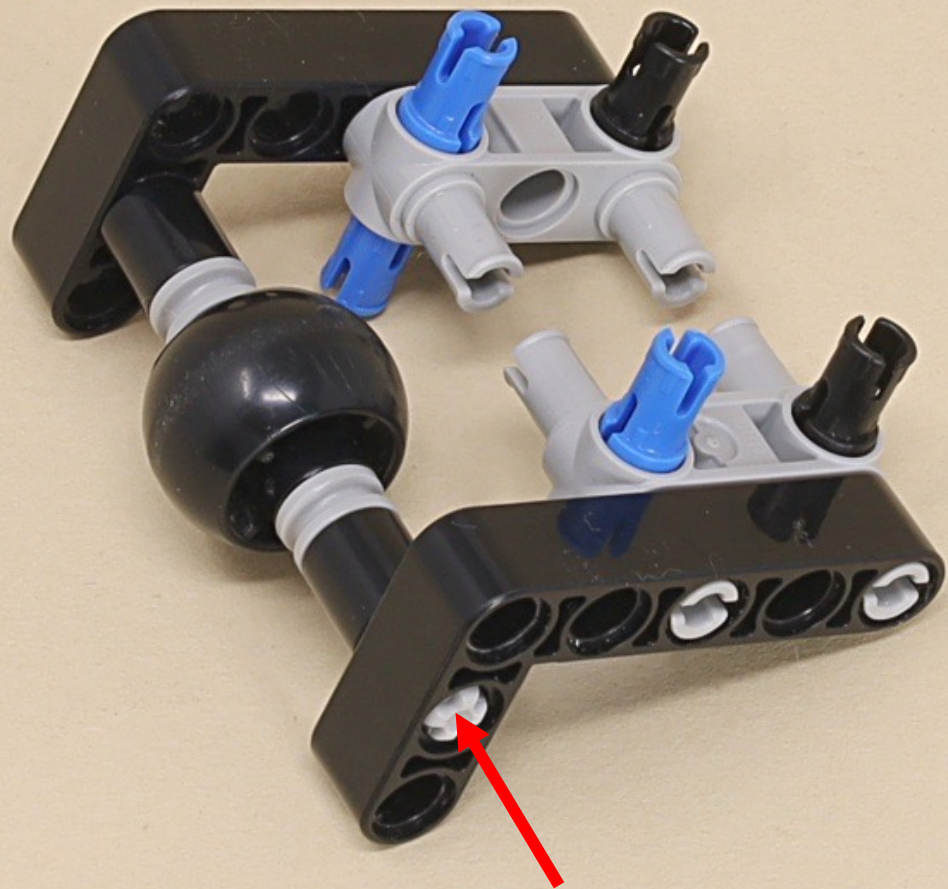


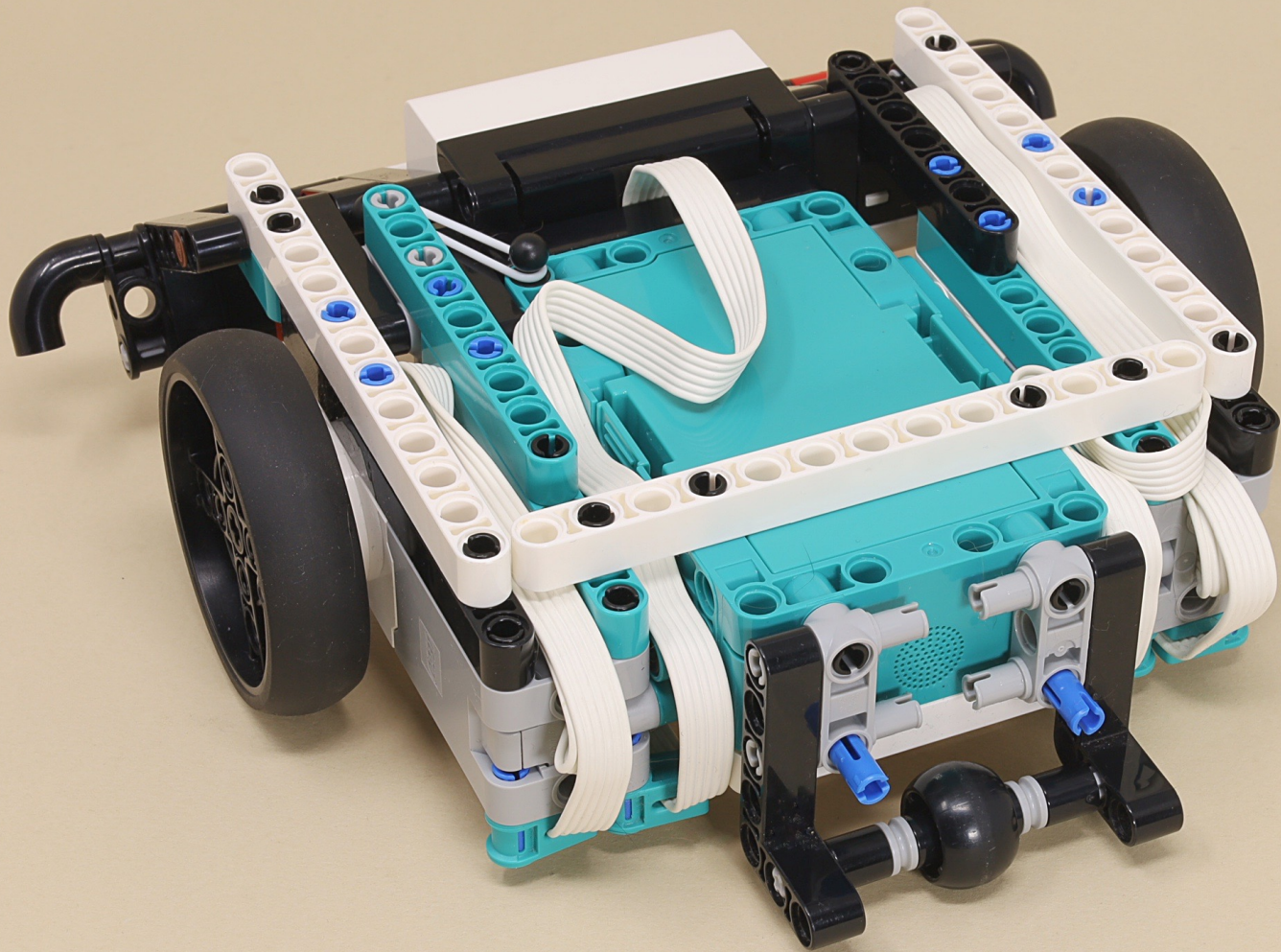


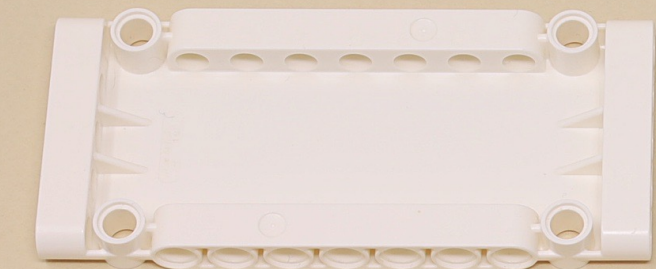












21

22



(15 x)





